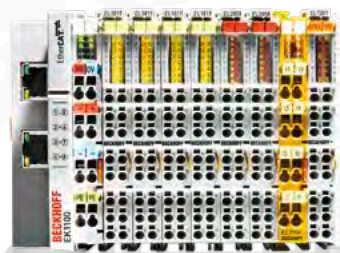


# BECKHOFF New Automation Technology

## Product Overview | 2018



Industrial PC  
Embedded PC



EtherCAT  
EtherCAT Terminal  
EtherCAT Box  
EtherCAT Plug-in Modules  
Bus Terminal  
Fieldbus Box  
Infrastructure Components



Drive Technology



TwinCAT  
TwinSAFE

## IPC



- 8 Industrial PC, Control Panel**  
PC Control for all applications



- 20 Embedded PC**  
Modular DIN rail IPCs

## I/O



- 26 Fieldbus Components**  
I/Os for all common fieldbus systems



- 26 EtherCAT**  
The real-time Ethernet fieldbus



- 32 EtherCAT Terminal**  
Ultra high-speed communication



- 40 EtherCAT Box**  
High performance for harsh environments



- 48 EtherCAT Plug-in Modules**  
Bus Terminals for circuit boards



- 52 Bus Terminal**  
The modular fieldbus system for automation



- 58 Fieldbus Box**  
The compact IP 67 modules



- 61 Infrastructure Components**  
PC Fieldbus Cards, Switches, Media Converters

## Motion



- 62 Drive Technology**  
The drive system for highly dynamic positioning tasks

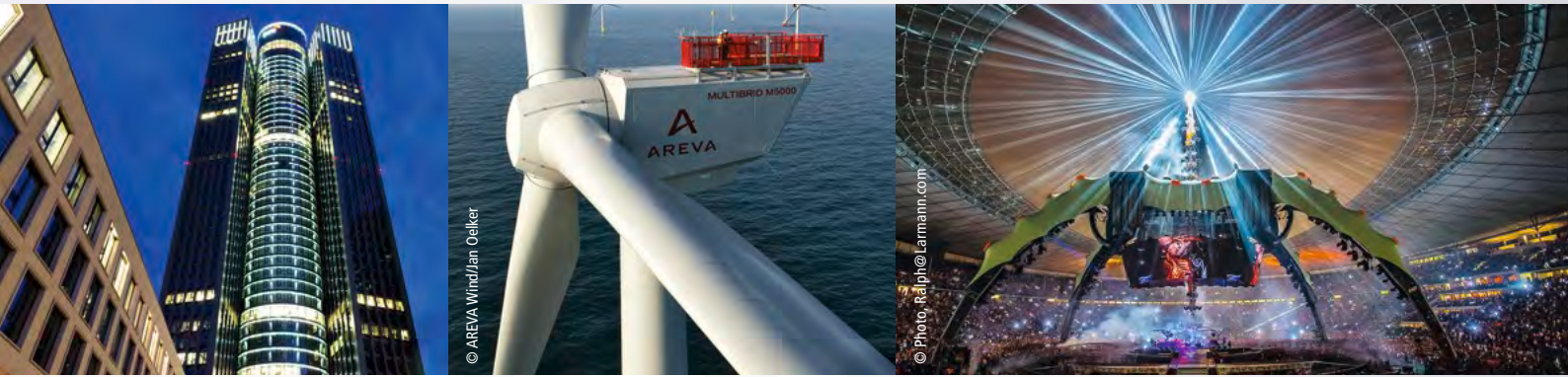
## Automation



- 74 TwinCAT**  
PLC and Motion Control on the PC

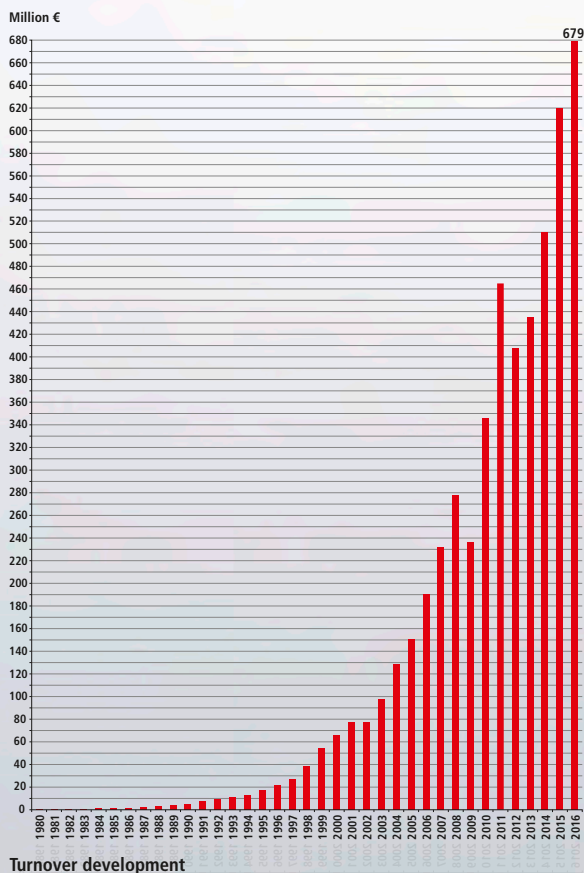


- 86 TwinSAFE**  
Open and scalable safety technology



# New Automation Technology

Beckhoff implements open automation systems based on PC Control technology. The product range covers Industrial PCs, I/O and Fieldbus Components, Drive Technology and automation software. Products that can be used as separate components or integrated into a complete and seamless control system are available for all industries. The Beckhoff “New Automation Technology” philosophy represents universal and open control and automation solutions that are used worldwide in a wide variety of different applications, ranging from CNC-controlled machine tools to intelligent building automation.



## Beckhoff Automation

- Headquarters: Verl, Germany
- Sales 2016: **679 million € (+9.5 %)**
- Staff worldwide: **3850**
- Sales Offices Germany: **20**
- Subsidiaries/Branch Offices worldwide: **34**
- Distributors worldwide:  
**in more than 75 countries**

(as of 11/2017)

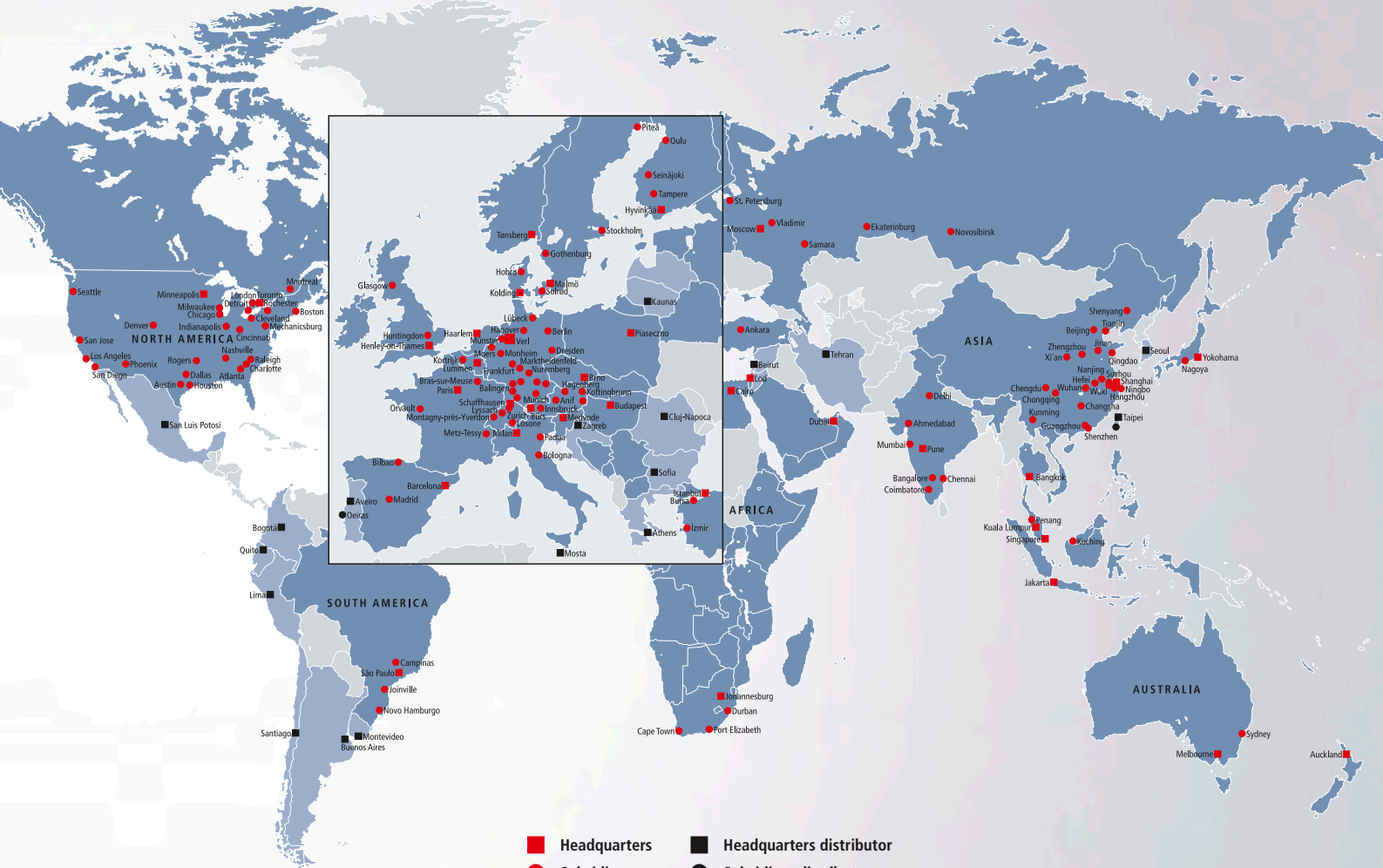
# PC-based control technology

Since the foundation of the company in 1980, continuous development of innovative products and solutions using PC-based control technology has been the basis for the continued success of Beckhoff. Many automation technology standards that are taken for granted today were conceptualised by Beckhoff at an early stage and successfully introduced to the market.

The Beckhoff PC Control philosophy and the invention of the Lightbus system, the Bus Terminals and TwinCAT automation software represent milestones in automation technology and have become accepted as high-performance alternatives to traditional control technology. EtherCAT, the real-time Ethernet solution, makes forward-looking, high-performance technology available for a new generation of leading edge control concepts.

## Milestones

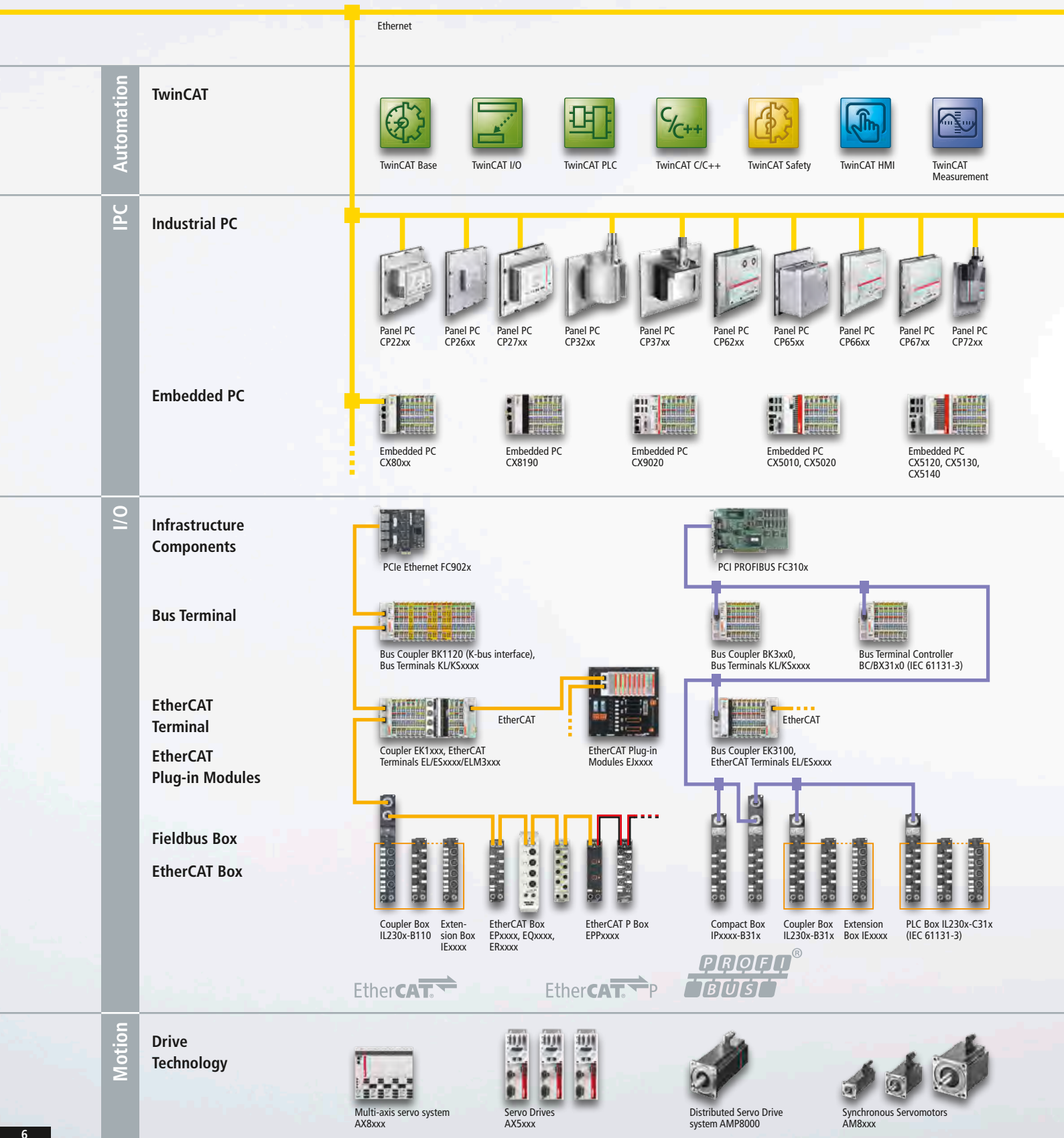
- |             |  |             |   |
|-------------|--|-------------|---|
| <b>1982</b> | P1000 – single-board motion controller   | <b>2012</b> | 2 <sup>nd</sup> generation of Control Panels – Panel PCs and Control Panels with multi-touch technology |
| <b>1986</b> | PC Control – first PC-based machine controller   | <b>2012</b> | XTS – eXtended Transport System   |
| <b>1988</b> | S1000 – software PLC/NC on PC (DOS)  | <b>2014</b> | Many-core control – Industrial server maximises industrial computing power                              |
| <b>1989</b> | Lightbus – high-speed fieldbus utilising optical fibre                                   | <b>2014</b> | AX8000 – Multi-axis servo system  |
| <b>1990</b> | All-in-one PC motherboard  | <b>2014</b> | EtherCAT Plug-in Modules – Bus Terminals for circuit boards   |
| <b>1995</b> | Bus Terminal – fieldbus technology in terminal block format                              | <b>2015</b> | EtherCAT P – One Cable Automation   |
| <b>1996</b> | TwinCAT – real-time software package under Windows with PLC and Motion Control functions | <b>2015</b> | TwinCAT HMI – for platform-independent user interfaces  |
| <b>1998</b> | Control Panel – remote IPC Control Panels  | <b>2015</b> | TwinCAT IoT – for simple cloud communication  |
| <b>1999</b> | Fieldbus Box – the I/O system in IP 67   | <b>2015</b> | TwinCAT Analytics – Recording and analysis of process data  |
| <b>2002</b> | CX1000 – modular Embedded PCs for DIN rail mounting                                      | <b>2016</b> | EtherCAT measurement modules – system-integrated high-end measurement technology                        |
| <b>2003</b> | EtherCAT – real-time Ethernet fieldbus system  | <b>2017</b> | Process technology – system-integrated solutions for explosion protection requirement                   |
| <b>2005</b> | TwinSAFE – the compact safety solution   | <b>2017</b> | C60xx – The generation of ultra-compact IPCs  |
| <b>2005</b> | AX5000 – EtherCAT Servo Drives   | <b>2017</b> | AMP8000 – Distributed Servo Drive system  |
| <b>2007</b> | Industrial Motherboards – made in Germany  | <b>2017</b> | TwinCAT Vision – Machine vision integrated into automation technology                                   |
| <b>2008</b> | XFC – eXtreme Fast Control Technology  |             |   |
| <b>2009</b> | HD Bus Terminals – 16-channel terminals in 12 mm   |             |   |
| <b>2010</b> | TwinCAT 3 – eXtended Automation Technology   |             |   |
| <b>2011</b> | AM8000 – Synchronous Servomotors with One Cable Technology                               |             |   |



## Worldwide presence on all continents

The central divisions of Beckhoff, such as development, production, administration, distribution, marketing, support and service are located at the Beckhoff Automation GmbH & Co. KG headquarters in Verl, Germany. Rapidly growing presence in the international market is taking place through subsidiaries and branch offices. Through worldwide co-operation with partners, Beckhoff is represented in more than 75 countries.

# System overview





TwinCAT Vision



TwinCAT Control



TwinCAT Motion



TwinCAT PTP



TwinCAT NC I



TwinCAT CNC



TwinCAT Robotics



TwinCAT Connectivity



TwinCAT Industrie 4.0



TwinCAT Industry specific



Panel PC CP77xx



Panel PC C36xx



19-inch slide-in PC C5xxx



Control cabinet PC C61xx



Built-in Industrial PC C65xx



Control cabinet PC C66xx



Control cabinet PC C60xx



Control cabinet PC C69xx



Built-in Control Panel CP29xx



Control Panel CP39xx



Built-in Control Panel CP69xx



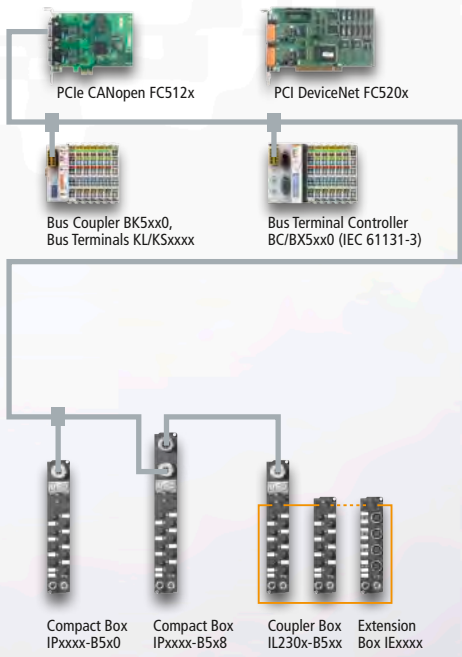
Control Panel CP79xx



Embedded PC CX2020, CX2030, CX2040

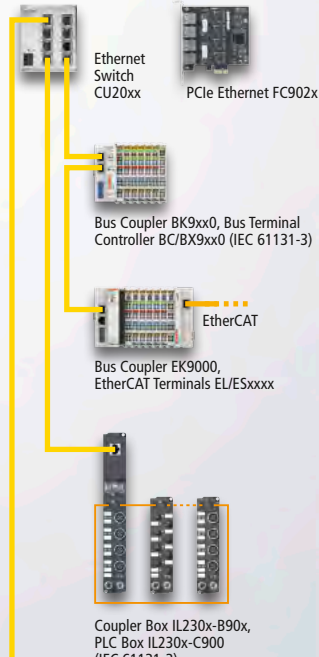


Embedded PC CX2042, CX2062, CX2072



CANopen

DeviceNet



Ethernet TCP/IP



Stainless steel servomotors AM88xx



Linear Servomotors ALxxx



Compact Drive Technology



XTS | eXtended Transport System

# The IPC Company

The Industrial PC (IPC) is the hardware centrepiece of PC-based control technology. Beckhoff supplies Industrial PCs suitable for any application, which are based on open standards, enabling individual configuration to meet a wide range of control requirements.

Whether in the form of an Embedded PC with a compact form-factor for DIN rail mounting, a control cabinet PC, or as a Panel PC, in-house motherboard development enables Beckhoff to respond quickly to IT trends and customer-specific requirements.

► [www.beckhoff.com/IPC](http://www.beckhoff.com/IPC)

## Multi-touch Panel PCs 12

- Large model variety
- High computing power
- Display sizes from 7-inch to 24-inch
- Easy installation in control cabinets or on mounting arms
- Special versions for explosion protection
- Customer-specific implementations

► [www.beckhoff.com/multi-touch](http://www.beckhoff.com/multi-touch)

## Multi-touch Control Panels 13

- Large model variety
- Display sizes from 7-inch to 24-inch
- Landscape and portrait orientation
- Easy installation in control cabinets or on mounting arms
- Special versions for explosion protection
- Customer-specific implementations

► [www.beckhoff.com/multi-touch](http://www.beckhoff.com/multi-touch)

## Single-touch Panels 14

- Control Panels or Panel PCs
- Display sizes from 5.7-inch to 19-inch
- Easy installation in control cabinets or on mounting arms
- Customer-specific implementations

► [www.beckhoff.com/single-touch](http://www.beckhoff.com/single-touch)







Control cabinet Industrial PC



Embedded PC

**Control cabinet Industrial PCs** 16

- High computing power
- Industrial-strength housing designs
- Easy installation
- High flexibility in terms of display connections

**Embedded PCs** 20

- Scalable performance range
- Up to 12 cores
- Compact design
- Direct I/O interface
- Modular extension options
- DIN rail mounting

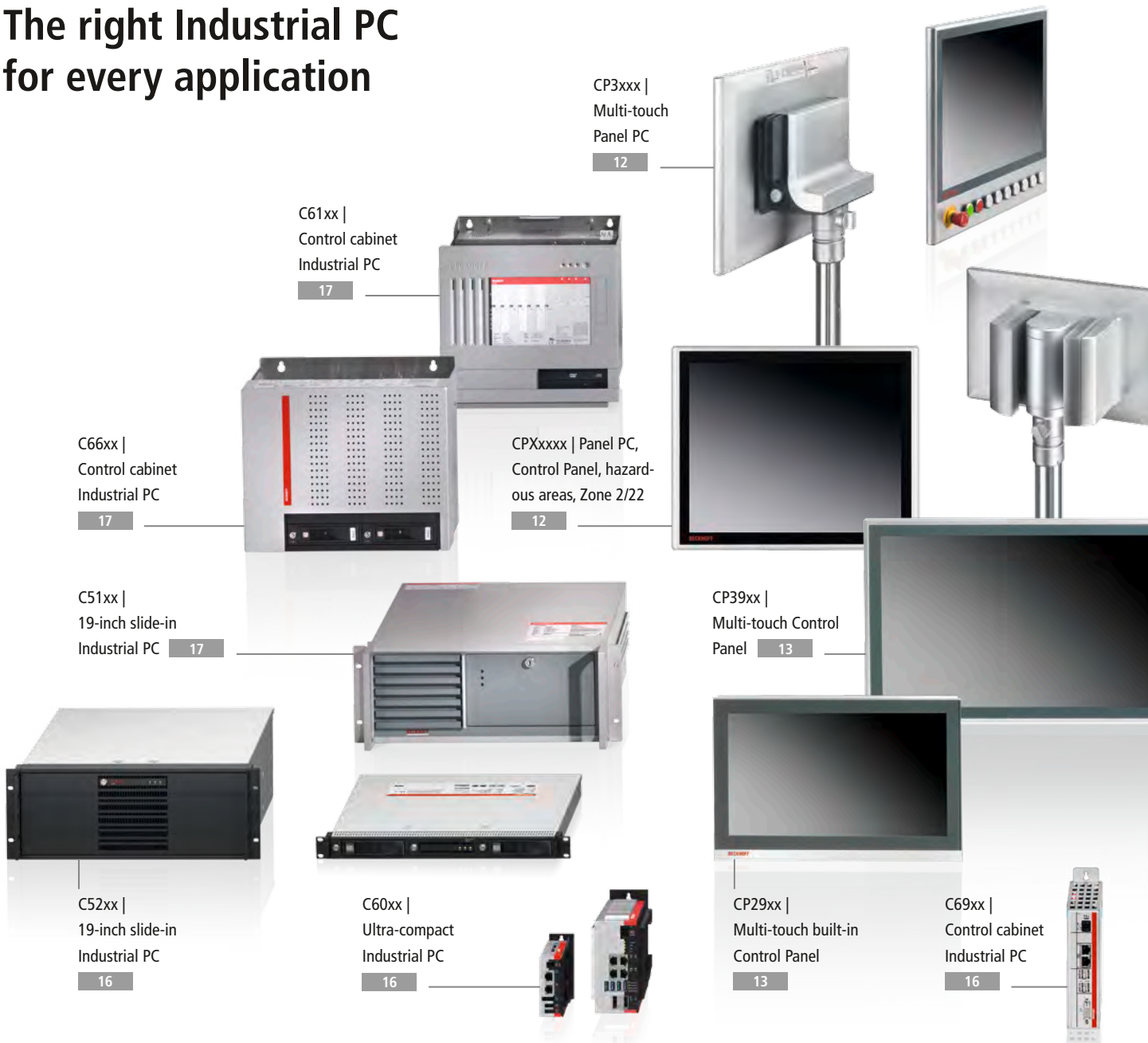
► [www.beckhoff.com/Control-cabinet-PC](http://www.beckhoff.com/Control-cabinet-PC)

► [www.beckhoff.com/Embedded-PC](http://www.beckhoff.com/Embedded-PC)



- Wide variety of device variants of Industrial PCs and Embedded PCs
- High-performance PCs, featuring a wide range of processors, from Intel® Celeron® to top of the line Core™ i7 processors
- Long-term availability of all Industrial PCs and Embedded PCs
- As the inventor of PC-based control technology, Beckhoff closely cooperates with global technology partners Intel and Microsoft.

# The right Industrial PC for every application



## Industrial PCs

	ATX motherboard Intel® Core™	3½-inch motherboard Intel® Core™	3½-inch motherboard Intel® Atom™/ Celeron® ULV	3½-inch motherboard ARM Cortex™-A8	Control Panels
Multi-touch Panel PCs/Control Panels		CP22xx CP32xx	CP27xx/CPX27xx CP37xx/CPX37xx	CP26xx	CP29xx/CPX29xx CP39xx/CPX39xx
Single-touch Panel PCs/Control Panels	CP65xx C36xx	CP62xx CP72xx	CP67xx CP77xx	CP66xx	CP69xx CP79xx
19-inch slide-in Industrial PCs	C5102 C5240	C5210			
Control cabinet Industrial PCs	C6140/C6150 C6240/C6250 C6640/C6650	C6515/C6525			
Compact Industrial PCs		C6920/C6930	C6905/C6915 C6925		



### Ultra-compact Industrial PCs

Compact motherboard  
Intel® Atom™  
C6015

Compact motherboard  
Intel® Core™  
C6030

### Control cabinet industrial server

SSI EEB motherboard  
2 x Intel® Xeon®  
C6670

# Multi-touch Panel PCs

► [www.beckhoff.com/multi-touch](http://www.beckhoff.com/multi-touch)



## Multi-touch built-in Panel PCs, front side IP 65

	Display	7-inch	12-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	4:3	16:9	16:9	5:4	16:9	16:9
<b>CP22xx</b> – up to Core™ i3/i5/i7	multi-finger touch screen		CP2212	CP2215	CP2216	CP2218	CP2219	CP2221	CP2224
<b>CP26xx</b> – ARM Cortex™-A8	dual-finger touch screen	CP2607	CP2612	CP2615	CP2616	CP2618	CP2619	CP2621	CP2624
<b>CP27xx</b> – Intel® Celeron™ ULV or Atom™	multi-finger touch screen, only horizontal		CP2712	CP2715 CPX2715 <u>i</u>	CP2716	CP2718	CP2719 CPX2719 <u>i</u>	CP2721 CPX2721 <u>i</u>	CP2724

## Multi-touch Panel PCs, all sides IP 65

	Display	7-inch	12-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	4:3	16:9	16:9	5:4	16:9	16:9
<b>CP32xx</b> – up to Core™ i3/i5/i7	multi-finger touch screen, only horizontal		CP3212	CP3215	CP3216	CP3218	CP3219	CP3221	CP3224
<b>CP37xx</b> – Intel® Atom™	multi-finger touch screen, only horizontal		CP3712	CP3715 CPX3715 <u>i</u>	CP3716	CP3718	CP3719 CPX3719 <u>i</u>	CP3721 CPX3721 <u>i</u>	CP3724

# Multi-touch Control Panels

► [www.beckhoff.com/multi-touch](http://www.beckhoff.com/multi-touch)



CP29xx



CP39xx

## Multi-touch built-in Control Panels, front side IP 65

	Display	7-inch	12-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	4:3	16:9	16:9	5:4	16:9	16:9
<b>CP29xx-0000</b> – DVI/USB Extended interface*	multi-finger touch screen	CP2907-0000	CP2912-0000	CP2915-0000 CPX2915-0000 <u>i</u>	CP2916-0000	CP2918-0000	CP2919-0000 CPX2919-0000 <u>i</u>	CP2921-0000 CPX2921-0000 <u>i</u>	CP2924-0000
<b>CP29xx-0010</b> – CP-Link 4*	multi-finger touch screen	CP2907-0010	CP2912-0010	CP2915-0010	CP2916-0010	CP2918-0010	CP2919-0010	CP2921-0010	CP2924-0010

## Multi-touch Control Panels, all sides IP 65

	Display	7-inch	12-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	4:3	16:9	16:9	5:4	16:9	16:9
<b>CP39xx-0000</b> – DVI/USB Extended interface*	multi-finger touch screen	CP3907-0000	CP3912-0000	CP3915-0000	CP3916-0000	CP3918-0000	CP3919-0000	CP3921-0000	CP3924-0000
<b>CP39xx-0010</b> – CP-Link 4*	multi-finger touch screen	CP3907-0010	CP3912-0010	CP3915-0010 CPX3915-0010 <u>i</u>	CP3916-0010	CP3918-0010	CP3919-0010 CPX3919-0010 <u>i</u>	CP3921-0010 CPX3921-0010 <u>i</u>	CP3924-0010

\*For further information on DVI/USB Extended and CP-Link 4 see page

19

# Single-touch Panels

► [www.beckhoff.com/single-touch](http://www.beckhoff.com/single-touch)



## Single-touch built-in Panel PCs, front side IP 54/65

	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
Resolution		640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
Format		4:3	4:3	5:3	17:10	4:3	4:3	5:4
Protect. class front		IP 65	IP 65	IP 54	IP 54	IP 65	IP 65	IP 65
<b>CP62xx</b> – 3½-inch motherboard – up to Core™ i3/i5/i7	without keys					CP6201	CP6202	CP6203
	function keys					CP6211	CP6212	CP6213
	numerical					CP6221	CP6222	CP6223
	alphanumeric					CP6231	CP6232 CP6242	CP6233
<b>CP65xx</b> – ATX motherboard – up to Core™ i3/i5/i7 – 7 slots free	without keys					CP6501	CP6502	CP6503
	function keys					CP6511	CP6512	CP6513
	numerical					CP6521	CP6522	CP6523
	alphanumeric					CP6531	CP6532 CP6542	CP6533
<b>CP66xx</b> – 3½-inch motherboard – ARM Cortex™-A8	without keys	CP6607	CP6609			CP6601	CP6602	CP6603
	function keys		CP6619			CP6611	CP6612	CP6613
	numerical		CP6629			CP6621	CP6622	CP6623
	alphanumeric					CP6631	CP6632	CP6633
<b>CP6606, CP6600</b> – 3½-inch motherboard – ARM Cortex™-A8	without keys			CP6606	CP6600			
<b>CP67xx</b> – 3½-inch motherboard – Celeron™ ULV or Intel® Atom™	without keys	CP6707				CP6701	CP6702	CP6703
	function keys					CP6711	CP6712	CP6713
	numerical					CP6721	CP6722	CP6723
	alphanumeric					CP6731	CP6732 CP6742	CP6733
<b>CP6706, CP6700</b> – 3½-inch motherboard – Celeron™ ULV or Intel® Atom™	without keys			CP6706	CP6700			
<b>C36xx</b> – ATX motherboard – up to Core™ i3/i5/i7 – 7 slots free	without keys					C3620	C3640	



### Single-touch Panel PCs, all sides IP 65

	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
<b>CP72xx</b> – 3½-inch motherboard – up to Core™ i3/i5/i7	without keys					CP7201	CP7202	CP7203
	function keys					CP7211	CP7212	CP7213
	numerical					CP7221	CP7222	CP7223
	alphanumeric					CP7231	CP7232 CP7242	CP7233
<b>CP77xx</b> – CP motherboard – Celeron® ULV	without keys					CP7701	CP7702	CP7703
	function keys					CP7711	CP7712	CP7713
	numerical					CP7721	CP7722	CP7723
	alphanumeric					CP7731	CP7732	CP7733

### Single-touch built-in Control Panels, front side IP 54/65

	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
	Protect. class front	IP 65	IP 65	IP 54	IP 54	IP 65	IP 65	IP 65
<b>CP69xx</b> – DVI/USB Extended interface*	without keys	CP6907	CP6909	CP6906	CP6900	CP6901	CP6902	CP6903
	function keys		CP6919			CP6911	CP6912	CP6913
	numerical		CP6929			CP6921	CP6922	CP6923
	alphanumeric					CP6931	CP6932 CP6942	CP6933

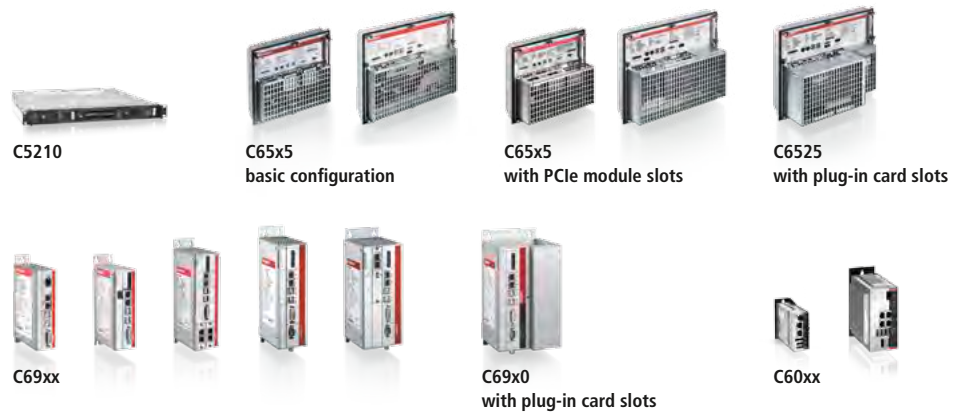
### Single-touch Control Panels, all sides IP 65

	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
<b>CP79xx</b> – DVI/USB Extended interface*	without keys		CP7909			CP7901	CP7902	CP7903
	function keys		CP7919			CP7911	CP7912	CP7913
	numerical		CP7929			CP7921	CP7922	CP7923
	alphanumeric					CP7931	CP7932 CP7942	CP7933
<b>CP79xx-14xx</b> – DVI/USB Extended interface* stainless steel housing	without keys, stainless steel housing					CP7901-14xx	CP7902-14xx	CP7903-14xx

\*For further information on DVI/USB Extended see page 19

# Control cabinet Industrial PCs

► [www.beckhoff.com/Control-cabinet-PC](http://www.beckhoff.com/Control-cabinet-PC)



## Control cabinet Industrial PCs with 3½-inch motherboard

	Processor	Intel® Atom™	Intel® Celeron® ULV	Intel® Celeron®, Intel® Core™ i3/i5/i7 4th Generation	Intel® Celeron®, Intel® Core™ i3/i5/i7 6th/7th Generation	
<b>19-inch slide-in Industrial PC series C5210</b>	1 rack unit			C5210-0020	C5210-0030	<a href="#"><u>i</u></a>
<b>Control cabinet PC series C65xx</b>	fanless			C6515-0050	C6515-0060	<a href="#"><u>i</u></a>
	RAID			C6525-0050	C6525-0060	<a href="#"><u>i</u></a>
<b>Compact Industrial PC series C69xx, connectors on front</b>	fanless	C6905-0010				
	fanless, 1 CFast card slot	C6915-0010				
	fanless, 2 PCIe module slots	C6925-0030	C6925-0020			
	optional plug-in card slots			C6920-0050	C6920-0060	<a href="#"><u>i</u></a>
	2 PCIe module slots, optional plug-in card slots			C6930-0050	C6930-0060	<a href="#"><u>i</u></a>

## Ultra-compact control cabinet Industrial PCs with compact industrial motherboard

	Processor	Intel® Atom™	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 6th/7th Generation
<b>Ultra-compact Industrial PC series C60xx</b>	fanless, without slots up to 2 M.2 SSDs	C6015-0010	C6030-0060





### Control cabinet Industrial PCs with ATX motherboard

	Processor	Intel® Pentium®, Intel® Core™ i3/i5/i7 4 <sup>th</sup> Generation	Intel® Pentium®, Intel® Core™ i3/i5/i7 6 <sup>th</sup> /7 <sup>th</sup> Generation	
19-inch slide-in Industrial PC series C5xxx	7 slots, 4 rack units	C5102-0060	C5102-0070	
		C5240-0000	C5240-0010	
Control cabinet PC series C61xx, connectors on top	7 slots	C6140-0060	C6140-0070	
		C6150-0060	C6150-0070	
Control cabinet PC series C62xx, connectors on front	7 slots	C6240-0060	C6240-0070	
		C6250-0070	C6250-0080	
Control cabinet PC series C6640/C6650, connectors on top	7 slots	C6640-0040	C6640-0050	
		7 slots, 2 removable frames	C6650-0040	C6650-0050

### Control cabinet industrial server with SSI EEB motherboard

	Processor	2 x Intel® Xeon®
Control cabinet industrial server C6670	6 slots, 2 removable frames	C6670

# Customisation options for Panel PCs and Control Panels

- stainless steel housings
- special membrane keyboards
- integration of electro-mechanical keyboards
- flush-mounted touch screens
- adaptation of membrane colours
- integration of customer logos



Built-in panel with individual front laminate



Stainless steel panel



Stainless steel panel with emergency stop



Customer-specific multi-touch Control Panel



Multi-touch Control Panel for machine tools



Multi-touch Control Panel with push-button extension

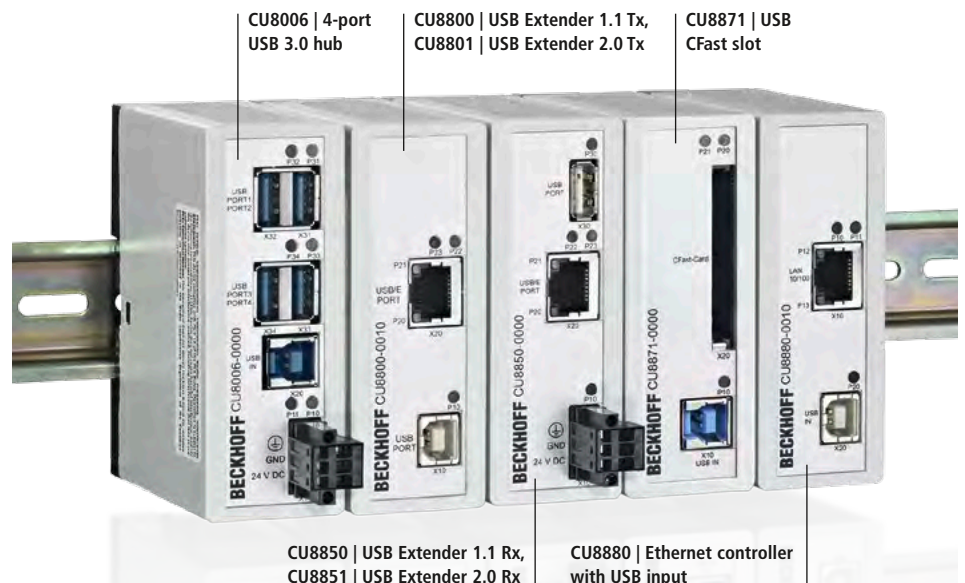


Control Panel with CNC push-button extension

## Industrial PC accessories

### CU8xxx modules

Different modules enable the use of various technologies in the industrial environment. All modules are intended for DIN rail mounting.



CU8006 | 4-port USB 3.0 hub

CU8800 | USB Extender 1.1 Tx, CU8801 | USB Extender 2.0 Tx

CU8871 | USB C/Fast slot

CU8850 | USB Extender 1.1 Rx, CU8851 | USB Extender 2.0 Rx

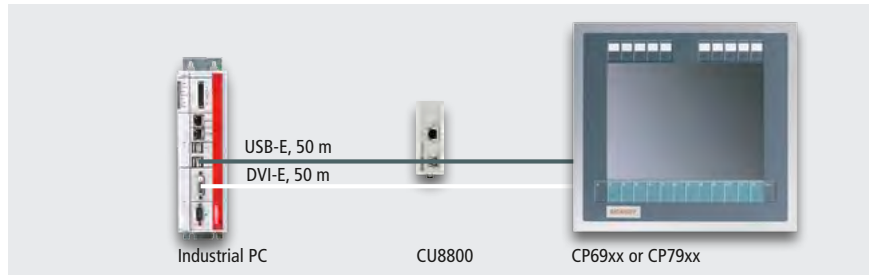
CU8880 | Ethernet controller with USB input

## DVI/USB Extended

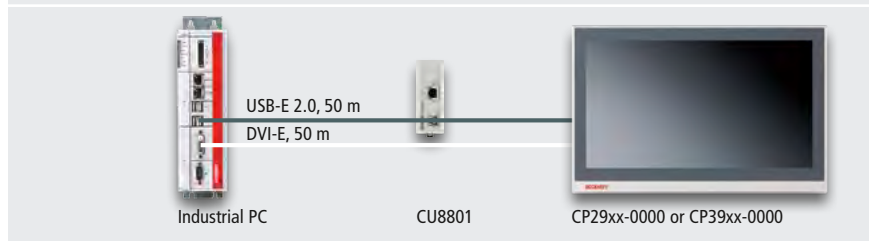
The DVI/USB Extended technology enables remote panel operation at a distance of up to 50 m from the PC. The DVI graphics signal is directly transmitted from the PC via DVI E cable. A signal processor in the Control Panels restores the DVI signal after it a distance of 50 m. For connection of the CP69xx and CP79xx Control Panels, a CU8800 USB Extender box is connected to an USB port of the PC. The signal is transmitted by the CU8800 USB Extender (USB-E) via Cat.5 cable over 50 m max. and is reconverted by the Control Panel into USB 1.1 with 12 Mbit/s.

For the CP29xx-0000 and CP39xx-0000 Control Panels, the USB signal from the PC is converted into USB Extended 2.0 by the USB Extender box CU8801, transmitted to the Control Panel via Cat.5 cable over 50 m max. to be reconverted into USB 2.0 with 480 Mbit/s. An USB hub in the Control Panel enables the connection of two external USB devices such as a keyboard or USB stick, in addition to touch screen and push-button extension.

DVI/USB Extended for CP69xx or CP79xx via the CU8800 transmitter box



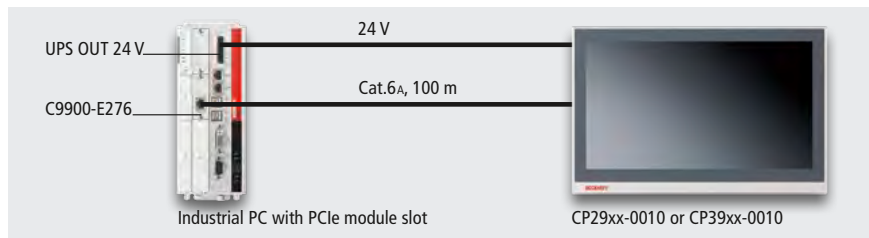
DVI/USB Extended 2.0 for CP29xx-0000 or CP39xx-0000 via the CU8801 transmitter box



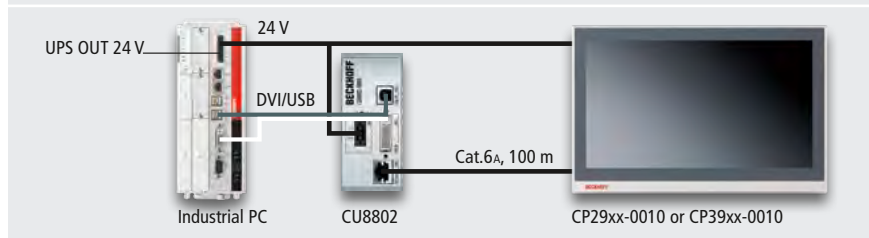
## CP-Link 4: The One Cable Display Link

With CP-Link 4 operating panels can be located up to 100 m away from the Industrial PC. The single-cable solution can be used to transfer video signals, USB 2.0 and the power supply in an industrial Cat.6A cable, thus significantly reducing cable and installation costs. A further benefit is the use of purely passive displays. The CP-Link 4 technology is supported by the new Beckhoff multi-touch panel series CP29xx-0010 (built-in version) and CP39xx-0010 (mounting arm version).

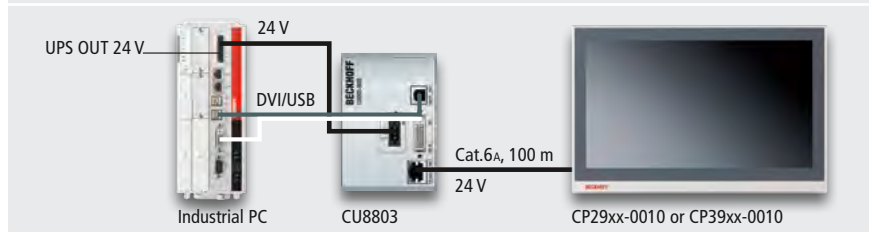
CP-Link 4 – The Two Cable Display Link: via C9900-E276 PCIe module integrated in the PC



CP-Link 4 – The Two Cable Display Link: via CU8802 transmitter box



CP-Link 4 – The One Cable Display Link: DVI, USB and 24 V via CU8803 transmitter box




► [www.beckhoff.com/CP-Link4](http://www.beckhoff.com/CP-Link4)

# Embedded PC

► [www.beckhoff.com/Embedded-PC](http://www.beckhoff.com/Embedded-PC)



Embedded PC			
Basic CPU	CX80xx	CX8190	 CX9000, CX9010
Processor	32 bit, 400 MHz	ARM Cortex™-A9, 800 MHz	Intel® IXP420 with XScale® technology, clock frequency 266/533 MHz
Flash memory	512 MB microSD (optionally expandable), 1 x microSD card slot	512 MB microSD (optionally expandable), 1 x microSD card slot	32 MB Flash (internal, not expandable)
Internal main memory	64 MB RAM (internal, not expandable)	512 MB DDR3 RAM (internal, not expandable)	128 MB RAM (internal, not expandable)
Interfaces	1 x RJ45 (Ethernet), 2 x RJ45 (RT Ethernet, internal switch), 100 Mbit/s	1 x RJ45 (Ethernet), 2 x RJ45 (RT Ethernet, internal switch), 100 Mbit/s	2 x RJ45 (Ethernet, internal switch), 10/100 Mbit/s
I/O connection	E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition	direct connection for E-bus or K-bus
System interfaces	optionally integrated or via EtherCAT Terminals	optionally integrated or via EtherCAT Terminals	modularly expandable
DVI/USB	–	–	CX90x0-N010
RS232	CX8080	–	CX9000-N030 CX9010-N030
RS422/RS485	CX8080	–	CX9000-N031 CX9010-N031
Audio	–	–	–
Ethernet	in the basic CPU	in the basic CPU	–
4-port USB hub	–	–	CX90x0-N070
Memory medium	–	–	CX90x0-A001
Fieldbus interfaces	optionally integrated or via EtherCAT Terminals	via EtherCAT Terminals	via EtherCAT Terminals
EtherCAT	CX8010 slave	–	–
Lightbus	EL6720 master	EL6720 master	EL6720 master
PROFIBUS	CX8030 master	EL6731 master	EL6731 master
	CX8031 slave	EL6731-0010 slave	EL6731-0010 slave
CANopen	CX8050 master	EL6751 master	EL6751 master
	CX8051 slave	EL6751-0010 slave	EL6751-0010 slave
DeviceNet	EL6752 master	EL6752 master	EL6752 master
	EL6752-0010 slave	EL6752-0010 slave	EL6752-0010 slave
PROFINET RT	CX8093 device	–	–
EtherNet/IP	CX8095 slave	–	–
SERCOS interface	–	–	–
UPS options	1-second UPS	1-second UPS	–



CX9020	CX1010	CX5010, CX5020
ARM Cortex™-A8, 1 GHz	compatible with Intel® Pentium® MMX, clock frequency 500 MHz	Intel® Atom™, 1.1/1.6 GHz clock frequency
512 MB microSD (optionally expandable), 2 x microSD card slot	128 MB Compact Flash card (optionally expandable)	128 MB Compact Flash card (optionally expandable)
1 GB DDR3 RAM	256 MB DDR RAM (not expandable)	CX5010: 512 MB RAM (internal, not expandable), CX5020: 512 MB RAM (optional expandable to 1 GB)
2 x RJ45 (Ethernet, internal switch), 10/100 Mbit/s, DVI-D, 4 x USB 2.0, 1 x optional interface	1 x RJ45 (Ethernet), 10/100 Mbit/s	2 x RJ45, 10/100/1000 Mbit/s, DVI-D, 4 x USB 2.0, 1 x optional interface
E-bus or K-bus, automatic recognition	via power supply module (E-bus, K-bus, K-bus/IP-Link)	E-bus or K-bus, automatic recognition
<b>optionally integrated</b>	<b>modularly expandable</b>	<b>optionally integrated</b>
in the basic CPU	CX1010-N010	in the basic CPU
CX9020-N030	CX1010-N030 (COM 1/2) CX1010-N040 (COM 3/4)	CX50x0-N030
CX9020-N031	CX1010-N031 (COM 1/2) CX1010-N041 (COM 3/4)	CX50x0-N031
CX9020-N020	CX1010-N020	CX50x0-N020
in the basic CPU	CX1010-N060	in the basic CPU
in the basic CPU	–	in the basic CPU
2 <sup>nd</sup> microSD slot in the basic CPU	–	in the basic CPU
<b>optionally integrated or via EtherCAT Terminals</b>	<b>modularly expandable</b>	<b>optionally integrated or via EtherCAT Terminals</b>
CX9020-B110 slave	–	CX50x0-B110 slave
EL6720 master	CX1500-M200 master CX1500-B200 slave	EL6720 master
CX9020-M310 master	CX1500-M310 master	CX50x0-M310 master
CX9020-B310 slave	CX1500-B310 slave	CX50x0-B310 slave
CX9020-M510 master	CX1500-M510 master	CX50x0-M510 master
CX9020-B510 slave	CX1500-B510 slave	CX50x0-B510 slave
EL6752 master	CX1500-M520 master	EL6752 master
EL6752-0010 slave	CX1500-B520 slave	EL6752-0010 slave
CX9020-M930 controller	–	CX50x0-M930 controller
CX9020-B930 device	–	CX50x0-B930 device
CX9020-B950 slave <b>i</b>	–	CX50x0-B950 slave <b>i</b>
–	CX1500-M750 SERCOS II master	–
<b>1-second UPS (optional)</b>	<b>CX1100-0910, -0900</b>	<b>1-second UPS</b>



## Embedded PC





Basic CPU	CX5120	CX5130	CX5140
<b>Processor</b>	Intel® Atom™ E3815, 1.46 GHz	Intel® Atom™ E3827, 1.75 GHz	Intel® Atom™ E3845, 1.91 GHz
<b>Flash memory</b>	slot for CFast card (card not included), slot for microSD card	slot for CFast card (card not included), slot for microSD card	slot for CFast card (card not included), slot for microSD card
<b>Internal main memory</b>	2 GB DDR3 RAM (not expandable)	4 GB DDR3 RAM (not expandable)	4 GB DDR3 RAM (not expandable)
<b>Interfaces</b>	2 x RJ45, 10/100/1000 Mbit/s, DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45, 10/100/1000 Mbit/s, DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45, 10/100/1000 Mbit/s, DVI-I, 4 x USB 2.0, 1 x optional interface
<b>I/O connection</b>	E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition
<b>System interfaces</b>	<b>optionally integrated</b>	<b>optionally integrated</b>	<b>optionally integrated</b>
<b>DVI/USB</b>	in the basic CPU	in the basic CPU	in the basic CPU
<b>RS232</b>	CX5120-N030	CX5130-N030	CX5140-N030
<b>RS422/RS485</b>	CX5120-N031	CX5130-N031	CX5140-N031
<b>Audio</b>	CX5120-N020	CX5130-N020	CX5140-N020
<b>Ethernet</b>	in the basic CPU	in the basic CPU	in the basic CPU
<b>4-port USB hub</b>	in the basic CPU	in the basic CPU	in the basic CPU
<b>Memory medium</b>	in the basic CPU	in the basic CPU	in the basic CPU
<b>Fieldbus interfaces</b>	<b>optionally integrated or via EtherCAT Terminals</b>	<b>optionally integrated or via EtherCAT Terminals</b>	<b>optionally integrated or via EtherCAT Terminals</b>
<b>EtherCAT</b>	CX5120-B110 slave	CX5130-B110 slave	CX5140-B110 slave
<b>Lightbus</b>	EL6720 master	EL6720 master	EL6720 master
<b>PROFIBUS</b>	CX5120-M310 master CX5120-B310 slave	CX5130-M310 master CX5130-B310 slave	CX5140-M310 master CX5140-B310 slave
<b>CANopen</b>	CX5120-M510 master CX5120-B510 slave	CX5130-M510 master CX5130-B510 slave	CX5140-M510 master CX5140-B510 slave
<b>DeviceNet</b>	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave
<b>PROFINET RT</b>	CX5120-M930 controller CX5120-B930 device	CX5130-M930 controller CX5130-B930 device	CX5140-M930 controller CX5140-B930 device
<b>PROFINET IRT</b>	CX5120-B931 device	<b>i</b> CX5130-B931 device	<b>i</b> CX5140-B931 device
<b>EtherNet/IP</b>	CX5120-B950 slave	<b>i</b> CX5130-B950 slave	<b>i</b> CX5140-B950 slave
<b>SERCOS interface</b>	–	–	–
<b>UPS options</b>	1-second UPS	1-second UPS	1-second UPS



CX1020	CX1030
Intel® Celeron® M ULV, 1 GHz clock frequency	Intel® Pentium® M, 1.8 GHz clock frequency
128 MB Compact Flash card (optionally expandable)	128 MB Compact Flash card (optionally expandable)
256 MB DDR RAM (expandable to 512 MB, 1 GB)	256 MB DDR RAM (expandable to 512 MB, 1 GB)
2 x RJ45 (Ethernet, internal switch), 10/100 Mbit/s	2 x RJ45 (Ethernet, internal switch), 10/100 Mbit/s
via power supply module (E-bus, K-bus, K-bus/IP-Link)	via power supply module (E-bus, K-bus, K-bus/IP-Link)
<b>modularly expandable</b>	<b>modularly expandable</b>
CX1020-N010	CX1030-N010
CX1020-N030 (COM 1/2)	CX1030-N030 (COM 1/2)
CX1020-N040 (COM 3/4)	CX1030-N040 (COM 3/4)
CX1020-N031 (COM 1/2)	CX1030-N031 (COM 1/2)
CX1020-N041 (COM 3/4)	CX1030-N041 (COM 3/4)
CX1020-N020	CX1030-N020
CX1020-N060	CX1030-N060
–	–
–	–
<b>modularly expandable</b>	<b>modularly expandable</b>
–	–
CX1500-M200 master	CX1500-M200 master
CX1500-B200 slave	CX1500-B200 slave
CX1500-M310 master	CX1500-M310 master
CX1500-B310 slave	CX1500-B310 slave
CX1500-M510 master	CX1500-M510 master
CX1500-B510 slave	CX1500-B510 slave
CX1500-M520 master	CX1500-M520 master
CX1500-B520 slave	CX1500-B520 slave
–	–
–	–
–	–
CX1500-M750 SERCOS II master	CX1500-M750 SERCOS II master
<b>CX1100-0920</b>	<b>CX1100-0930</b>



## Embedded PC

Basic CPU	CX2020	CX2030	CX2040
<b>Processor</b>	Intel® Celeron® 827E 1.4 GHz	Intel® Core™ i7 2610UE 1.5 GHz	Intel® Core™ i7 2715QE 2.1 GHz
<b>Flash memory</b>	4 or 8 GB CFast flash card (optionally expandable)	4 or 8 GB CFast flash card (optionally expandable)	4 or 8 GB CFast flash card (optionally expandable)
<b>Internal main memory</b>	2 GB DDR3 RAM (optionally expandable)	2 GB DDR3 RAM (optionally expandable)	4 GB DDR3 RAM
<b>Interfaces</b>	2 x RJ45, 10/100/1000 Mbit/s, DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45, 10/100/1000 Mbit/s, DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45, 10/100/1000 Mbit/s, DVI-I, 4 x USB 2.0, 1 x optional interface
<b>I/O connection</b>	via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)
<b>System interfaces</b>	<b>modularly expandable</b>	<b>modularly expandable</b>	<b>modularly expandable</b>
<b>DVI/USB</b>	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2020-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2030-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2040-N010
<b>RS232</b>	CX2020-N030 or CX2500-0030	CX2030-N030 or CX2500-0030	CX2040-N030 or CX2500-0030
<b>RS422/RS485</b>	CX2020-N031 or CX2500-0031	CX2030-N031 or CX2500-0031	CX2040-N031 or CX2500-0031
<b>Audio</b>	CX2500-0020	CX2500-0020	CX2500-0020
<b>Ethernet</b>	in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060
<b>Power over Ethernet</b>	CX2500-0061	CX2500-0061	CX2500-0061
<b>4-port USB hub</b>	in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070
<b>Memory medium</b>	in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020
<b>USB extension</b>	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)
<b>Fieldbus interfaces</b>	<b>optionally integrated or via EtherCAT Terminals</b>	<b>optionally integrated or via EtherCAT Terminals</b>	<b>optionally integrated or via EtherCAT Terminals</b>
<b>EtherCAT</b>	CX2020-B110 slave	CX2030-B110 slave	CX2040-B110 slave
<b>Lightbus</b>	EL6720 master	EL6720 master	EL6720 master
<b>PROFIBUS</b>	CX2020-M310 or CX2500-M310 master CX2020-B310 or CX2500-B310 slave	CX2030-M310 or CX2500-M310 master CX2030-B310 or CX2500-B310 slave	CX2040-M310 or CX2500-M310 master CX2040-B310 or CX2500-B310 slave
<b>CANopen</b>	CX2020-M510 or CX2500-M510 master CX2020-B510 or CX2500-B510 slave	CX2030-M510 or CX2500-M510 master CX2030-B510 or CX2500-B510 slave	CX2040-M510 or CX2500-M510 master CX2040-B510 or CX2500-B510 slave
<b>DeviceNet</b>	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave
<b>PROFINET RT</b>	CX2020-M930 controller CX2020-B930 device	CX2030-M930 controller CX2030-B930 device	CX2040-M930 controller CX2040-B930 device
<b>PROFINET IRT</b>	CX2020-B931 device	 CX2030-B931 device	 CX2040-B931 device
<b>EtherNet/IP</b>	CX2020-B950 slave	 CX2030-B950 slave	 CX2040-B950 slave
<b>UPS options</b>	CX2100-0904, CX2100-0914	CX2100-0904, CX2100-0914	CX2100-0904, CX2100-0914



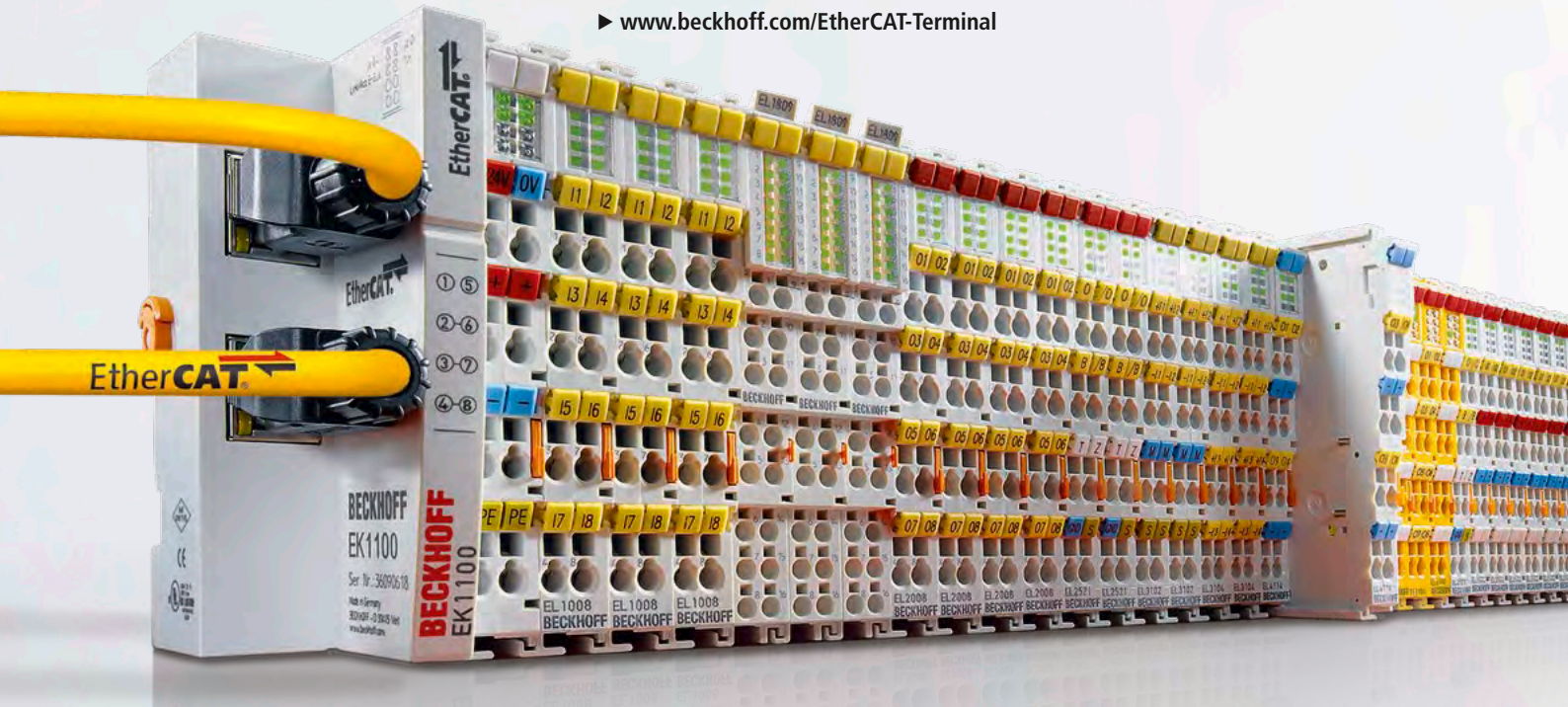


CX2042	CX2062	CX2072
Intel® Xeon® D-1527 2.2 GHz, 4 cores slot for CFast card, card not included	Intel® Xeon® D-1548 2.0 GHz, 8 cores slot for CFast card, card not included	Intel® Xeon® D-1567 2.1 GHz, 12 cores slot for CFast card, card not included
8 GB DDR4 RAM (optionally expandable)	8 GB DDR4 RAM (optionally expandable)	8 GB DDR4 RAM (optionally expandable)
2 x RJ45, 10/100/1000 Mbit/s, 4 x USB 3.0, 1 x DVI-I	2 x RJ45, 10/100/1000 Mbit/s, 4 x USB 3.0, 1 x DVI-I	2 x RJ45, 10/100/1000 Mbit/s, 4 x USB 3.0, 1 x DVI-I
via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)
<b>modularly expandable</b>	<b>modularly expandable</b>	<b>modularly expandable</b>
in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2042-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2062-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2072-N010
CX2042-N030 or CX2500-0030	CX2062-N030 or CX2500-0030	CX2072-N030 or CX2500-0030
CX2042-N031 or CX2500-0031	CX2062-N031 or CX2500-0031	CX2072-N031 or CX2500-0031
–	–	–
in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060
CX2500-0061	CX2500-0061	CX2500-0061
in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070
in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020
CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)
<b>optionally integrated or via EtherCAT Terminals</b>	<b>optionally integrated or via EtherCAT Terminals</b>	<b>optionally integrated or via EtherCAT Terminals</b>
CX2042-B110 slave	CX2062-B110 slave	CX2072-B110 slave
EL6720 master	EL6720 master	EL6720 master
CX2042-M310 or CX2500-M310 master	CX2062-M310 or CX2500-M310 master	CX2072-M310 or CX2500-M310 master
CX2042-B310 or CX2500-B310 slave	CX2062-B310 or CX2500-B310 slave	CX2072-B310 or CX2500-B310 slave
CX2042-M510 or CX2500-M510 master	CX2062-M510 or CX2500-M510 master	CX2072-M510 or CX2500-M510 master
CX2042-B510 or CX2500-B510 slave	CX2062-B510 or CX2500-B510 slave	CX2072-B510 or CX2500-B510 slave
EL6752 master	EL6752 master	EL6752 master
EL6752-0010 slave	EL6752-0010 slave	EL6752-0010 slave
CX2042-M930 controller	CX2062-M930 controller	CX2072-M930 controller
CX2042-B930 device	CX2062-B930 device	CX2072-B930 device
CX2042-B931 device <b>i</b>	CX2062-B931 device <b>i</b>	CX2072-B931 device <b>i</b>
CX2042-B950 slave	CX2062-B950 slave	CX2072-B950 slave
–	–	–

## EtherCAT Terminals 32

- IP 20 EtherCAT I/O system
- Real-time Ethernet performance retained into each terminal
- Integration of highly precise measurement technology, condition monitoring, drive technology and process technology
- Electronic overcurrent protection
- Gateways for subordinate fieldbus systems
- TwinSAFE PLC and safety I/Os

► [www.beckhoff.com/EtherCAT-Terminal](http://www.beckhoff.com/EtherCAT-Terminal)



## EtherCAT Box 40

- IP 67 EtherCAT I/O system
- High performance for harsh environments
- Compact and robust
- Can be mounted directly on machines, outside of control cabinets and terminal boxes
- Integrated sensor/actuator supply directly via EtherCAT P

► [www.beckhoff.com/EtherCAT-Box](http://www.beckhoff.com/EtherCAT-Box)  
 ► [www.beckhoff.com/EtherCAT-P-Box](http://www.beckhoff.com/EtherCAT-P-Box)

## EtherCAT Plug-in Modules 48

- Very compact EtherCAT I/O system in IP 20 for plug-in into a circuit board (signal distribution board)
- Optimised for high-volume production
- Application-specific connector interface
- Use of cable harnesses avoids wiring errors.

► [www.beckhoff.com/EtherCAT-Plug-in-Modules](http://www.beckhoff.com/EtherCAT-Plug-in-Modules)

## Bus Terminals 52

- Open, fieldbus-neutral IP 20 I/O system
- More than 400 different Bus Terminals
- Support for more than 20 fieldbus systems
- Gateways for subordinate bus systems
- System-integrated safety I/O terminals available

► [www.beckhoff.com/BusTerminal](http://www.beckhoff.com/BusTerminal)



# The I/O Company

Beckhoff supplies a complete range of fieldbus components for all common I/O and bus systems. With Bus Terminals offering IP 20 protection and Fieldbus Box modules in IP 67, a comprehensive range of devices is available for a wide variety of signal types and fieldbus systems. In addition to components for conventional bus systems, Beckhoff offers an integrated product range optimised for EtherCAT. Invented by Beckhoff, this real-time Ethernet solution for industrial automation has global acceptance and is characterised by outstanding performance and simple handling. The result is high-precision machine and plant control and significantly increased production efficiency.

► [www.beckhoff.com/IO](http://www.beckhoff.com/IO)

► [www.beckhoff.com/EtherCAT](http://www.beckhoff.com/EtherCAT)

## Fieldbus Box 58

- Open, fieldbus-neutral IP 67 I/O system
- 12 fieldbus systems, 24 signal types
- Compact and robust
- Can be mounted directly on machines, outside of control cabinets and terminal boxes while reducing machine footprint
- IO-Link box modules for inexpensive point-to-point connections

► [www.beckhoff.com/FieldbusBox](http://www.beckhoff.com/FieldbusBox)

## Infrastructure Components 61

- PC cards for all common fieldbus systems
- Industrial Ethernet switches
- EtherCAT junctions and media converters in IP 20 and IP 67 ratings

► [www.beckhoff.com/Infrastructure-components](http://www.beckhoff.com/Infrastructure-components)

- Comprehensive, modular I/O system for all signal types and fieldbus systems
- Universal product range optimised for EtherCAT
- High investment security: Mature I/O technology based on more than 20 years of success in the field
- Beckhoff is the I/O pioneer, developing the Bus Terminal concept and EtherCAT.



# System overview EtherCAT I/O



EK EtherCAT Coupler series



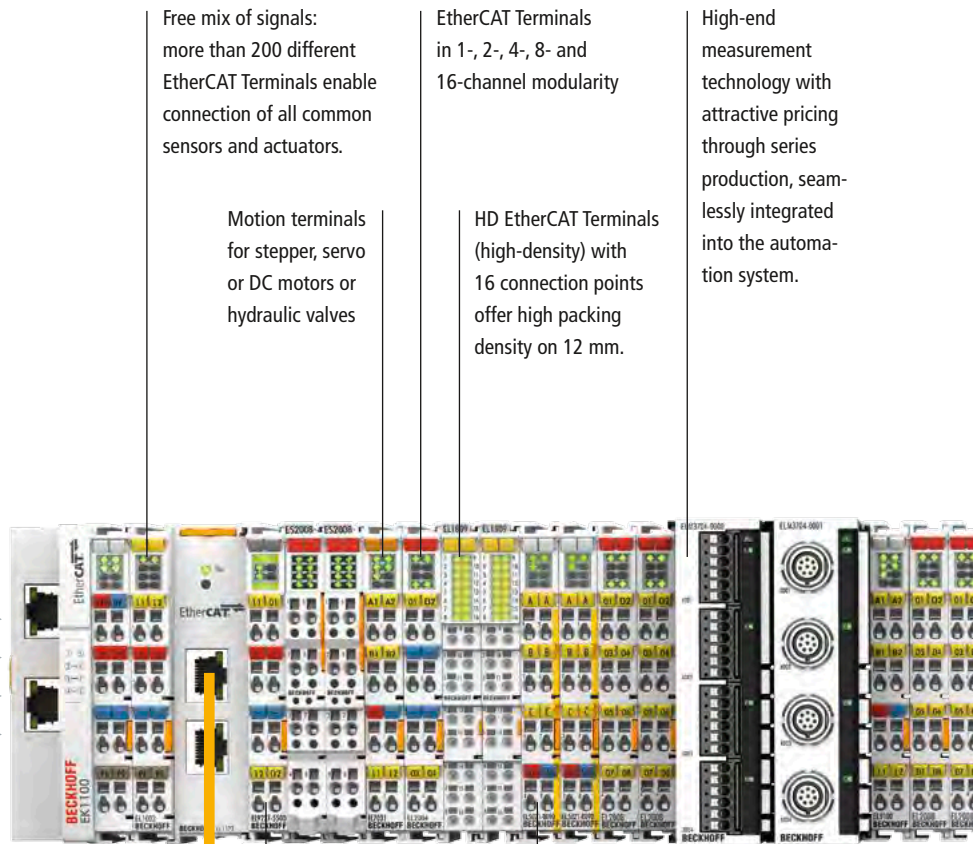
EtherCAT Coupler with integrated digital I/Os



Bus Coupler (e.g. PROFIBUS) for EtherCAT Terminals



Embedded PC series CX, further Embedded PCs see page 20



Free mix of signals: more than 200 different EtherCAT Terminals enable connection of all common sensors and actuators.

Motion terminals for stepper, servo or DC motors or hydraulic valves

EtherCAT Terminals in 1-, 2-, 4-, 8- and 16-channel modularity

HD EtherCAT Terminals (high-density) with 16 connection points offer high packing density on 12 mm.

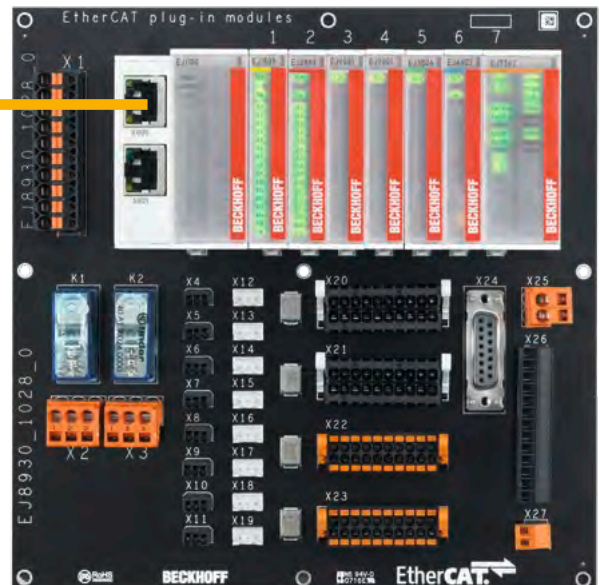
High-end measurement technology with attractive pricing through series production, seamlessly integrated into the automation system.

100 m Industrial Ethernet cable (100BASE-TX)

Integrated electronic overcurrent protection for safeguarding of potential groups incl. monitoring function

With the aid of the TwinSAFE SC technology it is possible to make use of standard signals for safety tasks in any network or fieldbus.

EtherCAT plug-in modules: very compact EtherCAT I/O system in IP 20 for plug-in into a circuit board (signal distribution board)



TwinSAFE: safety I/Os and compact Safety PLC for up to 128 safetyrelevant bus devices

Ultra-fast I/O terminals for I/O response times < 100 µs for fast I/O, oversampling and timestamp

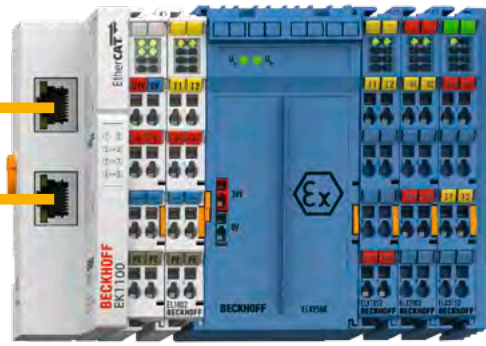
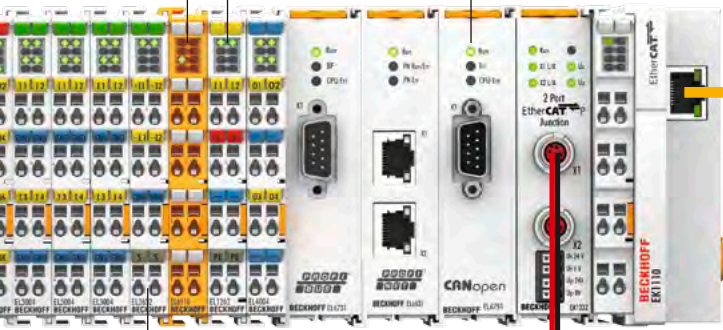
Optional fieldbus integration via decentralised fieldbus master/slave terminals

ELX terminals: direct connection of intrinsically safe sensors and actuators

2000/20,000 m fibre optic (100BASE-FX)

50 m Plastic Optical Fibre (100BASE-FX POF)

High-speed measurement, high-precision measurement, Condition Monitoring, energy monitoring











IP 67  
EtherCAT P  
Box

IP 67  
EtherCAT  
Box

IP 69K EtherCAT Box  
(stainless steel)

IP 67  
EtherCAT Box  
(die-cast zinc)

# Product overview fieldbus systems

Fieldbus	EtherCAT Terminal	EtherCAT Box	EtherCAT Plug-in Modules	Bus Terminal	Fieldbus Box	
	Couplers/Gateways	Modules		Bus Couplers/ PLC Master term. (IEC 61131-3)	Compact Box	Coupler Box
EtherCAT 	EK1xxx, EKM1xxx	EPxxxx	EJxxxx	BK1120		IL230x-B110
	EL6695 bridge	EQxxxx		BK1150		
		ERxxxx		BK1250		
EtherCAT  P	EK13xx	 EPPxxxx EP1312				
LIGHTBUS	EL6720 master			BK20x0	IPxxxx-B200	IL230x-B200
	EK3100			BK3xx0	BC31x0	IL230x-B31x
	EL6731 master/slave			LC3100	BX3100	
	EL6740 slave			BK40x0		IPxxxx-B400 IL230x-B400
CANopen	EL6751 master/slave			BK51xx	BC5150	IPxxxx-B51x IL230x-B51x
				LC5100	BX5100	
DeviceNet	EL6752 master/slave			BK52x0	BC5250	IPxxxx-B52x IL230x-B52x
				LC5200	BX5200	
ControlNet				BK7000		
CC-Link				BK7150		
Modbus				BK73x0	BC7300	IPxxxx-B730 IL230x-B730
SERCOS				BK7520		
RS485	EL6021, EL6022	EP600x		BK8000	BC8050	IPxxxx-B800 IL230x-B800
		EPP600x		KL6021	BX8000	
				KL6041		
RS232	EL6001, EL6002	EP600x		BK8100	BC8150	IPxxxx-B810 IL230x-B810
		EPP600x		KL6001	BX8000	
				KL6031		
Ethernet TCP/IP	EK9000 EL6601, EL6614 switch port			BK9xx0	BC9xxx	IL230x-B90x
					BX9000	
	EK9300 EL6631 RT controller/device EL6632 IRT controller	EP9300		BK9xx3		IL230x-B903
						
EtherNet/IP	EK9500 EL6652 master/slave			BK9xx5		IL230x-B905
AS-Interface	EL6201			KL62x1		
IO-Link	EL6224 master	EP622x, EPP6228 master	EJ6224 master	KL6224 master		
EIB/KNX				KL6301		
LON				KL6401		
MP-Bus				KL6771		
M-Bus				KL6781		
DALI/DSI				KL6811		
DALI 2				KL6821		
IEEE 1588	EL6688					
DMX	EL6851					
EnOcean				KL658x		
SMI				KL68x1		
BACnet	EL6861					

		Fieldbus Modules	Infrastructure Components	Embedded PC	Drive Technology	Accessories
PLC Box (IEC 61131-3)	IO-Link box	For thermo-couples/mV	Interfaces	Master/Slave	Servo Drives	Connectors/ Cables
		FM33xx-B110	FC90xx, FC11xx CUxxxx EP9xxx	CXxxxx	AX8000 AX5000	ZS1090-00xx ZK1090-9191 ZK1090-xxxx ZB7xxx ZK/ZS7xxx
			FC200x	CX1500-M/B200		Z1xxx
IL230x-C31x		FM33xx-B310	FC31xx	CXxxxx CX2500-M/B310		ZB3xxx ZK/ZS1031 ZB4200
			FC51xx	CXxxxx CX2500-M/B510		ZB51xx ZK/ZS1052
			FC52xx	CX1500-M/B520		ZB52xx ZK/ZS1052
				CXxxxx		ZK/ZS1031
			FC75xx	CXxxxx CXxxxx		ZK/ZS1031
IL230x-C810				CXxxxx		ZK/ZS1031
IL230x-C900			FC90xx CU2xxx, CU2508 Ethernet Switch CU2508	CXxxxx CXxxxx		ZS1090-00xx ZB90x0 ZK1090-xxxx ZS1090-00xx ZB90x0
			FC93xx IRT device CU2508	CXxxxx		ZK1090-xxxx ZS1090-00xx
	EPIxxxx, ERIxxxx devices					

# EtherCAT Terminal

► [www.beckhoff.com/EtherCAT-Terminal](http://www.beckhoff.com/EtherCAT-Terminal)



EtherCAT Couplers					
EtherCAT Couplers E-bus	<b>EK1100</b>	<b>EK1000</b> Ethernet/TSN	<b>EK1300</b> EtherCAT P	<b>EK1101</b> ID switch	<b>EKM1101</b> ID switch and diagnostics
	<b>EK1101-0080</b> ID switch, Fast Hot Connect	<b>EK1100-0008</b> M8 connection	<b>EK1501</b> ID switch, multimode fibre optic	<b>EK1501-0010</b> ID switch, singlemode fibre optic	<b>EK1501-0100</b> ID switch, multimode fibre optic to RJ45
	<b>EK1541</b> ID switch, POF				
EtherCAT Couplers E-bus with integrated digital I/Os	<b>EK1814</b> 4 inputs + 4 outputs	<b>EK1818</b> 8 inputs + 4 outputs	<b>EK1828</b> 4 inputs + 8 outputs	<b>EK1828-0010</b> 8 outputs	
	<b>EK1914</b> 4 inputs + 4 outputs, 2 safe inputs + 2 safe outputs	<b>EK1960</b> TwinSAFE Compact Controller, 20 safe digital inputs, 10 safe digital outputs			
EtherCAT Couplers K-bus	<b>BK1120</b>	<b>BK1150</b> "Compact"	<b>BK1250</b> between E-bus and K-bus terminals		
Bus Couplers (for ELxxxx)	<b>EK3100</b> PROFIBUS	<b>EK9000</b> Modbus TCP/UDP	<b>EK9160</b> IoT	<b>EK9300</b> PROFINET RT	<b>EK9500</b> EtherNet/IP
Extension system and junctions	<b>EK1110</b> extension end terminal	<b>EK1110-0008</b> extension end terminal, M8	<b>EK1122</b> 2-port junction	<b>EK1122-0008</b> 2-port junction, M8	<b>EK1122-0080</b> 2-port junction, Fast Hot Connect
	<b>EK1310</b> EtherCAT P extension with feed-in	<b>EK1322</b> EtherCAT P junction with feed-in	<b>EK1521</b> multimode fibre optic junction	<b>EK1521-0010</b> singlemode fibre optic junction	<b>EK1561</b> POF junction

Embedded PCs with E-bus interface see page 20 , Infrastructure Components see page 61

**i** Product announcement for availability status see [www.beckhoff.com](http://www.beckhoff.com)



## EtherCAT Terminal | Digital input 24 V DC: EL1xxx/ES1xxx

Signal	2-channel	4-channel	8-channel	16-channel
<b>Filter 3.0 ms</b>	<b>EL1002</b> type 3	<b>EL1004</b> type 3	<b>EL1004-0020</b> > 2500 V	<b>EL1008</b> type 3, 1-wire
		<b>EL1104</b> with sensor supply, type 3	<b>EL1804</b> 8 x 24 V, 4 x 0 V, type 3, 3-wire	<b>EL1808</b> 8 x 24 V DC, type 3, 2-wire
		<b>EL1084</b> negative switching	<b>EL1024</b> type 2	<b>EL1859</b> type 3, 8 inputs, 8 outputs, I <sub>max</sub> = 0.5 A
				<b>EL1088</b> negative switching
<b>Filter 10 μs</b>	<b>EL1012</b> type 3	<b>EL1014</b> type 3	<b>EL1034</b> potential-free inputs, type 1	<b>EL1018</b> type 3
		<b>EL1114</b> with sensor supply, type 3	<b>EL1814</b> 8 x 24 V, 4 x 0 V, type 3, 3-wire	<b>EL1819</b> type 3
			<b>EL1094</b> negative switching	<b>EL1872</b> flat-ribbon cable, type 3
<b>XFC:</b> <b>T<sub>ON</sub>/T<sub>OFF</sub> 1 μs</b>	<b>EL1202</b> fast input, type 3			<b>EL1258</b> multi-timestamping
	<b>EL1252</b> timestamp, type 3			<b>EL1259</b> 8 multi-timestamping inputs and outputs
	<b>EL1262</b> oversampling, type 3			
<b>Counter</b>	<b>EL1502</b> 100 kHz, 32 bit, type 1			
	<b>EL1512</b> 1 kHz, 16 bit, type 1			
<b>Safe input</b>		<b>EL1904</b> TwinSAFE, 4 safe inputs		

## EtherCAT Terminal | Digital input: EL1xxx/ES1xxx/ELX1xxx

Signal	2-channel	4-channel
<b>5 V DC</b>		<b>EL1124</b>
<b>12 V DC</b>		<b>EL1144</b>
<b>48 V DC</b>		<b>EL1134</b> filter 10 μs, type 1
<b>120 V AC/DC</b>	<b>EL1712</b> power contacts	<b>i</b>
<b>120 V DC</b>	<b>EL1712-0020</b> power contacts	<b>i</b>
<b>120...230 V AC</b>	<b>EL1702</b> power contacts	<b>i</b> <b>EL1722</b> no power contacts
<b>220 V DC</b>	<b>EL1702-0020</b> power contacts	<b>i</b>
<b>Thermistor</b>	<b>EL1382</b>	
<b>NAMUR</b>	<b>EL1052</b>	<b>EL1054</b>
<b>Ex i, NAMUR</b>	<b>ELX1052</b>	

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.  
EN 61131-2 specification ► [www.beckhoff.com/EN61131-2](http://www.beckhoff.com/EN61131-2)

## EtherCAT Terminal | Digital output 24 V DC: EL2xxx/ES2xxx/ELX2xxx

Signal	1-channel	2-channel	4-channel	8-channel	16-channel
$I_{\max} = 0.5 \text{ A}$		EL2002	EL2004	EL2008	EM2042 D-sub connection
			EL2014 with diagnostics	EL2808 8 x 0 V	EL2872 flat-ribbon cable
					EL2809
					EL2819 with diagnostics
			EL2084 negative switching	EL2088 negative switching	EL2889 negative switching
				EL1859 8 inputs, 8 outputs, filter 3.0 ms, type 3	EL2872-0010 flat-ribbon cable, negative switching
$I_{\max} = 2.0 \text{ A}$		EL2022	EL2024	EL2828	
		EL2032 with diagnostics	EL2034 with diagnostics		
$I_{\max} = \sum 8.0 \text{ A}$		EL2042 2 x 4.0 A, 1 x 8.0 A			
XFC: $T_{\text{ON}}/T_{\text{OFF}} 1 \mu\text{s}$		EL2202 push-pull outputs	EL2212 overexcitation, multi-timestamping	EL1259 8 multi-timestamping inputs and outputs	
		EL2252 timestamp	EL2262 oversampling	EL2258 multi-timestamping	
Ex i		ELX2002			
Safe output	EL2901 TwinSAFE, 1 safe output	<i>i</i> EL2902 TwinSAFE, 2 safe outputs	EL2904 TwinSAFE, 4 safe outputs		

## EtherCAT Terminal | Digital output: EL2xxx/ES2xxx

Signal	1-channel	2-channel	4-channel	8-channel
5 V DC			EL2124 $I_{\max} = \pm 20 \text{ mA}$	
12 V DC			EL2024-0010 $I_{\max} = 2.0 \text{ A}$	
30 V AC/DC ( $I_{\max} = 2.0 \text{ A}$ )			EL2784 potential-free	EL2788 potential-free
Relay (up to 230 V AC)		EL2602 $I_{\max} = 5.0 \text{ A}$ , make contact, power contacts	EL2622 $I_{\max} = 5.0 \text{ A}$ , make contact, no power contacts	EL2612 $I_{\max} = 2.0 \text{ A}$ , change-over, no power contacts
		EL2602-0010 $I_{\max} = 5.0 \text{ A}$ , make contact, power contacts, contact- protecting switching	EL2622-0010 $I_{\max} = 5.0 \text{ A}$ , make contact, no power contacts, contact- protecting switching	EL2652 $I_{\max} = 1.0 \text{ A}$ , change-over, no power contacts
			EL2624 $I_{\max} = 2.0 \text{ A}$ , make contact, no power contacts	

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.




## EtherCAT Terminal | Digital output: EL2xxx/ES2xxx

Signal	1-channel	2-channel			4-channel	8-channel
<b>Triac</b> (12...230 V AC)		EL2712 $I_{max} = 0.5 A$ , power contacts	<i>i</i> EL2722 $I_{max} = 1.0 A$ , mutually locked outputs	<i>i</i> EL2732 $I_{max} = 0.5 A$ , no power contacts		
<b>PWM</b>		EL2502 24 V DC, $I_{max} = 0.5 A$				
<b>Frequency output</b>	EL2521 1-channel AB, 0...500 kHz, RS422	EL2522 2-channel AB, 1-channel ABC, 0...4 MHz				
	EL2521-0024 1-channel AB, 0...500 kHz, 24 V DC					
<b>Current control</b>	EL2595 LED constant current terminal	EL2535 24 V DC, $I_{max} = \pm 50 mA$ , $\pm 1 A$ or $\pm 2 A$	EL2545 50 V DC, $I_{max} = \pm 3.5 A$	<i>i</i>		

## EtherCAT Terminal | Analog input: EL3xxx/ES3xxx/ELM3xxx/ELX3xxx

Signal	1-channel	2-channel		4-channel		5-/8-channel
<b>Multi-function</b>	EL3751 24 bit, 10 ksps	ELM3702 <i>i</i> 24 bit, 10 ksps		ELM3704 <i>i</i>	ELM3704-0001 <i>i</i>	
				EL3174 16 bit, NAMUR NE43	EL3174-0002 16 bit, electrically isolated, NAMUR NE43	
				EL3174-0032 16 bit, electrically isolated, NAMUR NE43, $\pm 3 V$	EL3174-0090 <i>i</i> 16 bit, NAMUR NE43, TwinSAFE SC	
<b><math>\pm 10 V</math></b>	EL3001 single-ended, 12 bit	EL3002 single-ended, 12 bit		EL3004 single-ended, 12 bit		EL3008 single-ended, 12 bit
	EL3101 differential input, 16 bit	EL3102 differential input, 16 bit	EL3602 differential input, 24 bit	EL3104 differential input, 16 bit		
		EL3702 differential input, 16 bit, oversampling				
<b>0...10 V</b>	EL3061 12 bit	EL3161 16 bit	EL3062 12 bit	EL3162 16 bit	EL3064 12 bit	EL3164 16 bit
						EL3068 12 bit
<b>0...30 V</b>		EL3062-0030 12 bit				
<b><math>\pm 30 V...</math> <math>\pm 20 mV</math></b>		ELM3002 24 bit, 20 ksps		ELM3004 24 bit, 10 ksps		
			EL3602-0002 differential input, 24 bit			
<b><math>\pm 200 mV</math></b>			EL3602-0010 differential input, 24 bit			
<b><math>\pm 75 mV</math></b>						

## EtherCAT Terminal | Analog input: EL3xxx/ES3xxx/ELM3xxx/ELX3xxx

Signal	1-channel		2-channel		4-channel		5-/8-channel
0...20 mA	<b>EL3041</b> single-ended, 12 bit	<b>EL3141</b> single-ended, 16 bit	<b>EL3042</b> single-ended, 12 bit	<b>EL3142</b> single-ended, 16 bit	<b>EL3044</b> single-ended, 12 bit	<b>EL3144</b> single-ended, 16 bit	<b>EL3048</b> single-ended, 12 bit
	<b>EL3011</b> differential input, 12 bit	<b>EL3111</b> differential input, 16 bit	<b>EL3742</b> differential input, 16 bit, oversampling	<b>EL3012</b> differential input, 12 bit	<b>EL3014</b> differential input, 12 bit	<b>EL3114</b> differential input, 16 bit	
			<b>EL3112</b> differential input, 16 bit	<b>EL3612</b> differential input, 24 bit			
4...20 mA	<b>EL3051</b> single-ended, 12 bit	<b>EL3151</b> single-ended, 16 bit	<b>EL3052</b> single-ended, 12 bit	<b>EL3152</b> single-ended, 16 bit	<b>EL3054</b> single-ended, 12 bit	<b>EL3154</b> single-ended, 16 bit	<b>EL3058</b> single-ended, 12 bit
	<b>EL3021</b> differential input, 12 bit	<b>EL3121</b> differential input, 16 bit	<b>EL3022</b> differential input, 12 bit	<b>EL3122</b> differential input, 16 bit	<b>EL3024</b> differential input, 12 bit	<b>EL3124</b> differential input, 16 bit	
		<b>EL3621-0020</b> differential input, 24 bit	<b>EL3182</b> single-ended, 16 bit, HART			<b>EL3124-0090</b> 16 bit, TwinSAFE SC	
Ex i, 0/4...20 mA	<b>ELX3181</b> single-ended, 16 bit, HART		<b>ELX3152</b> single-ended, 16 bit				
±20 mA			<b>EL3112-0011</b> differential input, 16 bit	<b>ELM3102</b> 24 bit, 20 ksp/s, NAMUR NE43	<b>ELM3104</b> 24 bit, 10 ksp/s, NAMUR NE43		
±10 mA			<b>EL3142-0010</b> single-ended, 16 bit				
Thermo- couple/mV	<b>EL3311</b> 16 bit		<b>EL3312</b> 16 bit		<b>EL3314</b> 16 bit	<b>EL3314-0090</b> 16 bit, TwinSAFE SC	<b>EL3318</b> 16 bit
					<b>EL3314-0002</b>  24 bit, electrically isolated		
Ex i, thermo- couple/mV			<b>ELX3312</b> 16 bit		<b>ELX3314</b> 16 bit		
Resistance thermometer (RTD)	<b>EL3201</b> 16 bit		<b>EL3202</b> 16 bit		<b>EL3204</b> 2-wire, 16 bit	<b>EL3204-0200</b> 16 bit, universal input for RTD	<b>EL3208</b> 16 bit
					<b>EL3214</b> 3-wire, 16 bit	<b>EL3214-0090</b> 16 bit, TwinSAFE SC	
Ex i, resistance thermometer (RTD)			<b>ELX3202</b> 16 bit		<b>ELX3204</b> 2-wire, 16 bit		
Measurement bridge (SG)	<b>EL3351</b>	<b>EL3356</b> self-calibration	<b>ELM3502</b>  24 bit, 20 ksp/s		<b>ELM3504</b>  24 bit, 10 ksp/s		
	<b>EL3356-0010</b> 24 bit, 10 ksp/s	<b>EL3356-0090</b> TwinSAFE SC					
Ex i, measurement bridge (SG)	<b>ELX3351</b> 16 bit						

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.

### EtherCAT Terminal | Analog input: EL3xxx/ES3xxx/ELM3xxx/ELX3xxx

Signal	1-channel	2-channel	4-channel	5-/8-channel
<b>Measurement technology</b>	<b>EL3681</b> digital multimeter terminal, 18 bit	<b>EL3692</b> resistance measurement, 10 mΩ...10 MΩ		<b>EL3255</b> potentiometer measurement, 5-channel
<b>Condition Monitoring/ IEPE</b>		<b>EL3632</b> 16 bit, 50 ksp/s	<b>ELM3602</b> 24 bit, 50 ksp/s	<b>ELM3604</b> 24 bit, 20 ksp/s
<b>Pressure measuring</b>	<b>EM3701</b> differential pressure measuring, -100...+100 hPa	<b>EM3702</b> relative pressure measuring, 7500 hPa	<b>EM3712</b> relative pressure measuring, -1000...+1000 hPa	

### EtherCAT Terminal | Analog input 3-phase power measurement terminal: EL3xxx

Signal	≤ 500 V						> 500 V
<b>Power measurement</b>	<b>EL3403</b> 500 V AC, 1 A	<b>EL3423</b> 480 V AC/DC, 1 A, Economy	<b>EL3433</b> 500 V AC, 10 A	<b>EL3443</b> 480 V AC/DC, 1 A, extended functionality	<b>EL3443-0010</b> 480 V AC/DC, 5 A, extended functionality	<b>EL3483</b> 480 V AC/DC, mains monitor	<b>EL3413</b> 690 V AC, 5 A
<b>Power monitoring</b>	<b>EL3773</b> 500 V AC/DC, 10 ksp/s						<b>EL3783</b> 690 V AC, 20 ksp/s

### EtherCAT Terminal | Analog output: EL4xxx/ES4xxx/ELX4xxx

Signal	1-channel	2-channel	4-channel	8-channel		
<b>0...10 V</b>	<b>EL4001</b> 12 bit	<b>EL4002</b> 12 bit	<b>EL4102</b> 16 bit	<b>EL4004</b> 12 bit	<b>EL4104</b> 16 bit	<b>EL4008</b> 12 bit
<b>±10 V</b>	<b>EL4031</b> 12 bit	<b>EL4032</b> 12 bit	<b>EL4132</b> 16 bit	<b>EL4034</b> 12 bit	<b>EL4134</b> 16 bit	<b>EL4038</b> 12 bit
		<b>EL4732</b> 16 bit, oversampling				
<b>0...20 mA</b>	<b>EL4011</b> 12 bit	<b>EL4012</b> 12 bit	<b>EL4112</b> 16 bit	<b>EL4014</b> 12 bit	<b>EL4114</b> 16 bit	<b>EL4018</b> 12 bit
		<b>EL4712</b> 16 bit, oversampling				
<b>4...20 mA</b>	<b>EL4021</b> 12 bit	<b>EL4022</b> 12 bit		<b>EL4024</b> 12 bit		<b>EL4028</b> 12 bit
		<b>EL4122</b> 16 bit		<b>EL4124</b> 16 bit		
<b>Ex i, 0/4...20 mA</b>	<b>ELX4181</b> HART, 16 bit					
<b>±10 mA</b>		<b>EL4112-0010</b> 16 bit				

## EtherCAT Terminal | Position measurement: EL5xxx/ES5xxx/ELX5xxx

Signal	1-channel				2-channel	
<b>Absolute encoder</b>	<b>EL5001</b> SSI encoder interface	<b>EL5001-0011</b> SSI monitor terminal	<b>EL5001-0090</b> SSI encoder interface, TwinSAFE SC	<b>i</b>	<b>EL5002</b> SSI encoder interface	<b>EL5032</b> EnDat 2.2 interface
						<b>EL5042</b> BiSS-C interface, unidirectional
<b>Incremental encoder</b>	<b>EL5151</b> incremental encoder interface 24 V DC	<b>EL5151-0021</b> incremental encoder interface 24 V DC, parameterisable 24 V DC output	<b>EL5151-0090</b> incremental encoder interface 24 V DC, TwinSAFE SC	<b>i</b>	<b>EL5152</b> incremental encoder interface 24 V DC	
	<b>EL5101</b> incremental encoder interface, RS422, 4 million increments/s	<b>EL5101-0010</b> incremental encoder interface, RS422, 20 million increments/s	<b>EL5101-0011</b> incremental encoder interface, RS422, oversampling	<b>EL5101-0090</b> incremental encoder interface, RS422, TwinSAFE SC		
	<b>EL5021</b> SinCos encoder interface, 1 V <sub>PP</sub>	<b>EL5021-0090</b> SinCos encoder interface, 1 V <sub>PP</sub> , TwinSAFE SC				
<b>Ex i, incremental encoder</b>	<b>ELX5151</b> incremental encoder interface NAMUR					

## EtherCAT Terminal | Communication: EL6xxx/ES6xxx

Signal	1-channel			2-channel		4-channel
<b>System</b>	<b>EL6090</b> display terminal	<b>EL6070</b> license key terminal	<b>EL6080</b> memory terminal 128 kbyte			
<b>Serial</b>	<b>EL6001</b> RS232, 115.2 kbaud	<b>EL6021</b> RS422/RS485, 115.2 kbaud		<b>EL6002</b> RS232, 115.2 kbaud, D-sub	<b>EL6022</b> RS422/RS485, 115.2 kbaud, D-sub	
<b>EtherCAT/Ethernet</b>	<b>EL6601</b> switch port	<b>EL6688</b> IEEE 1588 master/slave		<b>EL6692</b> EtherCAT bridge	<b>EL6695</b> EtherCAT bridge, high performance	<b>EL6614</b> switch port
<b>Master</b>	<b>EL6201</b> AS-Interface	<b>EL6631</b> PROFINET RT	<b>EL6632</b> PROFINET IRT	<b>i</b>	<b>EL6224</b> IO-Link	
	<b>EL6652</b> EtherNet/IP	<b>EL6720</b> Lightbus	<b>EL6731</b> PROFIBUS		<b>EL6224-0090</b> IO-Link, TwinSAFE SC	
	<b>EL6751</b> CANopen	<b>EL6752</b> DeviceNet	<b>EL6851</b> DMX			
	<b>EL6861</b> BACnet, MS/TP, RS485					
<b>Slave</b>	<b>EL6631-0010</b> PROFINET RT	<b>EL6652-0010</b> EtherNet/IP	<b>EL6731-0010</b> PROFIBUS			
	<b>EL6740-0010</b> Interbus	<b>EL6751-0010</b> CANopen	<b>EL6752-0010</b> DeviceNet			
	<b>EL6851-0010</b> DMX					
<b>Safety</b>	<b>EL6900</b> TwinSAFE Logic	<b>EL6910</b> TwinSAFE Logic	<b>EL6930</b> TwinSAFE/PROFIsafe logic and gateway			

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.

## EtherCAT Terminal | Motion: EL7xxx/ES7xxx/EM7xxx

	< 3 A	3...5 A	> 5 A
<b>Servomotor</b>	<b>EL7201-9014</b> <i>I<sub>ms</sub></i> = 2.8 A, 50 V DC, OCT, STO	<b>EL7211-9014</b> <i>I<sub>ms</sub></i> = 4.5 A, 50 V DC, OCT, STO	<b>EL7221-9014</b> <i>I<sub>ms</sub></i> = 7...8 A with ZB8610, 50 V DC, OCT, STO
	<b>EL7201-0010</b> <i>I<sub>ms</sub></i> = 2.8 A, 50 V DC, OCT	<b>EL7211-0010</b> <i>I<sub>ms</sub></i> = 4.5 A, 50 V DC, OCT	<b>ZB8610</b> fan cartridge for EtherCAT and Bus Terminals
	<b>EL7201</b> <i>I<sub>ms</sub></i> = 2.8 A, 50 V DC, resolver	<b>EL7211</b> <i>I<sub>ms</sub></i> = 4.5 A, 50 V DC, resolver	
<b>Stepper motor</b>	<b>EL7031</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC	<b>EL7041</b> <i>I<sub>max</sub></i> = 5.0 A, 50 V DC, incremental encoder	
	<b>EL7031-0030</b> <i>I<sub>max</sub></i> = 2.8 A, 24 V DC, 2 AI	<b>EL7041-0052</b> <i>I<sub>max</sub></i> = 5.0 A, 50 V DC	<b>i</b>
	<b>EL7037</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC, incremental encoder, vector control	<b>EL7047</b> <i>I<sub>max</sub></i> = 5.0 A, 50 V DC, incremental encoder, vector control	
<b>DC motor output stage</b>	<b>EL7332</b> <i>I<sub>max</sub></i> = 1.0 A, 24 V DC	<b>EL7342</b> <i>I<sub>max</sub></i> = 3.5 A, 50 V DC, incremental encoder	
		<b>EL7411-9014</b> <i>I<sub>ms</sub></i> = 4.5 A, 50 V DC, STO	<b>i</b>
<b>4-axis interface</b>	<b>EM7004</b> 4 incremental encoders, 32 digital I/Os 24 V DC, 4 analog outputs ±10 V		

## EtherCAT Terminal | System terminals: EL9xxx/ES9xxx/ELM9xxx/ELX9xxx

Signal	System				
<b>Components for system bus</b>	<b>EL9011</b> bus end cover	<b>EL9012</b> bus end cover for power and E-bus contacts	<b>ELM9012</b> bus end cover for ELMxxxx, black	<b>ELX9012</b> bus end cover for ELXxxxx, blue	<b>EL9195</b> shield terminal
	<b>EL9070</b> shield terminal	<b>EL9080</b> isolation terminal			
<b>Potential distribution</b>	<b>EL9180</b> 2 clamping units per power contact	<b>EL9181</b> 2 x 8 terminal points	<b>EL9182</b> 8 x 2 terminal points	<b>EL9183</b> 1 x 16 terminal points	<b>EL9184</b> 8 x 24 V DC, 8 x 0 V DC
	<b>EL9185</b> 4 clamping units at 2 power contacts	<b>EL9186</b> 8 x 24 V DC	<b>EL9187</b> 8 x 0 V DC	<b>EL9188</b> 16 x 24 V DC	<b>EL9189</b> 16 x 0 V DC
<b>Potential supply, 24 V DC</b>	<b>EL9100</b>	<b>EL9110</b> diagnostics	<b>EL9200</b> with fuse	<b>EL9210</b> diagnostics, with fuse	<b>EL9520</b> AS-Interface potential supply with filter
<b>Potential supply, 120...230 V AC</b>	<b>EL9150</b> with LED	<b>EL9160</b> diagnostics	<b>i</b> <b>EL9190</b>	<b>EL9250</b> with fuse, with LED	<b>i</b> <b>EL9260</b> diagnostics, with fuse
	<b>EL9290</b> with fuse	<b>i</b>			
<b>Overcurrent protection, 24 V DC</b>	<b>EL9221</b> 1-channel	<b>i</b> <b>EL9222</b> 2-channel	<b>i</b> <b>EL9227</b> 2-channel, extended functionalities	<b>i</b>	
<b>Power supply</b>	<b>EL9410</b> input 24 V DC, output 5 V DC/2 A	<b>ELM9410</b> input 24 V DC, output 5 V DC/2 A	<b>i</b> <b>EL9505</b> input 24 V DC, output 5 V DC/0.5 A	<b>EL9508</b> input 24 V DC, output 8 V DC/0.5 A	<b>EL9510</b> input 24 V DC, output 10 V DC/0.5 A
	<b>EL9512</b> input 24 V DC, output 12 V DC/0.5 A	<b>EL9515</b> input 24 V DC, output 15 V DC/0.5 A	<b>EL9560</b> input 24 V DC, output 24 V DC/0.1 A with electrical isolation	<b>ELX9560</b> for ELXxxxx, input 24 V DC, output 24 V DC/1.0 A	
<b>Filtering and smoothing</b>	<b>EL9540</b> surge filter terminal for field supply	<b>EL9550</b> surge filter terminal for system/field supply	<b>EL9576</b> brake chopper terminal, up to 72 V DC, 155 µF	<b>ZB8110</b> external ballast resistor	

# EtherCAT Box

► [www.beckhoff.com/EtherCAT-Box](http://www.beckhoff.com/EtherCAT-Box)



EPxxxx



ERxxxx



EQxxxx

## EtherCAT Box | Digital I/O

Input		8 x M8	16 x M8	4 x M12	8 x M12	Other
24 V DC	8-channel filter 3.0 ms	EP1008-0001 ER1008-0001		EP1008-0002 ER1008-0002 EQ1008-0002	EP1008-0022 ER1008-0022	
	8-channel filter 10 µs	EP1018-0001 ER1018-0001		EP1018-0002 ER1018-0002		
	8-channel filter 10 µs, negative switching	EP1098-0001 ER1098-0001				
	8-channel 2-channel timestamp	EP1258-0001 ER1258-0001		EP1258-0002 ER1258-0002		
	8-channel multi-function input			EP1518-0002 ER1518-0002		
	8-channel TwinSAFE, 8 safe inputs			EP1908-0002		
	16-channel filter 3.0 ms		EP1809-0021 ER1809-0021		EP1809-0022 ER1809-0022 EQ1809-0022	
	16-channel filter 10 µs		EP1819-0021 ER1819-0021		EP1819-0022 ER1819-0022	
	16-channel filter 10 µs, D-sub, 25-pin					EP1816-0008 EP1816-3008 acceleration sensor
	Output		8 x M8	16 x M8	4 x M12	8 x M12
24 V DC	8-channel $I_{max} = 0.5 A$	EP2008-0001 ER2008-0001		EP2008-0002 ER2008-0002 EQ2008-0002	EP2008-0022 ER2008-0022	
	8-channel $I_{max} = 2 A, \sum 4 A$	EP2028-0001 ER2028-0001		EP2028-0002 ER2028-0002		
	8-channel $I_{max} = 2.8 A, \sum 16 A$				EP2028-0032 ER2028-1032	
	8-channel $I_{max} = 2 A, \sum 4 A, \text{ with diagnostics}$	EP2038-0001 ER2038-0001		EP2038-0002 ER2038-0002		
	16-channel $I_{max} = 0.5 A, \sum 4 A$		EP2809-0021 ER2809-0021		EP2809-0022 ER2809-0022 EQ2809-0022	
	16-channel $I_{max} = 0.5 A, \sum 4 A$					EP2816-0008 D-sub, 25-pin EP2816-0010 2 x D-sub, 9-pin EP2816-0004 M16, 19-pin EP2816-0003 IP 20 plug EP2817-0008 D-sub, 25-pin
	24-channel $I_{max} = 0.5 A$					
	25 V AC/ 30 V DC	4-channel relay output			EP2624-0002 ER2624-0002	


EPxxxx: industrial housing in IP 67, ERxxxx: zinc die-cast housing in IP 67, EQxxxx: stainless steel housing in IP 69K



## EtherCAT Box | Digital I/O


Combi		8 x M8	16 x M8	4 x M12	8 x M12	Other
24 V DC	<b>8-channel</b> 4 inputs + 4 outputs, filter 3.0 ms, $I_{max} = 0.5 A$	EP2308-0001 ER2308-0001		EP2308-0002 ER2308-0002		
	<b>8-channel</b> 4 inputs + 4 outputs, filter 10 $\mu s$ , $I_{max} = 0.5 A$	EP2318-0001 ER2318-0001		EP2318-0002 ER2318-0002		
	<b>8-channel</b> 4 inputs + 4 outputs, filter 3.0 ms, $I_{max} = 2 A$	EP2328-0001 ER2328-0001		EP2328-0002 ER2328-0002		
	<b>8-channel</b> 8 inputs/outputs, filter 10 $\mu s$ , $I_{max} = 0.5 A$	EP2338-0001 ER2338-0001		EP2338-0002 ER2338-0002		
	<b>8-channel</b> 8 inputs/outputs, filter 3.0 ms, $I_{max} = 0.5 A$	EP2338-1001 ER2338-1001		EP2338-1002 ER2338-1002		
	<b>16-channel</b> 16 inputs/outputs, filter 3.0 ms, $I_{max} = 0.5 A$ , $\Sigma 4 A$		EP2339-0021 ER2339-0021		EP2339-0022 ER2339-0022 EQ2339-0022	
	<b>16-channel</b> 16 inputs/outputs, filter 10 $\mu s$ , $I_{max} = 0.5 A$ , $\Sigma 4 A$		EP2349-0021 ER2349-0021		EP2349-0022 ER2349-0022	
	<b>16-channel</b> 8 inputs + 8 outputs, filter 10 $\mu s$ , $I_{max} = 0.5 A$					EP2316-0008 D-sub, 25-pin EP2316-0003 IP 20 plug

## EtherCAT Box | Analog I/O

Input		M8	M12
±10 V, 0/4...20 mA	<b>2-channel</b> parameterisable, with galvanic isolation, single-ended, 16 bit		EP3162-0002
	<b>4-channel</b> parameterisable, differential inputs, 16 bit		EP3174-0002 ER3174-0002 EQ3174-0002 EP3174-0092  TwinSAFE SC
	<b>2-channel</b> 2 analog inputs, parameterisable, single-ended, 16 bit, 2 digital control outputs (sink/source type), 24 V DC, short-circuit-proof		EP3182-1002
	<b>4-channel</b> parameterisable, single-ended, 16 bit		EP3184-0002 ER3184-0002 EP3184-1002 2 channels per socket ER3184-1002 2 channels per socket
<b>Resistance thermometer (RTD)</b>	<b>4-channel</b> PT100, PT200, PT500, PT1000, Ni100, Ni120, Ni1000, 16 bit		EP3204-0002 ER3204-0002 EQ3204-0002
<b>Thermo-couple/mV</b>	<b>4-channel</b> type J, K, L, B, E, N, R, S, T, U, 16 bit		EP3314-0002 ER3314-0002 EQ3314-0002
<b>Measuring bridge (SG)</b>	<b>1-channel</b> 24 bit, self-calibration		EP3356-0022
<b>Condition Monitoring/ IEPE</b>	<b>2-channel</b>	EP3632-0001	
<b>Pressure measuring</b>	<b>4-channel</b> differential/absolute pressure measurement, 6 digital inputs, 2 digital outputs	EP3744-0041 4 pressure inputs -1...1 bar (differential pressure to fifth connection) EP3744-1041 4 pressure inputs 0...7 bar (differential pressure to fifth connection)	
Output		M8	M12
±10 V, 0/4...20 mA	<b>4-channel</b> parameterisable, 16 bit		EP4174-0002 ER4174-0002
	<b>4-channel</b> 2 inputs + 2 outputs, parameterisable, 16 bit		EP4374-0002 ER4374-0002

EPxxxx: industrial housing in IP 67, ERxxxx: zinc die-cast housing in IP 67, EQxxxx: stainless steel housing in IP 69K

## EtherCAT Box | Special functions

Function	M8	M12	Other
<b>Position measurement</b>	<b>SSI encoder interface</b> 1 MHz, 32 bit	EP5001-0002	
	<b>Incremental encoder interface RS422</b> 32/16 bit, 5 V DC sensor supply	EP5101-0002 ER5101-0002	EP5101-0011 D-sub, 4 million increments/s EP5101-2011 D-sub, 20 million increments/s
	<b>Incremental encoder interface RS422</b> 32/16 bit, 24 V DC sensor supply	EP5101-1002 ER5101-1002	
	<b>Incremental encoder interface 24 V DC</b> 32/16 bit	EP5151-0002 ER5151-0002	
<b>Communication</b>	<b>Serial interface</b> 1-channel, RS232, RS422/RS485, 5 V DC/1 A	EP6001-0002 ER6001-0002	
	<b>Serial interface</b> 2-channel, RS232, RS422/RS485	EP6002-0002 ER6002-0002	
	<b>IO-Link master</b> 4 ports	EP6224-2022 Class A EP6224-3022 Class B	
	<b>IO-Link master</b> 8 ports	EP6228-0022 Class A EP6228-3032 Class B	
<b>Motion</b>	<b>Servomotor module</b> $I_{ms} = 4.5 \text{ A}$ , 50 V DC, OCT, STO		EP7211-9034
	<b>Stepper motor module</b> $I_{max} = 1.5 \text{ A}$ , 50 V DC, incremental encoder	EP7041-1002 ER7041-1002	
	<b>Stepper motor module</b> $I_{max} = 5 \text{ A}$ , 50 V DC, incremental encoder	EP7041-0002 ER7041-0002 EP7041-2002 ER7041-2002 EP7041-3002 ER7041-3002 EP7041-3102	
	<b>DC motor output stage</b> $I_{max} = 3.5 \text{ A}$ , 50 V DC	EP7342-0002 ER7342-0002	
	<b>Multi-functional I/O box</b> 8 digital inputs/outputs, 2 x tachometer input, 2 x 0/4...20 mA input, 1 x 0/4...20 mA output, 1 x 1.2 A PWMi output	EP8309-1022 ER8309-1022	
	<b>EtherCAT Box</b> 3 decimal ID switches	EP1111-0000	
	<b>EtherCAT junction</b> 2-channel	EP1122-0001	
<b>EtherCAT P junction</b> 2 ports	EP1312-0001		
<b>EtherCAT junction</b> 8 ports	EP9128-0021		
<b>System</b>	<b>Power distribution</b> 4/4-channel		EP9214-0023 7/8" plug, 7/8" socket
	<b>Power distribution with current measurement/data logging</b> 4/4-channel		EP9224-0023 7/8" plug, 7/8" socket
	<b>1-channel power distribution box ENP to EtherCAT P</b>		EP9221-0057 ENP-B17 plug, ENP-B17 socket
	<b>4-channel power distribution box ENP to EtherCAT P</b>		EP9224-0037 ENP-B17 plug, ENP-B17 socket
	<b>PROFINET RT EtherCAT Box</b> EtherCAT Box interface with PROFINET RT	EP9300-0022	
	<b>EtherCAT media converter fibre optic</b> 1-channel		EP9521-0020
	<b>EtherCAT Box</b> 3 decimal ID switches	EP1111-0000	
	<b>EtherCAT junction</b> 2-channel	EP1122-0001	

# EtherCAT P Box


► [www.beckhoff.com/EtherCAT-P-Box](http://www.beckhoff.com/EtherCAT-P-Box)



EtherCAT P Box   Digital I/O						
Input	4 x M8	8 x M8	16 x M8	4 x M12	8 x M12	Other
24 V DC	4-channel filter 3.0 ms	EPP1004- 0061				
	8-channel filter 3.0 ms		EPP1008- 0001	EPP1008- 0002	EPP1008- 0022	
	8-channel filter 10 µs		EPP1018- 0001	EPP1018- 0002		
	8-channel 2-channel timestamp		EPP1258- 0001	EPP1258- 0002		
	8-channel multi-function input			EPP1518- 0002		
	16-channel filter 3.0 ms			EPP1809- 0021		EPP1809- 0022
	16-channel filter 10 µs			EPP1819- 0021		EPP1819- 0022
	16-channel filter 10 µs, D-sub, 25-pin					EPP1816- 0008 EPP1816- 3008 acceleration sensor
Output	4 x M8	8 x M8	16 x M8	4 x M12	8 x M12	Other
24 V DC	8-channel $I_{max} = 0.5 A, \sum 3 A$		EPP2008- 0001	EPP2008- 0002	EPP2008- 0022	
	8-channel $I_{max} = 2 A, \sum 3 A$		EPP2028- 0001	EPP2028- 0002		
	8-channel $I_{max} = 2 A, \sum 3 A, \text{ with diagnostics}$		EPP2038- 0001	EPP2038- 0002		
	16-channel $I_{max} = 0.5 A, \sum 3 A$			EPP2809- 0021		EPP2809- 0022
	16-channel $I_{max} = 0.5 A, \sum 3 A$					EPP2816- 0008 D-sub, 25-pin EPP2816- 0010 2 x D-sub, 9-pin EPP2816- 0004 M16, 19-pin
	24-channel $I_{max} = 0.5 A$					EPP2817- 0008 D-sub, 25-pin
25 V AC/ 30 V DC	4-channel relay output			EPP2624- 0002		



## EtherCAT P Box | Digital I/O

Combi		4 x M8	8 x M8	16 x M8	4 x M12	8 x M12	Other
24 V DC	<b>4-channel</b> 4 inputs/outputs, filter 10 $\mu$ s, $I_{max} = 0.5$ A, $\Sigma$ 3 A	EPP2334- 0061					
	<b>8-channel</b> 4 inputs + 4 outputs, filter 3.0 ms, $I_{max} = 0.5$ A		EPP2308- 0001		EPP2308- 0002		
	<b>8-channel</b> 4 inputs + 4 outputs, filter 10 $\mu$ s, $I_{max} = 0.5$ A		EPP2318- 0001		EPP2318- 0002		
	<b>8-channel</b> 4 inputs + 4 outputs, filter 3.0 ms, $I_{max} = 2$ A, $\Sigma$ 3 A		EPP2328- 0001		EPP2328- 0002		
	<b>8-channel</b> 8 inputs/outputs, filter 10 $\mu$ s, $I_{max} = 0.5$ A, $\Sigma$ 3 A		EPP2338- 0001		EPP2338- 0002		
	<b>8-channel</b> 8 inputs/outputs, filter 3.0 ms, $I_{max} = 0.5$ A, $\Sigma$ 3 A		EPP2338- 1001		EPP2338- 1002		
	<b>16-channel</b> 16 inputs/outputs, filter 3.0 ms, $I_{max} = 0.5$ A, $\Sigma$ 3 A				EPP2339- 0021		EPP2339- 0022
	<b>16-channel</b> 16 inputs/outputs, filter 10 $\mu$ s, $I_{max} = 0.5$ A, $\Sigma$ 3 A				EPP2349- 0021		EPP2349- 0022
	<b>16-channel</b> 8 inputs + 8 outputs, filter 10 $\mu$ s, $I_{max} = 0.5$ A, $\Sigma$ 3 A						EPP2316- 0008 D-sub, 25-pin EPP2316- 0003 IP 20 plug

## EtherCAT P Box | Analog I/O

Input		M8	M12
±10 V, 0/4...20 mA	4-channel parameterisable, differential input, 16 bit		EPP3174-0002
	4-channel parameterisable, single-ended, 16 bit		EPP3184-0002
Resistance thermometer (RTD)	4-channel PT100, PT200, PT500, PT1000, Ni100, Ni120, Ni1000, 16 bit		EPP3204-0002
Thermo- couple/mV	4-channel type J, K, L, B, E, N, R, S, T, U, 16 bit		EPP3314-0002
Condition Monitoring/ IEPE	2-channel	EPP3632-0001	
Pressure measuring	4-channel differential/absolute pressure measurement, 6 digital inputs, 2 digital outputs	EPP3744-0041 4 pressure inputs -1...1 bar (differential pressure to fifth connection)	
		EPP3744-1041 4 pressure inputs 0...7 bar (differential pressure to fifth connection)	
Output		M8	M12
±10 V, 0/4...20 mA	4-channel parameterisable, 16 bit		EPP4174-0002
	4-channel 2 inputs + 2 outputs, parameterisable, 16 bit		EPP4374-0002

## EtherCAT P Box | Special functions

Function	M8	M12	Other	
<b>Position measurement</b>	<b>Incremental encoder interface RS422</b> 32/16 bit, 5 V DC sensor supply		EPP5101-0002 EPP5101-0011 D-sub, 4 million increments/s	
	<b>Incremental encoder interface RS422</b> 32/16 bit, 24 V DC sensor supply		EPP5101-1002	
	<b>Incremental encoder interface 24 V DC</b> 32/16 bit		EPP5151-0002	
<b>Communication</b>	<b>Serial interface</b> 1-channel, RS232, RS422/RS485, 5 V DC/1 A		EPP6001-0002	
	<b>Serial interface</b> 2-channel, RS232, RS422/RS485		EPP6002-0002	
	<b>IO-Link master</b> Class A, 8 ports		EPP6228-0022 <u>i</u>	
<b>Motion</b>	<b>Stepper motor module</b> $I_{max} = 1.5 \text{ A}$ , 50 V DC, incremental encoder		EPP7041-1002	
	<b>Stepper motor module</b> $I_{max} = 5.0 \text{ A}$ , 50 V DC, incremental encoder		EPP7041-3002	
	<b>DC motor output stage</b> $I_{max} = 3.5 \text{ A}$ , 50 V DC		EPP7342-0002	
<b>System</b>	<b>EtherCAT P Box</b> 3 decimal ID switches	EPP1111-0000		
	<b>EtherCAT P junction</b> 3 ports, with feed-in	EPP1322-0001		
	<b>EtherCAT P junction</b> 3 ports, with refresh	EPP1332-0001		
	<b>EtherCAT P junction</b> 3 ports	EPP1342-0001		
	<b>EtherCAT P Box</b> EtherCAT P/EtherCAT connector with power transmission	EPP9001-0060	<u>i</u>	
	<b>EtherCAT P Box</b> 4 x diagnostics ( $U_s$ , $U_r$ , $I_s$ , $I_r$ )	EPP9022-0060	<u>i</u>	

# EtherCAT Plug-in Modules

► [www.beckhoff.com/EtherCAT-Plug-in-Modules](http://www.beckhoff.com/EtherCAT-Plug-in-Modules)



## EtherCAT Couplers

EtherCAT Couplers E-bus	EJ1100	EJ1101-0022
		external: connectors, power supply module and optional ID switches

## EtherCAT Plug-in Modules | Digital input 24 V DC: EJ1xxx

Signal	4-channel	8-channel	16-channel
Filter 10 $\mu$ s			EJ1819 type 3
Filter 3.0 ms		EJ1008 type 3	EJ1809 type 3
		EJ1859 type 3, 8 inputs, 8 outputs	EJ1889 negative switching
Safe input	EJ1914 TwinSAFE, 4 safe inputs <i>i</i>	EJ1918 TwinSAFE, 8 safe inputs <i>i</i>	
		EJ1957 TwinSAFE, 8 safe inputs, 4 safe outputs <i>i</i>	

## EtherCAT Plug-in Modules | Digital input: EJ1xxx

Signal	8-channel
5 V DC	EJ1128 <i>i</i>

## EtherCAT Plug-in Modules | Digital output 24 V DC: EJ2xxx

Signal	1-channel	2-channel	4-channel	8-channel	16-channel
$I_{max} = 0.5$ A				EJ2008	EJ2809
				EJ1859 type 3, 8 inputs, 8 outputs	EJ2889 negative switching
Safe output			EJ2914 TwinSAFE, 4 safe outputs <i>i</i>	EJ2918 TwinSAFE, 8 safe outputs <i>i</i>	
			EJ1957 TwinSAFE, 8 safe inputs, 4 safe outputs <i>i</i>		
PWM	EJ2521-0224 24 V DC, 1 A <i>i</i>	EJ2502 24 V DC, 0.5 A			

## EtherCAT Plug-in Modules | Analog input: EJ3xxx

Signal	2-channel	4-channel	8-channel
$\pm 10$ V		EJ3004 single-ended, 12 bit	
		EJ3104 differential input, 16 bit	EJ3108 6 x differential inputs, 2 x single-ended, 16 bit
0...20 mA			EJ3048 single-ended, 12 bit
4...20 mA			EJ3058 single-ended, 12 bit <i>i</i>
Thermocouple			EJ3318 type J, K, L...U, 16 bit
Resistance thermometer (RTD)	EJ3202 16 bit	EJ3214 16 bit	

EN 61131-2 specification ► [www.beckhoff.com/EN61131-2](http://www.beckhoff.com/EN61131-2)

*i* Product announcement for availability status see [www.beckhoff.com](http://www.beckhoff.com)



### EtherCAT Plug-in Modules | Analog output: EJ4xxx

Signal	2-channel	4-channel	8-channel
0...10 V	EJ4002 12 bit		
±10 V	EJ4132 16 bit	EJ4134 16 bit	
0...20 mA			EJ4018 12 bit

### EtherCAT Plug-in Modules | Position measurement: EJ5xxx

Signal	1-channel	2-channel
Absolute encoder		EJ5002 SSI encoder interface
Incremental encoder	EJ5101 incremental encoder interface RS422	

### EtherCAT Plug-in Modules | Communication: EJ6xxx

Signal	1-channel	2-channel	4-channel
Master		EJ6002 serial interface RS232, RS485 or RS422	<i>i</i> EJ6224 IO-Link
Safety	EJ6910 TwinSAFE Logic	<i>i</i>	

### EtherCAT Plug-in Modules | Motion: EJ7xxx

	< 3 A	3...5 A
Servomotor		EJ7211-0010 $I_{ms} = 4.5 \text{ A}$ , 50 V DC, OCT EJ7211-9414 $I_{ms} = 4.5 \text{ A}$ , 50 V DC, OCT, STO, TwinSAFE SC <i>i</i>
Stepper motor	EJ7031 $I_{max} = 1.5 \text{ A}$ , 24 V DC	<i>i</i> EJ7047 $I_{max} = 5.0 \text{ A}$ , 50 V DC, incremental encoder, vector control
DC motor output stage		EJ7342 $I_{max} = 3.5 \text{ A}$ , 50 V DC, incremental encoder

### EtherCAT Plug-in Modules | System: EJ9xxx

Signal	Power supply and accessories	
Power supply	EJ9400 input 24 V DC, E-bus power supply, 2.5 A	EJ9404 input 24 V DC, E-bus power supply, 12 A
	EJ9505 input 24 V DC, output 5 V DC, 0.5 A	<i>i</i>
Filtering and smoothing	EJ9576 brake chopper module, up to 72 V DC, 155 $\mu\text{F}$	
	System	
System	EJ9001 placeholder module	

# System overview fieldbus I/O



Bus Coupler series BK, the link between Bus Terminals and fieldbus



Bus Terminal Controller series BC with integrated IEC 61131-3 PLC



Bus Terminal Controller series BX with integrated IEC 61131-3 PLC and extended interfaces



Embedded PC series CX, further Embedded PCs see page 20

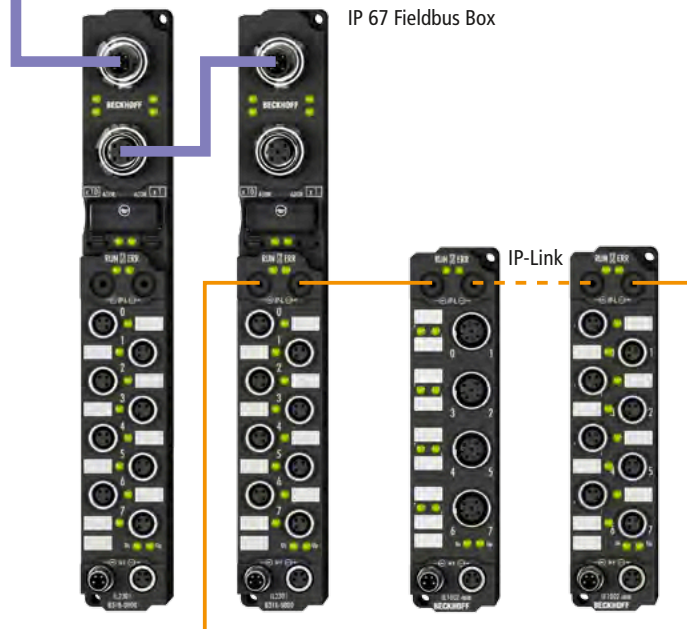
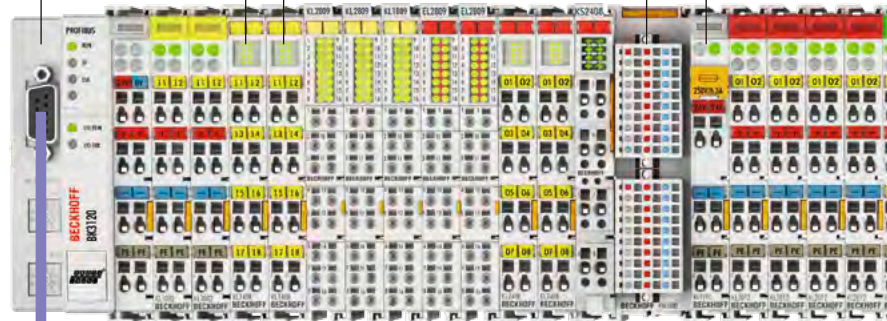
The head station of the Bus Terminals: from Bus Coupler with fieldbus interface to Embedded PC

Free mix of signals: about 400 different Bus Terminals for connection to all common sensors and actuators

Potential feed terminals enable configuration of different potential groups.

Bus Terminals in 1-, 2-, 4-, 8- and 16-channel modularity

The terminal modules with plug-in wiring combine 16, 32 or 64 digital I/Os within a very small space and with high packing density.



IP 67 Fieldbus Box

IP-Link

Compact Box

Coupler Box/  
PLC Box

Extension Box modules

3-phase power measurement capability enables all relevant electrical data of the supply network to be measured.

Communication terminals enable the integration of subsystems such as AS-Interface, RS232 and RS485.

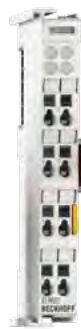
Integrated safety: the TwinSAFE Bus Terminals enable the connection of all common safety sensors and actuators.

Bus Terminals with a maximum measurement error of  $\pm 0.01\%$

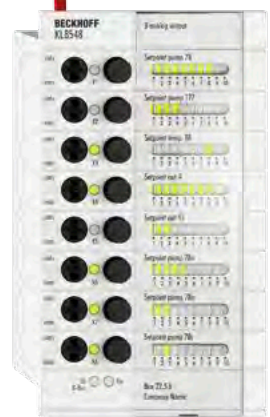
IO-Link box modules



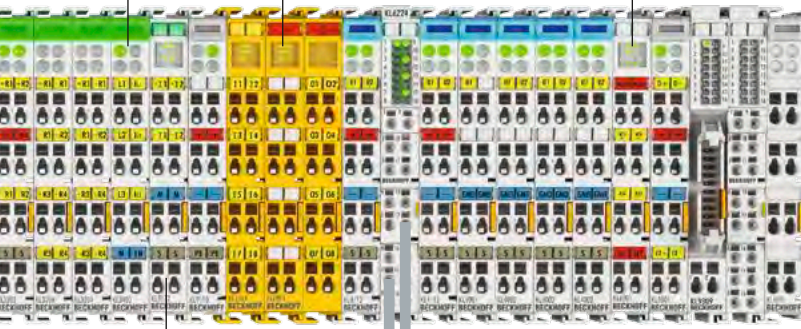
Bus end terminal



The terminal bus extension enables the connection of up to 255 Bus Terminals (instead of 64) to a single station.



Manual operating modules enable switching, controlling and monitoring of digital and analog signals as well as setting and reading of data and values in the event of a controller failure. Process data connection via K-bus interface with K-bus extension (up to 31 modules). Signal connection via KL9309.



# Bus Terminal

► [www.beckhoff.com/BusTerminal](http://www.beckhoff.com/BusTerminal)



Bus Coupler						PLC		
Fieldbus slave	Standard	Economy	Economy plus	Compact	Low Cost	Controller (IEC 61131-3)		
		only digital I/Os			only digital I/Os	Program memory 32/96 kbyte	Program memory 48 kbyte	Program memory 128 kbyte
<b>EtherCAT</b>			BK1120	BK1150 BK1250				
<b>LIGHTBUS</b>	BK2000	BK2010	BK2020					
<b>PROFIBUS</b>		BK3010 1.5 Mbaud						
	BK3100 12 Mbaud	BK3110 12 Mbaud	BK3120 12 Mbaud	BK3150 12 Mbaud	LC3100 12 Mbaud	BC3100 12 Mbaud	BC3150 12 Mbaud	
			BK3520 12 Mbaud, fibre optic					
<b>INTERBUS</b>	BK4000		BK4020					
<b>CANopen</b>		BK5110	BK5120	BK5150 BK5151	LC5100		BC5150	
<b>DeviceNet</b>	BK5200	BK5210	BK5220	BK5250	LC5200		BC5250	
<b>ControlNet</b>	BK7000							
<b>CC-Link</b>				BK7150				
<b>Modbus</b>	BK7300			BK7350		BC7300	BC8050 BC8150	
<b>sercos</b> the automation bus			BK7520					
<b>RS485</b>	BK8000						BC8050	
<b>RS232</b>	BK8100						BC8150	
<b>Ethernet TCP/IP</b>	BK9000			BK9050		BC9000	BC9050	BC9020
	BK9100 2-channel switch					BC9100 2-channel switch	BC9191 Room Controller	BC9191-0100 Room Controller
								BC9120 2-channel switch
<b>PROFINET</b>	BK9103 2-channel switch			BK9053				
<b>EtherNet/IP</b>	BK9105 2-channel switch			BK9055				





		Embedded PC							
Program memory 256 kbyte	CX80xx	CX900x, CX9010	CX9020	CX1010	CX50xx	CX51xx	CX1020, CX1030	CX20xx	
	<b>CX8010</b>		optional <sup>(2)</sup>		optional <sup>(2)</sup>	optional <sup>(2)</sup>		optional <sup>(2)</sup>	
				optional <sup>(1)</sup>			optional <sup>(1)</sup>		
	<b>CX8030</b> master		optional <sup>(2)</sup>	optional <sup>(1)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(1)</sup>	optional <sup>(2)</sup>	
<b>BX3100</b> 12 Mbaud	<b>CX8031</b> slave		optional <sup>(2)</sup>	optional <sup>(1)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(1)</sup>	optional <sup>(2)</sup>	
<b>BX5100</b>	<b>CX8050</b> master		optional <sup>(2)</sup>	optional <sup>(1)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(1)</sup>	optional <sup>(2)</sup>	
	<b>CX8051</b> slave		optional <sup>(2)</sup>	optional <sup>(1)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(1)</sup>	optional <sup>(2)</sup>	
<b>BX5200</b>									
		optional <sup>(3)</sup>	optional <sup>(3)</sup>	optional <sup>(3)</sup>	optional <sup>(3)</sup>	optional <sup>(3)</sup>	optional <sup>(3)</sup>	optional <sup>(3)</sup>	
<b>BX8000</b>	<b>CX8080</b>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	
<b>BX8000</b>	<b>CX8080</b>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	optional <sup>(2)</sup>	
<b>BX9000</b>	<b>CX8090</b>	<b>CX9000</b>	<b>CX9020</b>	<b>CX1010</b>	<b>CX5010</b>	<b>CX5120</b>	<b>CX1020</b>	<b>CX2020</b>	
	<b>CX8190</b>	<b>CX9010</b>			<b>CX5020</b>	<b>CX5130</b>	<b>CX1030</b>	<b>CX2030</b>	
						<b>CX5140</b>		<b>CX2040</b>	
								<b>CX2042</b>	
								<b>CX2062</b>	
								<b>CX2072</b>	
	<b>CX8093</b>	optional <sup>(3)</sup>	optional <sup>(2)</sup>	optional <sup>(3)</sup>	optional <sup>(2,3)</sup>	optional <sup>(2,3)</sup>	optional <sup>(3)</sup>	optional <sup>(2,3)</sup>	
	<b>CX8095</b>	optional <sup>(3)</sup>	optional <sup>(2)</sup>	optional <sup>(3)</sup>	optional <sup>(2,3)</sup>	optional <sup>(2,3)</sup>	optional <sup>(3)</sup>	optional <sup>(2,3)</sup>	

<sup>(1)</sup>via modular fieldbus interface, <sup>(2)</sup>via hardware, <sup>(3)</sup>via software library

Bus Terminal   Digital input: KL1xxx/KS1xxx						KM1xxx	
Signal	2-channel	4-channel	8-channel	16-channel	4-/16-/32-/64-ch.		
5 V DC		KL1124					
24 V DC (filter 3.0 ms)	KL1002 type 3		KL1104 type 3	KL1304 type 2	KL1408 type 3	KL1809 type 3	
	KL1302 type 2	KL1402 type 3	KL1154 positive/negative switching	KL1184 negative switching	KL1488 negative switching	KL1862 flat-ribbon cable, type 3	KM1002 16-channel, type 1
	KL1052 positive/negative switching	KL1352 NAMUR	KL1404 4 x 2-wire connection, type 3	KL1804 8 x 24 V, 4 x 0 V, type 3	KL1808 8 x 24 V DC, type 3	KL1889 negative switching	KM1004 32-channel, type 1
	KL1212 short-circuit-protected sensor supply, type 1	KL1362 break-in alarm			KL1859 8 inputs, 8 outputs, type 3, I <sub>max</sub> = 0.5 A	KL1862-0010 flat-ribbon cable, type 3, negative switching	KM1008 64-channel, type 1
24 V DC (filter 0.2 ms)	KL1012 type 3	KL1312 type 2	KL1114 type 3	KL1314 type 2	KL1418 type 3	KL1819 type 3	
		KL1412 type 3	KL1164 positive/negative switching	KL1194 negative switching	KL1498 negative switching	KL1872 flat-ribbon cable, type 3	KM1012 16-channel, type 1
			KL1414 4 x 2-wire connection, type 3	KL1434 4 x 2-wire connection, type 2			KM1014 32-channel, type 1
			KL1814 8 x 24 V, 4 x 0 V, type 3				KM1018 64-channel, type 1
24 V DC	KL1232 pulse expansion	KL1382 thermistor	KL1904 TwinSAFE, 4 safe inputs			KM1644 manual operation, 4-channel	
≥ 48 V DC	KL1032 filter 3.0 ms	KL1712-0060					
120 V AC/DC	KL1712						
230 V AC	KL1702	KL1722 no power contacts	KL1704				
Counter (24 V DC)	KL1501 up/down, 100 kHz	KL1512 up/down, 1 kHz, 16 bit					

Bus Terminal   Digital output: KL2xxx/KS2xxx						KM2xxx
Signal	2-channel	4-channel	8-channel	16-channel	2-/4-/16-/32-/64-channel	
5 V DC		KL2124				
24 V DC (I <sub>max</sub> = 0.5 A)	KL2012		KL2114	KL2408	KL2809	
					KL2819 with diagnostics	KM2002 16-channel
	KL2032 reverse voltage protection	KL2184 negative switching	KL2488 negative switching	KL2889 negative switching	KL2872 flat-ribbon cable	KM2004 32-channel
		KL2134 reverse voltage protection	KL2808 8 x 0 V	KL2872 flat-ribbon cable		KM2008 64-channel
	KL2212 diagnostics, protected sensor supply	KL2404 4 x 2-wire	KL1859 8 inputs, 8 outputs, filter 3.0 ms, type 3	KL2872-0010 flat-ribbon cable, negative switching		KM2042 16-channel, D-sub connection

The standard Bus Terminals (KLxxxx) can be optionally ordered as KSxxxx with pluggable wiring level. EN 61131-2 specification ► [www.beckhoff.com/EN61131-2](http://www.beckhoff.com/EN61131-2)

Bus Terminal   Digital output: KL2xxx/KS2xxx					KM2xxx
Signal	1-channel	2-channel	4-channel	8-channel	2-/4-/16-/32-/64-ch.
24 V DC ( $I_{max} = 2.0 \text{ A}$ )		KL2022	KL2424 4 x 2-wire	KL2828 8 x 2-wire	
30 V AC/DC ( $I_{max} = 2.0 \text{ A}$ ), solid state relay			KL2784		
			KL2794 potential-free	KL2798 potential-free	
24 V DC		KL2442 2 x 4 A/1 x 8 A	KL2904 TwinSAFE, 4 safe outputs		
Relay 125/400 V AC	KL2631 400 V AC, make contact	KL2612 125 V AC, change-over			
230 V AC	KL2641 relay, make contact, manual operation, $I_{max} = 16 \text{ A}$	KL2602 relay, make contact, $I_{max} = 5 \text{ A}$	KL2622 relay, make contact, no power contacts, $I_{max} = 5 \text{ A}$		KM2604 relay, $I_{max} = 16 \text{ A}$ , 4-channel
	KL2751 universal dimmer, 300 W	KL2602-0010 relay, make contact, $I_{max} = 5 \text{ A}$ , contact- protecting switching	KL2622-0010 relay, make contact, no power contacts, $I_{max} = 5 \text{ A}$ , contact-protecting switching		KM2614 relay, $I_{max} = 16 \text{ A}$ , 4-channel, manual operation
	KL2761 universal dimmer, 600 W	KL2652 relay, change-over, $I_{max} = 5 \text{ A}$	KL2702 solid state relay, $I_{max} = 0.3 \text{ A}$		KM2774 triac outputs, $I_{max} = 1.5 \text{ A}$
	KL2701 solid state relay, $I_{max} = 3 \text{ A}$	KL2712 triac	KL2722 triac, mutually locked outputs		KM2642 relay, $I_{max} = 6 \text{ A}$ , manual/automatic operation, relay state readable
		KL2732 triac, mutually locked outputs, no power contacts	KL2692 cycle monitoring (watchdog)		KM2652 relay, $I_{max} = 6 \text{ A}$ , manual/automatic operation, switch and relay state readable
PWM		KL2502 24 V DC, $I_{max} = 0.1 \text{ A}$	KL2512 24 V DC, $I_{max} = 1 \text{ A}$ , negative switching		
		KL2535 $I_{max} = \pm 1 \text{ A}$ , 24 V DC, current-controlled	KL2545 $I_{max} = \pm 3.5 \text{ A}$ , 50 V DC, current-controlled		
Frequency output	KL2521				

Bus Terminal   Motion: KL2xxx/KS2xxx	
	< 3 A
Stepper motor	KL2531 $I_{max} = 1.5 \text{ A}$ , 24 V DC
	3...5 A
DC motor output stage	KL2532 $I_{max} = 1.0 \text{ A}$ , 24 V DC
	KL2552 $I_{max} = 5.0 \text{ A}$ , 50 V DC, incremental encoder
	KL2284 reverse switching, $I_{max} = 2.0 \text{ A}$ , 0...24 V DC
AC motor speed controller	KL2791 230 V AC, 200 VA, 1-phase AC motor

Bus Terminal   Analog input: KL3xxx/KS3xxx, KM3xxx					
Signal	1-channel	2-channel	4-channel	8-channel	
0...2 V, 0...500 mV		KL3172 0...2 V, 16 bit, 0.05 %	KL3172-0500 0...500 mV, 16 bit, 0.05 %		
±2 V			KL3182 16 bit, 0.05 %		
0...10 V	KL3061 single-ended, 12 bit	KL3062 single-ended, 12 bit	KL3162 16 bit, 0.05 %	KL3064 single-ended, 12 bit	
				KL3464 single-ended, 12 bit	KL3468 single-ended, 12 bit
±10 V	KL3001 differential input, 12 bit	KL3002 differential input, 12 bit	KL3102 differential input, 16 bit	KL3404 single-ended, 12 bit	KL3408 single-ended, 12 bit
			KL3132 16 bit, 0.05 %		
0...20 mA	KL3011 differential input, 12 bit	KL3041 with sensor supply, 12 bit	KL3012 differential input, 12 bit	KL3112 differential input, 16 bit	KL3044 single-ended, 12 bit
			KL3042 with sensor supply, 12 bit	KL3142 16 bit, 0.05 %	KL3444 single-ended, 12 bit
4...20 mA	KL3021 differential input, 12 bit	KL3051 with sensor supply, 12 bit	KL3022 differential input, 12 bit	KL3122 differential input, 16 bit	KL3054 single-ended, 12 bit
			KL3052 with sensor supply, 12 bit	KL3152 16 bit, 0.05 %	KL3454 single-ended, 12 bit
Resistance thermometer (RTD)	KL3201 PT100...1000, Ni100, 16 bit		KL3202 PT100...1000, Ni100, 16 bit	KL3222 PT100, 4-wire connection, high-precision	KL3204 PT100...1000, Ni100...1000, 2-wire connection
					KL3208-0010 PT1000, Ni1000, NTC 1.8... 100 k, potentiom. 1, 5, 10 kΩ
				KL3214 PT100...1000, Ni100...1000, KTY, 3-wire connection	KL3228 PT1000, Ni1000
Thermo- couple/mV	KL3311 type J, K, L...U, 16 bit		KL3312 type J, K, L...U, 16 bit		KL3314 type J, K, L...U, 16 bit
Measurement bridge (SG)	KL3351 strain gauge, 16 bit	KL3356 strain gauge, 16 bit, self-calibration			
Oscilloscope	KL3361 ±16 mV		KL3362 ±10 V		
Measurement technology	KL3681 digital multimeter, 18 bit		KL3403 power measurement, 3-phase, 1 A	KL3403-0010 power measurement, 3-phase, 5 A	
Pressure measuring	KM3701 differential pressure, -100...+100 hPa	KM3701-0340 differential pressure, up to 340 hPa	KM3702 relative pressure, 7500 hPa	KM3712 relative pressure, -1000...+1000 hPa	

Bus Terminal   Analog output: KL4xxx/KS4xxx					KM4xxx
Signal	1-channel	2-channel	4-channel	8-channel	2-channel
0...10 V	KL4001 12 bit, potential-free output	KL4002 12 bit	KL4004 12 bit, no power contacts		KM4602 12-bit manual/automatic operation
			KL4404 12 bit	KL4408 12 bit	
±10 V	KL4031 12 bit, potential-free output	KL4032 12 bit	KL4034 12 bit, no power contacts		
		KL4132 16 bit	KL4434 12 bit	KL4438 12 bit	
			KL4494 12 bit, 2 x input, 2 x output		
0...20 mA	KL4011 12 bit	KL4012 12 bit	KL4414 12 bit	KL4418 12 bit	
		KL4112 16 bit			
4...20 mA	KL4021 12 bit	KL4022 12 bit	KL4424 12 bit	KL4428 12 bit	

The standard Bus Terminals (KLxxx) can be optionally ordered as KSxxx with pluggable wiring level.



## Bus Terminal | Special functions: KL5xxx/KS5xxx, KL6xxx/KS6xxx, KL8xxx

Signal			Signal	
<b>Position measurement</b>	<b>KL5001</b> SSI encoder interface	<b>KL5051</b> SSI encoder interface, bidirectional	<b>KL5121</b> incremental encoder interface with programmable outputs	<b>Safety</b> <b>KL6904</b> TwinSAFE Logic Bus Terminal, 4 safe outputs
	<b>KL5101</b> incremental encoder interface RS422	<b>KL5151</b> incremental encoder interface 24 V DC, 1-channel, 32 bit	<b>KL5152</b> incremental encoder interface 24 V DC, 2-channel, 32 bit	
	<b>KL5111</b> incremental encoder interface 24 V DC			
<b>Communication</b>	<b>KL6001</b> serial interface RS232, 19.2 kbaud	<b>KL6031</b> serial interface RS232, 115.2 kbaud	<b>KL6011</b> serial interface TTY, 20 mA current loop	<b>Manual operation</b> <b>KL8519</b> 16-channel digital input signal module <b>KL8524</b> 4 x 2-channel digital output, 24 V DC, 0.5 A <b>KL8528</b> 8-channel digital output, 24 V DC, 0.5 A <b>KL8548</b> 8-channel analog output, 0...10 V
	<b>KL6051</b> data exchange terminal, 32 bit	<b>KL6021</b> serial interface RS422/RS485, 19.2 kbaud	<b>KL6041</b> serial interface RS422/RS485, 115.2 kbaud	
	<b>KL6023</b> wireless adapter for EnOcean radio technology	<b>KL6021-0023</b> RS485 interface for EnOcean signals	<b>KL6201</b> AS-Interface master terminal	
	<b>KL6211</b> AS-Interface master terminal with power contacts	<b>KL6224</b> IO-Link master	<b>KL6301</b> EIB/KNX Bus Terminal	
	<b>KL6401</b> LON Bus Terminal	<b>KL6581</b> EnOcean master	<b>KL6583</b> EnOcean transmitter/receiver	
	<b>KL6771</b> MP-Bus master terminal	<b>KL6781</b> M-Bus master terminal	<b>KL6811</b> DALI/DSI master and power supply terminal	
	<b>KL6821</b> DALI 2 multi-master and power supply terminal	<b>KL6831</b> SMI terminal, LoVo	<b>KL6841</b> SMI terminal, 230 V AC	

## Bus Terminal | System terminals: KL9xxx/KS9xxx

Signal	System	Signal	Potential supply	Power supply and accessories
<b>System</b>	<b>KL9010</b> bus end terminal	<b>KL9070</b> shield terminal	<b>24 V DC</b>	<b>KL9100</b>
	<b>KL9020</b> terminal bus extension end terminal	<b>KL9050</b> terminal bus extension coupler terminal		<b>KL9110</b> diagnostics
	<b>KL9060</b> adapter terminal for power terminal KL8xxx	<b>KL9309</b> adapter terminal for KL85xx manual operating modules		<b>KL9200</b> with fuse
	<b>KL9080</b> isolation terminal	<b>KL9195</b> shield terminal		<b>KL9210</b> diagnostics, with fuse
<b>Potential distribution terminal</b>	<b>KL9180</b> 2 terminal points per power contact	<b>KL9181</b> 2 x 8 terminal points	<b>50 V DC</b>	<b>KL9400</b> K-bus power supply, 2 A
	<b>KL9182</b> 8 x 2 terminal points	<b>KL9183</b> 1 x 16 terminal points		<b>KL9505</b> output 5 V DC, 0.5 A
	<b>KL9184</b> 8 x 24 V DC, 8 x 0 V DC	<b>KL9185</b> only 2 power contacts		<b>KL9508</b> output 8 V DC, 0.5 A
	<b>KL9186</b> 8 x 24 V DC	<b>KL9187</b> 8 x 0 V DC		<b>KL9510</b> output 10 V DC, 0.5 A
	<b>KL9188</b> 16 x 24 V DC	<b>KL9189</b> 16 x 0 V DC		<b>KL9512</b> output 12 V DC, 0.5 A
	<b>KL9380</b> mains filter, approx. 1 µF			<b>KL9515</b> output 15 V DC, 0.5 A
<b>Filter</b>	<b>KL9540</b> surge filter terminal for field supply		<b>120... 230 V AC</b>	<b>KL9520</b> AS-Interface potential supply
	<b>KL9540-0010</b> surge filter field supply for analog terminals	<b>KL9550</b> surge filter terminal for system/field supply		<b>KL9528</b> AS-Interface power supply terminal
<b>Diode array</b>	<b>KL9300</b> 4 diodes, potential-free		<b>Up to 400 V AC</b>	<b>KL9560</b> output 24 V DC, 0.1 A
	<b>KL9301</b> 7 diodes, common cathode	<b>KL9302</b> 7 diodes, common anode		<b>KL9150</b> diagnostics
			<b>KL9160</b> diagnostics	<b>KL9570</b> buffer capacitor terminal, 500 µF
			<b>KL9250</b> with fuse	
			<b>KL9260</b> diagnostics, with fuse	
			<b>KL9190</b>	
			<b>KL9290</b> with fuse	

# Fieldbus Box

► [www.beckhoff.com/FieldbusBox](http://www.beckhoff.com/FieldbusBox)



Fieldbus Box	Compact Box		Coupler Box		PLC Box	
<b>Fieldbus</b>	Fieldbus Box without IP-Link interface		Fieldbus Box with IP-Link interface		Controller IEC 61131-3 with IP-Link interface	
<b>EtherCAT</b>			IL230x-B110			
<b>LIGHTBUS</b>	IPxxxx-B200		IL230x-B200			
<b>PROFINET</b>	IPxxxx-B310	IPxxxx-B318 with integrated tee-connector	IL230x-B310	IL230x-B318 with integrated tee-connector	IL230x-C310	IL230x-C318 with integrated tee-connector
<b>INTERBUS</b>	IPxxxx-B400		IL230x-B400			
<b>CANopen</b>	IPxxxx-B510	IPxxxx-B518 with integrated tee-connector	IL230x-B510	IL230x-B518 with integrated tee-connector		
<b>DeviceNet</b>	IPxxxx-B520	IPxxxx-B528 with integrated tee-connector	IL230x-B520	IL230x-B528 with integrated tee-connector		
<b>Modbus</b>	IPxxxx-B730		IL230x-B730			
<b>RS485</b>	IPxxxx-B800		IL230x-B800			
<b>RS232</b>	IPxxxx-B810		IL230x-B810		IL230x-C810	
<b>Ethernet TCP/IP</b>			IL230x-B900		IL230x-B901	
<b>PROFINET</b>			IL230x-B903			
<b>EtherNet/IP</b>			IL230x-B905			

## Fieldbus Box | Compact Box and Extension Box: Digital I/O

Input		8 mm	M8	M12
24 V DC	8-channel filter 3.0 ms	IP1000-Bxxx, IE1000	IP1001-Bxxx, IE1001	IP1002-Bxxx, IE1002
	8-channel filter 0.2 ms	IP1010-Bxxx, IE1010	IP1011-Bxxx, IE1011	IP1012-Bxxx, IE1012
Counter	2-channel up/down counter 24 V DC, 100 kHz			IP1502-Bxxx, IE1502
Output		8 mm	M8	M12
24 V DC	8-channel $I_{max} = 0.5 A$	IP2000-Bxxx, IE2000	IP2001-Bxxx, IE2001	IP2002-Bxxx, IE2002
	8-channel $I_{max} = 2 A, \Sigma 4 A$	IP2020-Bxxx, IE2020	IP2021-Bxxx, IE2021	IP2022-Bxxx, IE2022
	8-channel $I_{max} = 2 A, \Sigma 12 A$	IP2040-Bxxx, IE2040	IP2041-Bxxx, IE2041	IP2042-Bxxx, IE2042
	16-channel $I_{max} = 0.5 A, \Sigma 4 A, D\text{-sub}$			IE2808 IE2808-0001
PWM	2-channel PWM, 24 V DC, $I_{max} = 2.5 A$			IP2512-Bxxx, IE2512

## Fieldbus Box | Compact Box, Coupler Box, PLC Box and Extension Box: Digital I/O

Combi		8 mm	M8	M12	Other
24 V DC	<b>8-channel</b> 4 inputs + 4 outputs, filter 3.0 ms, $I_{max} = 0.5$ A	IL2300-Bxxx IL2300-Cxxx IP2300-Bxxx IE2300	IL2301-Bxxx IL2301-Cxxx IP2301-Bxxx IE2301	IL2302-Bxxx IL2302-Cxxx IP2302-Bxxx IE2302	
	<b>8-channel</b> 4 inputs + 4 outputs, filter 0.2 ms, $I_{max} = 0.5$ A	IP2310-Bxxx IE2310	IP2311-Bxxx IE2311	IP2312-Bxxx IE2312	
	<b>8-channel</b> 4 inputs + 4 outputs, filter 3.0 ms, $I_{max} = 2$ A, $\Sigma$ 4 A	IP2320-Bxxx IE2320	IP2321-Bxxx IE2321	IP2322-Bxxx IE2322	
	<b>8-channel</b> 4 inputs + 4 outputs, filter 0.2 ms, $I_{max} = 2$ A, $\Sigma$ 4 A	IP2330-Bxxx IE2330	IP2331-Bxxx IE2331	IP2332-Bxxx IE2332	
	<b>16-channel</b> combi inputs/outputs, filter 3.0 ms, $I_{max} = 0.5$ A	IP2400-Bxxx IE2400	IP2401-Bxxx IE2401		IE2403 IP 20 plug

## Fieldbus Box | Compact Box and Extension Box: Analog I/O

Input		M12
$\pm 10$ V	<b>4-channel</b> differential inputs, 16 bit	IP3102-Bxxx, IE3102
0/4...20 mA	<b>4-channel</b> differential inputs, 16 bit	IP3112-Bxxx, IE3112
Resistance thermometer	<b>4-channel</b> PT100, PT200, PT500, PT1000, Ni100, 16 bit	IP3202-Bxxx, IE3202
Thermocouple/mV	<b>4-channel</b> type J, K, L, B, E, N, R, S, T, U, 16 bit	IP3312-Bxxx, IE3312
Output		M12
$\pm 10$ V	<b>4-channel</b> 16 bit	IP4132-Bxxx, IE4132
0/4...20 mA	<b>4-channel</b> 16 bit	IP4112-Bxxx, IE4112

## Fieldbus Box | Compact Box and Extension Box: Special functions

Function		M12	M23
Position measurement	<b>1-channel</b> SSI encoder interface		IP5009-Bxxx, IE5009
	<b>1-channel</b> incremental encoder interface, 1 MHz		IP5109-Bxxx, IE5109
	<b>1-channel</b> SinCos encoder interface		IP5209-Bxxx (1 V <sub>pp</sub> ) IP5209-Bxxx-1000 (11 $\mu$ A <sub>pp</sub> )
Communication	<b>1-channel</b> serial interface, RS232	IP6002-Bxxx, IE6002	
	<b>1-channel</b> serial interface, 0...20 mA (TTY)	IP6012-Bxxx, IE6012	
	<b>1-channel</b> serial interface, RS422/RS485	IP6022-Bxxx, IE6022	



Fieldbus Box   IO-Link box: Digital I/O					
Input		8 x M8	16 x M8	4 x M12	8 x M12
24 V DC	8-channel filter 3.0 ms	EPI1008-0001 ERI1008-0001		EPI1008-0002 ERI1008-0002	
	16-channel filter 3.0 ms		EPI1809-0021 ERI1809-0021		EPI1809-0022 ERI1809-0022
Output		8 x M8	16 x M8	4 x M12	8 x M12
24 V DC	8-channel $I_{max} = 0.5 A$	EPI2008-0001 ERI2008-0001		EPI2008-0002 ERI2008-0002	
	16-channel $I_{max} = 0.5 A, \Sigma 4 A$		EPI2809-0021 ERI2809-0021		EPI2809-0022 ERI2809-0022
Combi		8 x M8	16 x M8	4 x M12	8 x M12
24 V DC	8-channel 8 inputs/outputs, filter 3.0 ms, $I_{max} = 0.5 A$	EPI2338-0001 ERI2338-0001		EPI2338-0002 ERI2338-0002	
	16-channel 16 inputs/outputs, filter 3.0 ms, $I_{max} = 0.5 A, \Sigma 4 A$		EPI2339-0021 ERI2339-0021		EPI2339-0022 ERI2339-0022

Fieldbus Box   IO-Link box: Analog I/O		
Input		M12
$\pm 10 V$ , 0/4...20 mA	4-channel parameterisable, differential input, 16 bit	EPI3174-0002 ERI3174-0002
Output		M12
$\pm 10 V$ , 0/4...20 mA	4-channel 2 inputs + 2 outputs, parameterisable, 16 bit	EPI4374-0002 ERI4374-0002

EPIxxxx: industrial housing in IP 67, ERIxxxx: zinc die-cast housing in IP 67

# Infrastructure Components

► [www.beckhoff.com/Infrastructure-components](http://www.beckhoff.com/Infrastructure-components)



Infrastructure Components	
<b>Ethernet</b>	<b>EtherCAT</b>
<b>Ethernet Switches</b>	<b>EtherCAT junctions</b>
<b>CU2005</b> 5 ports, 10/100 Mbit/s, IP 20	<b>CU1123</b> ⓘ 3-port, RJ45, IP 20
<b>CU2008</b> 8 ports, 10/100 Mbit/s, IP 20	<b>CU1124</b> ⓘ 4-port, RJ45, IP 20
<b>CU2016</b> 16 ports, 10/100 Mbit/s, IP 20	<b>CU1128</b> 8-channel, RJ45, IP 20
<b>CU2208</b> 8 Gbit ports, 10/100/1000 Mbit/s, IP 20	<b>EP9128</b> 8-channel, M8, IP 67
<b>CU2608</b> 8 ports, M12, D-coded, 10/100 Mbit/s, IP 67	<b>EtherCAT media converters fibre optic</b>
<b>CU2508</b> real-time Ethernet port multiplier, 10/100/1000 Mbit/s, IP 20	<b>CU1521-0000</b> multimode, IP 20
	<b>CU1521-0010</b> singlemode, IP 20
	<b>CU1561</b> POF, IP 20
	<b>EP9521</b> multimode, IP 67

PC Fieldbus Cards			
Fieldbus	PCI	Mini-PCI	PCIe
<b>EtherCAT</b> ⓘ	<b>FC1100</b> 1-channel, slave		<b>FC1121</b> 1-channel, slave
<b>LIGHTBUS</b>	<b>FC2001-0000</b> 1-channel		
	<b>FC2002-0000</b> 2-channel		
<b>PROFIBUS</b>	<b>FC3101-0000</b> 1-channel	<b>FC3151-0000</b> 1-channel	<b>FC3121</b> 1-channel
	<b>FC3101-0002</b> 1-channel, 32 kbytes NOVRAM	<b>FC3151-0002</b> 1-channel, 128 kbytes NOVRAM	
	<b>FC3102-0000</b> 2-channel		<b>FC3122</b> 2-channel
	<b>FC3102-0002</b> 2-channel, 32 kbytes NOVRAM		
<b>CANopen</b>	<b>FC5101-0000</b> 1-channel	<b>FC5151-0000</b> 1-channel	<b>FC5121</b> 1-channel
	<b>FC5101-0002</b> 1-channel, 32 kbytes NOVRAM	<b>FC5151-0002</b> 1-channel, 128 kbytes NOVRAM	
	<b>FC5102-0000</b> 2-channel		<b>FC5122</b> 2-channel
	<b>FC5102-0002</b> 2-channel, 32 kbytes NOVRAM		
<b>DeviceNet</b>	<b>FC5201-0000</b> 1-channel	<b>FC5251-0000</b> 1-channel	
	<b>FC5201-0002</b> 1-channel, 32 kbytes NOVRAM	<b>FC5251-0002</b> 1-channel, 128 kbytes NOVRAM	
	<b>FC5202-0000</b> 2-channel		
	<b>FC5202-0002</b> 2-channel, 32 kbytes NOVRAM		
<b>sercos</b> the automation bus	<b>FC7501-0000</b> 1-channel	<b>FC7551-0000</b> 1-channel	
	<b>FC7502-0000</b> 2-channel	<b>FC7551-0002</b> 1-channel, 128 kbytes NOVRAM	
<b>Ethernet</b>	<b>FC9001-0010</b> 1-channel, 10/100 Mbit/s	<b>FC9051-0000</b> 1-channel, 10/100 Mbit/s	
	<b>FC9011-0000</b> 1-channel, 10/100/1000 Mbit/s	<b>FC9151-0000</b> 1-channel, 10/100/1000 Mbit/s	
	<b>FC9002-0000</b> 2-channel, 10/100 Mbit/s		<b>FC9022-0000</b> 2-channel, 10/100/1000 Mbit/s
	<b>FC9004-0000</b> 4-channel, 10/100 Mbit/s		<b>FC9024-0000</b> 4-channel, 10/100/1000 Mbit/s
<b>PROFINET</b>			<b>FC9321-0010</b> 1-channel, IRT device
			<b>FC9361-0010</b> 1-channel, IRT device, compact

# The Motion Company



**AX8000 multi-axis  
EtherCAT drive**

## Servo Drives 64

- Available as multi-axis system or stand-alone version (1-/2-channel)
- High-speed EtherCAT communication
- Wide range of nominal current types, up to 170 A
- Flexible motor type selection
- Optimised for multi-axis applications

► [www.beckhoff.com/Servo-Drives](http://www.beckhoff.com/Servo-Drives)

## Distributed Servo Drive system 66

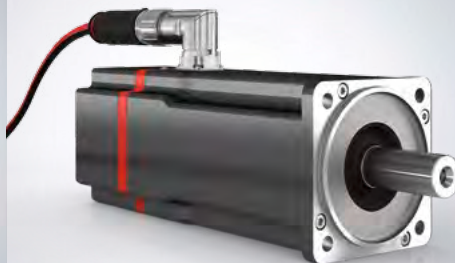
- Servo drives directly integrated into the motor
- STO/SS1 safety function as standard; optionally Safe Motion
- Advanced power electronics ensure minimal derating
- No changes in machine design required

► [www.beckhoff.com/AMP8000](http://www.beckhoff.com/AMP8000)

## Synchronous Servomotors 67

- For demanding positioning tasks
- Highly dynamic behaviour
- Brushless three-phase motors
- Permanent magnet in the rotor

► [www.beckhoff.com/Servomotors](http://www.beckhoff.com/Servomotors)



In combination with the motion control solutions offered by the company's TwinCAT automation software, Beckhoff Drive Technology provides an advanced, all-inclusive drive system. PC-based control technology from Beckhoff is ideally suited for single- and multi-axis positioning tasks with high dynamic requirements.

The AX5000 and AX8000 Servo Drive series with high-performance EtherCAT communication offer the best-possible performance and dynamics. Servomotors with One Cable Technology (OCT), combining power and feedback systems into one standard motor cable, reduce material and commissioning costs.

► [www.beckhoff.com/DriveTechnology](http://www.beckhoff.com/DriveTechnology)

#### Compact Drive Technology 70

- Solutions for up to 8 A in the space-saving I/O system
- Simple connection of stepper, servo, DC or AC motors
- IP 20 or IP 67 connection options
- Matching motors and gearboxes

► [www.beckhoff.com/compact-drive-technology](http://www.beckhoff.com/compact-drive-technology)

#### eXtended Transport System XTS 72

- Linear motor on an endless path
- Replaces traditional mechanics with advanced mechatronic solutions
- Software-based functional changes
- Individual product transport with continuous material flow

► [www.beckhoff.com/XTS](http://www.beckhoff.com/XTS)



- Scalable product range of servo drive technology
- Integrated safety technology in compliance with safety performance level PL e, integrated into Compact Drive Technology up to safety performance level PL d
- As the pioneer of One Cable Technology and the eXtended Transport System, Beckhoff specialises in manufacturing efficient, space-saving motion solutions.

# Servo Drives

► [www.beckhoff.com/Servo-Drives](http://www.beckhoff.com/Servo-Drives)



AX8000

## AX8000 | Multi-axis servo system: power supply modules

	AX8620-0000	AX8620-1000	AX8640-0000
<b>Rated output current</b>	20 A DC	20 A DC	40 A DC
<b>Supply voltage</b>	3 x 200...480 V AC	1 x 100...240 V AC	3 x 400...480 V AC

Any number of axis modules can be added provided that the rated output current of the power supply modules is sufficient.

## AX8000 | Multi-axis servo system: axis modules

	AX8108	AX8118	AX8206
<b>Rated current</b>	1 x 8 A	1 x 18 A	2 x 6 A
<b>Number of axes</b>	1	1	2
<b>Motor feedback</b>	OCT	OCT	OCT
<b>TwinSAFE/safe drive technology</b>	AX8108-0000 without TwinSAFE	AX8118-0000 without TwinSAFE	AX8206-0000 without TwinSAFE
	AX8108-0100 STO/SS1	AX8118-0100 STO/SS1	AX8206-0100 STO/SS1
	AX8108-0200 Safe Motion	AX8118-0200 Safe Motion	AX8206-0200 Safe Motion

## AX8000 | Multi-axis servo system: option modules

	1-channel	2-channel
<b>Coupling module for AMP8000</b>	AX8831	AX8832
	for AX86xx-1000	for AX86xx-0000
<b>Capacitor module</b>	AX8810-1000	AX8810-0000





AX5000

## AX5000 | Digital Compact Servo Drives

	AX5101...AX5112	AX5201...AX5206	AX5118...AX5140	AX5160...AX5193
<b>Number of axes</b>	1	2	1	1
<b>Rated current</b>	1.5...12 A	2 x 1.5...6 A	18...40 A	60...170 A
<b>Supply voltage</b>	3 x 100...480 V AC (wide voltage range), 1 x 100...240 V AC	3 x 100...480 V AC (wide voltage range), 1 x 100...240 V AC	3 x 100...480 V AC (wide voltage range)	3 x 400...480 V AC
<b>Motor feedback</b>	OCT, multi-feedback	OCT, multi-feedback	OCT, multi-feedback	multi-feedback

## AX5000 | Digital Compact Servo Drives: options

	1-channel	2-channel		
<b>Coupling module for AMP8000</b>	AX5031	AX5032		
<b>Encoder option cards</b>	AX5701 1 V <sub>PP</sub> , BiSS B, Hiperface, EnDat	AX5721 EnDat 2.2, BiSS C	AX5702 1 V <sub>PP</sub> , BiSS B, Hiperface, EnDat	AX5722 EnDat 2.2, BiSS C
<b>TwinSAFE/safe drive technology</b>	STO/SS1 AX5801-0200 for AX5101...AX5140 and AX5201...AX5206	Safe Motion AX5805-0000 for AX5101...AX5140 and AX5201...AX5206	AX5806-0000 for AX5160...AX5193	
<b>AX-Bridge</b>	Power supply AX5901 for AX5101...AX5125 and AX5201...AX5206	AX5902 for AX5140	Power distribution AX5911 for AX5101...AX5112 and AX5201...AX5206	AX5912 for AX5118 and AX5125
<b>Brake module</b>	Brake energy recovery AX5021 connection of external brake resistors			

# Distributed Servo Drive system

► [www.beckhoff.com/AMP8000](http://www.beckhoff.com/AMP8000)



## AMP804x | Distributed Servo Drive, flange code F4

Data for 560 V DC	AMP8041-wDyz	AMP8041-wEyz	AMP8042-wEyz	AMP8043-wEyz
Standstill torque	2.01 Nm	2.01 Nm	3.48 Nm	4.80 Nm
Rated speed	3000 min <sup>-1</sup>	6000 min <sup>-1</sup>	2500 min <sup>-1</sup>	2500 min <sup>-1</sup>
Rated power	0.61 kW	1.23 kW	0.87 kW	1.18 kW
Standstill current	1.65 A	3.00 A	2.15 A	2.90 A
Connection technology	ECP B23 plug	ECP B23 plug	ECP B23 plug	ECP B23 plug
One Cable Technology (OCT)	yes	yes	yes	yes

## AMP805x | Distributed Servo Drive, flange code F5

Data for 560 V DC	AMP8051-wEyz	AMP8051-wGyz	AMP8052-wFyz	AMP8053-wGyz
Standstill torque	4.08 Nm	4.08 Nm	6.97 Nm	9.70 Nm
Rated speed	2500 min <sup>-1</sup>	5000 min <sup>-1</sup>	2000 min <sup>-1</sup>	2000 min <sup>-1</sup>
Rated power	1.02 kW	1.02 kW	1.34 kW	1.78 kW
Standstill current	2.70 A	4.75 A	3.30 A	4.70 A
Connection technology	ECP B23 plug	ECP B23 plug	ECP B23 plug	ECP B23 plug
One Cable Technology (OCT)	yes	yes	yes	yes

## AX503x, AX883x | Coupling modules for AMP8000

	AX5031	AX5032	AX8831	AX8832
Function	coupling module with feed	coupling module with feed	coupling module	coupling module
Number of channels	1	2	1	2
Rated output current DC link	20 A DC	∑ 20 A DC	20 A DC	2 x 20 A DC
Rated output current 24 V	16 A DC	∑ 20 A DC	16 A DC	∑ 20 A DC
DC-Link voltage	565...680 V DC	565...680 V DC	565...680 V DC	565...680 V DC

## AMP8805 | Distribution module for AMP8000

	AMP8805
Function	distribution module
Number of channels	1 x Power IN, 5 x Power OUT, 1 x EtherCAT P OUT
Rated input current 24 V	16 A DC
DC-Link voltage	565...680 V DC
DC-Link capacitance	1120 µF
Protection class	IP 65

# Synchronous Servomotors

► [www.beckhoff.com/Servomotors](http://www.beckhoff.com/Servomotors)



AM8000, AM8500

AM8000, AM8500 with fan

## Synchronous Servomotors, OCT

	Flange code						
	F1 40 mm	F2 58 mm	F3 72 mm	F4 87 mm	F5 104 mm	F6 142 mm	F7 197 mm
<b>Standard 400 V AC</b>		<b>AM802x</b> $M_0 = 0.50 \dots 1.20 \text{ Nm}$	<b>AM803x</b> $M_0 = 1.37 \dots 3.22 \text{ Nm}$	<b>AM804x</b> $M_0 = 2.37 \dots 5.65 \text{ Nm}$	<b>AM805x</b> $M_0 = 4.80 \dots 11.4 \text{ Nm}$ , up to 15.4 Nm with fan	<b>AM806x</b> $M_0 = 12.8 \dots 29.0 \text{ Nm}$ , up to 41.4 Nm with fan	<b>AM807x</b> $M_0 = 29.0 \dots 92.0 \text{ Nm}$ , up to 129 Nm with fan
<b>Standard 230 V AC</b>	<b>AM801x</b> $M_0 = 0.20 \dots 0.52 \text{ Nm}$						
<b>Standard 48 V DC</b>	<b>AM811x</b> $M_0 = 0.20 \dots 0.52 \text{ Nm}$	<b>AM812x</b> $M_0 = 0.50 \dots 0.80 \text{ Nm}$	<b>AM813x</b> $M_0 = 1.35 \dots 2.37 \text{ Nm}$	<b>AM8141</b> $M_0 = 2.40 \text{ Nm}$			
<b>Increased inertia 400 V AC</b>			<b>AM853x</b> $M_0 = 1.37 \dots 3.22 \text{ Nm}$	<b>AM854x</b> $M_0 = 2.37 \dots 5.65 \text{ Nm}$	<b>AM855x</b> $M_0 = 4.80 \dots 11.4 \text{ Nm}$ , up to 15.4 Nm with fan	<b>AM856x</b> $M_0 = 12.8 \dots 29.0 \text{ Nm}$ , up to 41.4 Nm with fan	
<b>Stainl. steel 400 V AC</b>			<b>AM883x*</b> $M_0 = 0.85 \dots 1.85 \text{ Nm}$	<b>AM884x*</b> $M_0 = 1.60 \dots 3.50 \text{ Nm}$	<b>AM885x*</b> $M_0 = 3.10 \dots 6.40 \text{ Nm}$	<b>AM886x*</b> $M_0 = 7.75 \dots 16.7 \text{ Nm}$	

\*Please note the different flange size.

## Synchronous Servomotors, 2-cable standard

	Flange code							
	F1 40 mm	F2 58 mm	F3 72 mm	F4 87 mm	F5 104 mm	F6 142 mm	F7 197 mm	F8 260 mm
<b>Standard 400 V AC</b>		<b>AM802x</b> $M_0 = 0.50 \dots 1.20 \text{ Nm}$	<b>AM803x</b> $M_0 = 1.37 \dots 3.22 \text{ Nm}$	<b>AM804x</b> $M_0 = 2.37 \dots 5.65 \text{ Nm}$	<b>AM805x</b> $M_0 = 4.80 \dots 11.4 \text{ Nm}$ , up to 15.4 Nm with fan	<b>AM806x</b> $M_0 = 12.8 \dots 29.0 \text{ Nm}$ , up to 41.4 Nm with fan	<b>AM807x</b> $M_0 = 29.0 \dots 92.0 \text{ Nm}$ , up to 129 Nm with fan	
		<b>AM302x</b> $M_0 = 0.87 \dots 1.41 \text{ Nm}$	<b>AM303x*</b> $M_0 = 1.15 \dots 2.79 \text{ Nm}$	<b>AM304x*</b> $M_0 = 1.95 \dots 6.00 \text{ Nm}$	<b>AM305x*</b> $M_0 = 4.70 \dots 14.9 \text{ Nm}$	<b>AM306x*</b> $M_0 = 11.9 \dots 25.0 \text{ Nm}$	<b>AM307x*</b> $M_0 = 29.7 \dots 53.0 \text{ Nm}$	<b>AM308x</b> $M_0 = 75.0 \dots 180 \text{ Nm}$
<b>Standard 230 V AC</b>	<b>AM301x</b> $M_0 = 0.18 \dots 0.41 \text{ Nm}$	<b>AM302x</b> $M_0 = 0.48 \dots 0.87 \text{ Nm}$	<b>AM3031</b> $M_0 = 1.20 \text{ Nm}$					
<b>Standard 48 V DC</b>	<b>AM311x*</b> $M_0 = 0.21 \dots 0.34 \text{ Nm}$	<b>AM812x</b> $M_0 = 0.50 \dots 0.80 \text{ Nm}$	<b>AM813x</b> $M_0 = 1.35 \dots 2.37 \text{ Nm}$	<b>AM8141</b> $M_0 = 2.40 \text{ Nm}$				
		<b>AM3121*</b> $M_0 = 0.69 \text{ Nm}$						
<b>Increased inertia 400 V AC</b>			<b>AM853x</b> $M_0 = 1.37 \dots 3.22 \text{ Nm}$	<b>AM854x</b> $M_0 = 2.37 \dots 5.65 \text{ Nm}$	<b>AM855x</b> $M_0 = 4.80 \dots 11.4 \text{ Nm}$ , up to 15.4 Nm with fan	<b>AM856x</b> $M_0 = 12.8 \dots 29.0 \text{ Nm}$ , up to 41.4 Nm with fan		
				<b>AM354x*</b> $M_0 = 1.90 \dots 4.20 \text{ Nm}$	<b>AM355x*</b> $M_0 = 4.10 \dots 8.60 \text{ Nm}$	<b>AM356x*</b> $M_0 = 11.6 \dots 14.9 \text{ Nm}$		
<b>Stainl. steel 400 V AC</b>			<b>AM883x*</b> $M_0 = 0.85 \dots 1.85 \text{ Nm}$	<b>AM884x*</b> $M_0 = 1.60 \dots 3.50 \text{ Nm}$	<b>AM885x*</b> $M_0 = 3.10 \dots 6.40 \text{ Nm}$	<b>AM886x*</b> $M_0 = 7.75 \dots 16.7 \text{ Nm}$		

\*Please note the different flange size.

# Linear Servomotors, stepper motors

- ▶ [www.beckhoff.com/Linear-motors](http://www.beckhoff.com/Linear-motors)
- ▶ [www.beckhoff.com/Stepper-motors](http://www.beckhoff.com/Stepper-motors)



## Linear Servomotors

	AL2000	AL2400	AL2800
<b>Especially suitable for</b>	maximum power density	confined spaces	highest demands on force
<b>Magnetic path width</b>	80 mm	50 mm	130 mm
<b>Cooling</b>	air	air	air, partly water
<b>Max. speed</b>	7 m/s	12 m/s	6 m/s
<b>Max. force</b>	225...1800 N	120...480 N	1800...6750 N
<b>Protection class</b>	IP 64	IP 64	IP 64

## Linear actuators

	AA1121
<b>Rated force</b>	150 N
<b>Peak force</b>	800 N
<b>Max. movement</b>	10 mm
<b>Max. acceleration</b>	7 m/s <sup>2</sup>
<b>Protection class</b>	IP 54

## Stepper motors

	AS1000	AS2000
<b>Sizes</b>	N1 (NEMA17), N2 (NEMA23), N3 (NEMA34)	N2 (NEMA23), N3 (NEMA34)
<b>Resolution</b>	1.8°/200 full steps	1.8°/200 full steps
<b>Encoder</b>	incremental, 1024 lines	incremental, 1024 lines
<b>Standstill torque &lt; 3 A</b>	0.38...0.60 Nm	0.80 Nm
<b>Standstill torque &gt; 3 A</b>	1.20...5.00 Nm	1.50...8.00 Nm
<b>Protection class</b>	IP 43, AS1060: IP 20	IP 54

# Planetary gear units

► [www.beckhoff.com/Planetary-gears](http://www.beckhoff.com/Planetary-gears)



## Planetary gear units for AM8000/AM8500

	AG2210	AG3210	AG2300	AG3300	AG2400	AG3400
<b>Variant</b>	standard (MF)	standard (MF)	standard (MF), high-speed (MC)	standard (MF)	standard (MF)	standard (MF)
<b>Output type</b>	shaft	shaft	shaft	shaft	flange	flange
<b>Gear ratios</b>	1-stage $i = 3 \dots 10$ , 2-stage $i = 9 \dots 100$	1-stage $i = 4 \dots 10$ , 2-stage $i = 16 \dots 100$	1-stage $i = 3 \dots 10$ , 2-stage $i = 16 \dots 100$	1-stage $i = 3 \dots 10$ , 2-stage $i = 9 \dots 100$	1-stage $i = 4 \dots 10$ , 2-stage $i = 16 \dots 100$	1-stage $i = 3 \dots 10$ , 2-stage $i = 9 \dots 100$
<b>Protection class</b>	IP 64	IP 64	IP 65	IP 64	IP 65	IP 64

## Planetary gear units for other motor series

	AG2800	AG2250	AG1000
<b>Variant</b>	stainless steel	straight and angled versions	standard
<b>Motor series</b>	AM8800	AM8100, AS2000	AS1000
<b>Output type</b>	shaft	shaft	shaft
<b>Gear ratios</b>	1-stage $i = 3 \dots 10$ , 2-stage $i = 9 \dots 100$	1-stage $i = 3 \dots 10$ , 2-stage $i = 12 \dots 64$	1-stage $i = 3.7$ or $6.75$
<b>Protection class</b>	IP 69K	IP 54	IP 43, AS1060: IP 20

# Compact Drive Technology

► [www.beckhoff.com/compact-drive-technology](http://www.beckhoff.com/compact-drive-technology)



EtherCAT Terminals



EtherCAT Plug-in Modules




Bus Terminals



EtherCAT Box Modules



EtherCAT P Box Modules

	Product group	DC motor output stage			Stepper motor
		< 3 A	3...5 A	> 5 A	< 3 A
I/O	EtherCAT Terminals IP 20	EL7332 $I_{max} = 1.0 \text{ A}, 24 \text{ V DC}$	EL7332 + ZB8610 $I_{max} = 3.0 \text{ A}, 24 \text{ V DC}$		EL7037 $I_{max} = 1.5 \text{ A}, 24 \text{ V DC}$ , incremental encoder, vector control
			EL7342 $I_{max} = 3.5 \text{ A}, 50 \text{ V DC}$ , incremental encoder	EL7342 + ZB8610 $I_{max} = 6.5 \text{ A}, 50 \text{ V DC}$ , incremental encoder	EL7031 $I_{max} = 1.5 \text{ A}, 24 \text{ V DC}$
	EtherCAT Plug-in Modules IP 20		EJ7342 $I_{max} = 3.5 \text{ A}, 50 \text{ V DC}$ , incremental encoder		
	Bus Terminals IP 20	KL2532 $I_{max} = 1.0 \text{ A}, 24 \text{ V DC}$	KL2552 $I_{max} = 5.0 \text{ A}, 50 \text{ V DC}$ , incremental encoder		KL2531 $I_{max} = 1.5 \text{ A}, 24 \text{ V DC}$
	EtherCAT Box Modules IP 67		EP/ER7342-0002 $I_{max} = 3.5 \text{ A}, 50 \text{ V DC}$		EP/ER7041-1002 $I_{max} = 1.5 \text{ A}, 50 \text{ V DC}$ , incremental encoder
	EtherCAT P Box Modules IP 67		EPP7342-0002 $I_{max} = 3.5 \text{ A}, 50 \text{ V DC}$		EPP7041-1002 $I_{max} = 1.5 \text{ A}, 50 \text{ V DC}$ , incremental encoder
Motion	Flange code F1 (40 mm), N1 (NEMA17)				AS1010 1.0 A, 48 V DC, 0.38 Nm AS1020 1.0 A, 48 V DC, 0.50 Nm
	Flange code F2 (58 mm), N2 (NEMA23)				AS1030 1.5 A, 48 V DC, 0.60 Nm AS2021-0Dy0  2.0 A, 48 V DC, 0.80 Nm
	Flange code F3 (72 mm), N3 (NEMA34)				
	Flange code F4 (87 mm)				



Flange code F1

Flange code N1

Flange code F2

Flange code N2

Flange code F3

Flange code N3

Flange code F4

### Servomotor

		Servomotor		
3...5 A	> 5 A	< 3 A	3...5 A	> 5 A
<b>EL7037 + ZB8610</b> $I_{max} = 3.0\text{ A}$ , 24 V DC, incremental encoder, vector control		<b>EL7201-9014</b> $I_{rms} = 2.8\text{ A}$ , 50 V DC, OCT, STO	<b>EL7201-9014 + ZB8610</b> $I_{rms} = 4.5\text{ A}$ , 50 V DC, OCT, STO	<b>EL7221-9014</b> $I_{rms} = 7...8\text{ A}$ with ZB8610, 50 V DC, OCT, STO
<b>EL7047</b> $I_{max} = 5.0\text{ A}$ , 50 V DC, incremental encoder, vector control	<b>EL7047 + ZB8610</b> $I_{max} = 6.5\text{ A}$ , 50 V DC, incremental encoder, vector control	<b>EL7201-0010</b> $I_{rms} = 2.8\text{ A}$ , 50 V DC, OCT	<b>EL7201-0010 + ZB8610</b> $I_{rms} = 4.5\text{ A}$ , 50 V DC, OCT	
<b>EL7041</b> $I_{max} = 5.0\text{ A}$ , 50 V DC, incremental encoder		<b>EL7201</b> $I_{rms} = 2.8\text{ A}$ , 50 V DC, resolver	<b>EL7201 + ZB8610</b> $I_{rms} = 4.5\text{ A}$ , 50 V DC, resolver	
			<b>EL7211-9014</b> $I_{rms} = 4.5\text{ A}$ , 50 V DC, OCT, STO	
			<b>EL7211-0010</b> $I_{rms} = 4.5\text{ A}$ , 50 V DC, OCT	
			<b>EL7211</b> $I_{rms} = 4.5\text{ A}$ , 50 V DC, resolver	
<b>EJ7047</b> $I_{max} = 5.0\text{ A}$ , 50 V DC, incremental encoder, vector control			<b>EJ7211-0010</b> $I_{rms} = 4.5\text{ A}$ , 50 V DC, OCT	
<b>KL2541</b> $I_{max} = 5.0\text{ A}$ , 50 V DC, incremental encoder				
<b>EP/ER7041-3002</b> $I_{max} = 5.0\text{ A}$ , 50 V DC, incremental encoder			<b>EP7211-9034</b> $I_{rms} = 4.5\text{ A}$ , 50 V DC, OCT, STO	
<b>EPP7041-3002</b> $I_{max} = 5.0\text{ A}$ , 50 V DC, incremental encoder				
		<b>AM8111-wFyz</b> 2.8 A, 48 V DC, 0.20 Nm, 4000 min <sup>-1</sup>	<b>AM8112-wFyz</b> 4.7 A, 48 V DC, 0.38 Nm, 4500 min <sup>-1</sup>	
			<b>AM8113-wFyz</b> 4.8 A, 48 V DC, 0.52 Nm, 3000 min <sup>-1</sup>	
<b>AS1050</b> 5.0 A, 48 V DC, 1.20 Nm	<b>AS2022-0Hy0</b> 5.6 A, 48 V DC, 1.50 Nm	<b>AS2023-0Hy0</b> 5.6 A, 48 V DC, 1.80 Nm	<b>AM8121-wFyz</b> 4.0 A, 48 V DC, 0.50 Nm, 3000 min <sup>-1</sup>	
			<b>AM8122-wFyz</b> 4.0 A, 48 V DC, 0.80 Nm, 2000 min <sup>-1</sup>	<b>AM8122-wJyz</b> 8.0 A, 48 V DC, 0.80 Nm, 4500 min <sup>-1</sup>
<b>AS1060</b> 5.0 A, 48 V DC, 5.00 Nm	<b>AS2041-1Hy0</b> 5.6 A, 48 V DC, 3.30 Nm	<b>AS2042-1Hy0</b> 5.6 A, 48 V DC, 6.40 Nm	<b>AM8131-wFyz</b> 5.0 A, 48 V DC, 1.35 Nm, 1000 min <sup>-1</sup>	<b>AM8131-wJyz</b> 8.0 A, 48 V DC, 1.37 Nm, 1800 min <sup>-1</sup>
				<b>AM8132-wJyz</b> 8.0 A, 48 V DC, 2.35 Nm, 1000 min <sup>-1</sup>
				<b>AM8141-wJyz</b> 8.0 A, 48 V DC, 2.40 Nm, 1000 min <sup>-1</sup>

# XTS | eXtended Transport System

► [www.beckhoff.com/XTS](http://www.beckhoff.com/XTS)



Standard motor module

Black Line motor module

Hygienic motor module

Motor module   Standard				
	straight	curved, 180°	curved, 45°	curved, 22.5°
	AT2000-0250			
	AT2001-0250 with feed			
<b>Clothoid</b>		AT2050-0500		
<b>Positive curve (convex)</b>			AT2040-0250 with feed	AT2020-0250 with feed
<b>Negative curve (concave)</b>				AT2025-0250 with feed

Motor module   Black Line				
	straight	curved, 180°	curved, 45°	curved, 22.5°
	AT2000-0250-0002			
	AT2001-0250-0002 with feed			
<b>Clothoid</b>		AT2050-0500-0002		
<b>Positive curve (convex)</b>			AT2040-0250-0002 with feed	AT2020-0250-0002 with feed
<b>Negative curve (concave)</b>				AT2025-0250-0002

Motor module   Hygienic				
	straight	curved, 180°	curved, 45°	curved, 22.5°
	ATH2000-0250	<u>i</u>		
	ATH2001-0250 with feed	<u>i</u>		
<b>Clothoid</b>		ATH2050-0500	<u>i</u>	





Guide rail   Standard				
	straight	curved, 180°	curved, 45°	curved, 22.5°
	AT9000-xxxx without lock			
	AT9100-xxxx with lock			
<b>Clothoid</b>		AT9050-0500		
<b>Positive curve (convex)</b>		AT9040-1250	AT9040-xxxx AT9142-2000 full circle	AT9020-0500
<b>Negative curve (concave)</b>				AT9025-xxxx

Guide rail   Hygienic				
	straight	curved, 180°	curved, 45°	curved, 22.5°
	ATH9000-xxxx without lock	<a href="#">i</a>		
	ATH9100-xxxx with lock	<a href="#">i</a>		
<b>Clothoid</b>		ATH9050-0500-0075	<a href="#">i</a>	

Mover   Standard				
	straight*	curved, 180° *	curved, 45° *	curved, 22.5° *
<b>6 rollers, 50 mm</b>	AT9011-0050-0550	AT9011-0050-0550	AT9011-0050-0550	AT9011-0050-0550
<b>12 rollers, 50 mm</b>	AT9012-0050-0550	AT9012-0050-0550		
<b>6 rollers, 70 mm</b>	AT9011-0070-0550	AT9011-0070-0550	AT9011-0070-0550	AT9011-0070-0550

\* Movers can be used with specified motor module types.

Mover   Hygienic				
	straight*	curved, 180° *	curved, 45° *	curved, 22.5° *
<b>6 rollers, 75 mm</b>	ATH9011-0075-0550	<a href="#">i</a> ATH9011-0075-0550	<a href="#">i</a>	

\* Movers can be used with specified motor module types.

Starter kit   Standard			
	small	medium	large
	AT2000-0500	AT2000-1000	AT2000-1500

# The Automation Company

Beckhoff offers comprehensive system solutions in numerous performance classes for all areas of automation. The control technology is exceptionally scalable – from high-performance Industrial PCs to mini-PLCs – and can be adapted precisely to application-specific requirements. TwinCAT automation software integrates real-time control with PLC, NC and CNC functions in a single feature-filled package.

► [www.beckhoff.com/Automation](http://www.beckhoff.com/Automation)

## Efficient engineering

- Integration into Microsoft Visual Studio®
- Wide selection of programming languages: IEC 61131-3, C/C++, MATLAB®/Simulink®, Safety C/FBD
- Modular software development
- Automatic code generation interface
- Link to source code control systems

## High performance

- Cycle times from 50 µs
- Multi-core support
- Support of 32-bit and 64-bit operating systems
- Pre-emptive multitasking

## Connectivity

- Useable with all fieldbus systems
- Open and expandable for IT trends – today and tomorrow
- Adheres to industry-specific and standard protocols
- Ideal for IoT and cloud computing applications

► [www.beckhoff.com/TwinCAT3](http://www.beckhoff.com/TwinCAT3)





# TwinCAT 3

► [www.beckhoff.com/TwinCAT3](http://www.beckhoff.com/TwinCAT3)

TwinCAT 3 realises a new approach for the engineering and extends the runtime by many features. The engineering is embedded completely in the Microsoft Visual Studio® framework. This way, C/C++ or MATLAB®/Simulink® are available in a single environment with programming and debugging in addition to the configuration of system, motion, I/O and the IEC 61131 PLC programming languages.

With these programming languages it is possible to create modules that can be executed in the TwinCAT 3 runtime. The number of modules that can be executed is almost unlimited. The number of tasks in TwinCAT 3 has also been significantly extended. The TwinCAT 3 runtime environment allows modules to be loaded to different cores of a multi-core CPU.

The TwinCAT 3 runtime components are available for different platforms.

**TwinCAT 3 – Platforms**

**Example of a TwinCAT 3 performance class:**  
 C6920 | Control cabinet Industrial PC with Intel® Core™ i3, 2 cores, processor  
 TwinCAT 3 performance class: (TC3: 60), corresponds to the TwinCAT 3 platform P60 Mid performance

Platform	Processor	Performance Class	Core Count
P20	ARM, 600 MHz	Economy	-
P30	ARM Cortex™-A8, AMD LX800	Economy plus	-
P40	Intel® Atom™	Performance	-
P50	Intel® Celeron® ULV/1.6 GHz, Pentium® 2.2 GHz, 2.3 GHz, 2.4 GHz	Performance plus	-
P60	Intel® Core™ i3	Mid performance	-
P70	Intel® Core™ i5	High performance	-
P80	Intel® Core™ i7	Very high performance	-
P81	Many Core	Very high performance	5-8 cores
P82	Many Core	Very high performance	9-16 cores
P83	Many Core	Very high performance	17-32 cores
P84	Many Core	Very high performance	33-64 cores
P90	Third-party devices	-	-
P91	-	-	5-8 cores
P92	-	-	9-16 cores
P93	-	-	17-32 cores
P94	-	-	33-64 cores

The controllers integrated in the platform categorisation are only example configurations.

## TwinCAT 3 – eXtended Automation Engineering (XAE)

## TwinCAT 3 – eXtended Automation Runtime (XAR)

### Base

TC1270 | TC3 PLC/NC PTP 10/NC I/CNC

TC1260 | TC3 PLC/NC PTP 10/NC I

TC1250 | TC3 PLC/NC PTP 10

TC1200 | TC3 PLC

TC1100 | TC3 I/O

TC1000 | TC3 ADS

TC1220 | TC3 PLC/C++/MATLAB®/Simulink®

TC1210 | TC3 PLC/C++

TC1100 | TC3 I/O

TC1000 | TC3 ADS

TC1320 | TC3 C++/MATLAB®/Simulink®

TC1300 | TC3 C++

TC1100 | TC3 I/O

TC1000 | TC3 ADS

### Functions

TF1xxx | System

TF2xxx | HMI

TF3xxx | Measurement

TF4xxx | Controller

TF5xxx | Motion

TF6xxx | Connectivity

TF8xxx | Industry specific

TwinCAT 3 is divided into components. The TwinCAT 3 engineering components enable the configuration, programming and debugging of applications. The TwinCAT 3 runtime consists of further components – basic components and functions. The basic components can be extended by functions.

## TwinCAT 3 | Engineering

TE1000	TC3 Engineering	TwinCAT 3 engineering environment	
TE1111	TC3 EtherCAT Simulation	easy configurations of simulation environments with several EtherCAT slaves	
TE1120	TC3 XCAD Interface	transfer of existing engineering results from ECAD tools	
TE1200	TC3 PLC Static Analysis	analysis tool that tests PLC software on the basis of coding rules	
TE1210	TC3 PLC Profiler	analyses the runtime characteristics of a PLC application and identifies time-intensive callups and program sections	<b>i</b>
TE1300	TC3 Scope View Professional	software oscilloscope for the graphical display of data captured from several target systems	
TE1310	TC3 Filter Designer	graphic engineering tool for determining coefficient digital filters	<b>i</b>
TE1400	TC3 MATLAB®/Simulink® Target	TwinCAT target for MATLAB®/Simulink® for generating TwinCAT 3 modules	
TE1410	TC3 Interface for MATLAB®/Simulink®	communication interface between MATLAB®/Simulink® and the TwinCAT 3 runtime	
TE1420	TC3 Target for FMI	interface for simulation tools that support the Functional Mockup Interface (FMI)	<b>i</b>
TE1500	TC3 Valve Diagram Editor	graphical tool for designing the characteristic curve of a hydraulic valve	
TE1510	TC3 Cam Design Tool	graphic design tool for electronic cam plates	
TE1610	TC3 EAP Configurator	a tool for visualising and configuring communication networks, in which data exchange based on the EtherCAT Automation Protocol (EAP) takes place or is to be established	
TE2000	TC3 HMI	tool for developing platform-independent user interfaces	<b>i</b>
TE3500	TC3 Analytics Workbench	complete solution for 24/7 monitoring of machines and systems incl. visualisation on analysis dashboards	<b>i</b>
TE3501	TC3 Analytics Controller Pack 10	extension of the TC3 Analytics Workbench for the analysis of 10 additional controllers	<b>i</b>
TE3502	TC3 Analytics Controller Pack 20	extension of the TC3 Analytics Workbench for the analysis of 20 additional controllers	<b>i</b>
TE3503	TC3 Analytics Controller Pack 50	extension of the TC3 Analytics Workbench for the analysis of 50 additional controllers	<b>i</b>
TE3504	TC3 Analytics Controller Pack 100	extension of the TC3 Analytics Workbench for the analysis of 100 additional controllers	<b>i</b>
TE3505	TC3 Analytics Controller Pack Unlimited	extension of the TC3 Analytics Workbench for the analysis of an unlimited number of additional controllers, limited only by potential performance restrictions of the user	<b>i</b>
TE3510	TC3 Analytics Service Tool	process data analysis tool for commissioning and service technicians	<b>i</b>

## TwinCAT 3 | Base

TC1000	TC3 ADS	TwinCAT 3 ADS	
TC1100	TC3 I/O	TwinCAT 3 I/O	
TC1200	TC3 PLC	TwinCAT 3 PLC	
TC1210	TC3 PLC/C++	TwinCAT 3 PLC and C++	
TC1220	TC3 PLC/C++/MATLAB®/Simulink®	TwinCAT 3 PLC, C++ and modules generated in MATLAB®/Simulink®	
TC1250	TC3 PLC/NC PTP 10	TwinCAT 3 PLC and NC PTP 10	
TC1260	TC3 PLC/NC PTP 10/NC I	TwinCAT 3 PLC, NC PTP 10 and NC I	
TC1270	TC3 PLC/NC PTP 10/NC I/CNC	TwinCAT 3 PLC, NC PTP 10, NC I and CNC	
TC1275	TC3 PLC/NC PTP 10/NC I/CNC E	TwinCAT 3 PLC, NC PTP 10, NC I and CNC E	
TC1300	TC3 C++	TwinCAT 3 C++	
TC1320	TC3 C++/MATLAB®/Simulink®	TwinCAT 3 C++ and modules generated in MATLAB®/Simulink®	

## TwinCAT 3 | Functions

### System

TF1800	TC3 PLC HMI	stand-alone tool for displaying visualisations from the PLC development environment
TF1810	TC3 PLC HMI Web	display of visualisations from the PLC development environment in a web browser
TF1910	TC3 UML	UML (Unified Modeling Language) for modelling of PLC software

### HMI

TF2000	TC3 HMI Server	modular web server, includes a client connection and a target connection	<a href="#">i</a>
TF2010	TC3 HMI Clients Pack 1	extension of TC3 HMI server for one additional client connection	<a href="#">i</a>
TF2020	TC3 HMI Clients Pack 3	extension of TC3 HMI server for 3 additional client connections	<a href="#">i</a>
TF2030	TC3 HMI Clients Pack 10	extension of TC3 HMI server for 10 additional client connections	<a href="#">i</a>
TF2040	TC3 HMI Clients Pack 25	extension of TC3 HMI server for 25 additional client connections	<a href="#">i</a>
TF2050	TC3 HMI Targets Pack 1	extension of TC3 HMI server for one additional control system	<a href="#">i</a>
TF2060	TC3 HMI Targets Pack 3	extension of TC3 HMI server for 3 additional control systems	<a href="#">i</a>
TF2070	TC3 HMI Targets Pack 10	extension of TC3 HMI server for 10 additional control systems	<a href="#">i</a>
TF2080	TC3 HMI Targets Pack 25	extension of TC3 HMI server for 25 additional control systems	<a href="#">i</a>
TF2090	TC3 HMI Targets Pack 100	extension of TC3 HMI server for 100 additional control systems	<a href="#">i</a>
TF2100	TC3 HMI ADS	server extension for access to TwinCAT target systems via ADS	<a href="#">i</a>
TF2110	TC3 HMI OPC UA	server extension for access to TwinCAT target systems or other controllers via OPC UA	<a href="#">i</a>
TF2200	TC3 HMI Extension SDK	software development kit (C++/.NET) for programming application-specific solutions	<a href="#">i</a>
TF2210	TC3 HMI Recipe Management	server extension for recipe management	<a href="#">i</a>
TF2300	TC3 HMI Scope	software oscilloscope for graphic display of time sequences	<a href="#">i</a>

### Measurement

TF3300	TC3 Scope Server	data preparation for visual display in the TwinCAT 3 Scope View	
TF3500	TC3 Analytics Logger	The TwinCAT Analytics Logger enables the cyclic archiving of the process image.	<a href="#">i</a>
TF3510	TC3 Analytics Library	PLC library used for online or offline analysis in the PLC runtime of the TwinCAT Analytics Workbench	<a href="#">i</a>
TF3600	TC3 Condition Monitoring Level 1	PLC library for the implementation of Condition Monitoring for machines	
TF3601	TC3 Condition Monitoring Level 2	expanded PLC library for the implementation of Condition Monitoring for machines	<a href="#">i</a>
TF3650	TC3 Power Monitoring	TwinCAT Power Monitoring PLC library	
TF3900	TC3 Solar Position Algorithm	precise calculation of the sun's position	

### Controller

TF4100	TC3 Controller Toolbox	basic controllers (P, I, D), complex controllers (PI, PID), pulse width modulation, ramps, signal generators and filters
TF4110	TC3 Temperature Controller	temperature control for monitoring and controlling different temperature ranges

## TwinCAT 3 | Functions

### Motion

TF5000	TC3 NC PTP 10 Axes	NC PTP (point-to-point movements) for up to 10 axes	
TF5010	TC3 NC PTP Axes Pack 25	extension of TwinCAT 3 NC PTP to up to 25 axes	
TF5020	TC3 NC PTP Axes Pack unlimited	extension of TwinCAT 3 NC PTP to over 25 axes	
TF5050	TC3 NC Camming	using the TwinCAT NC cam plate functionality (table coupling)	
TF5055	TC3 NC Flying Saw	implementing flying saw functionality	
TF5060	TC3 NC FIFO Axes	implementation of a pre-defined user setpoint generator for an NC axis	
TF5065	TC3 Motion Control XFC	high-precision logging and switching of digital signals in relation to axis positions	
TF5100	TC3 NC I	NC I with 3 interpolating axes and 5 additional axes	
TF5110	TC3 Kinematic Transformation L1	realisation of different kinematic transformations Level 1	
TF5111	TC3 Kinematic Transformation L2	realisation of different kinematic transformations Level 2	
TF5112	TC3 Kinematic Transformation L3	realisation of different kinematic transformations Level 3	
TF5113	TC3 Kinematic Transformation L4	realisation of different kinematic transformations Level 4	
TF5120	TC3 Robotics mxAutomation	direct communication between the PLC and the KUKA KR C4 robot control	
TF5130	TC3 Robotics uniVAL PLC	direct communication between the PLC and the CS8C robotics controller from Stäubli	<b>i</b>
TF5200	TC3 CNC	CNC path control software	
TF5210	TC3 CNC E	CNC path control software export version	
TF5220	TC3 CNC Axes Pack	extension to up to a total of 64 axes/controlled spindles, of which a maximum of 32 can be path axes and a maximum of 12 can be controlled spindles	
TF5230	TC3 CNC Channel Pack	further CNC channel, extension to a maximum of 12 channels, channel synchronisation, axis transfer between channels	
TF5240	TC3 CNC Transformation	transformation functionality (5-axis functionality)	
TF5250	TC3 CNC HSC Pack	extending the CNC with HSC technology (high-speed cutting)	
TF5260	TC3 CNC Spline Interpolation	path programming via splines with programmable spline type, Akima-spline, B-spline	
TF5270	TC3 CNC Virtual NCK Basis	virtual TwinCAT CNC for simulation in a Windows environment	
TF5271	TC3 CNC Virtual NCK Options	virtual TwinCAT CNC for simulation in a Windows environment	
TF5280	TC3 CNC Volumetric Compensation	extension for compensating geometric machine errors based on an ISO-standardised parametric model	<b>i</b>
TF5290	TC3 CNC Cutting Plus	technology package for extending the CNC functionality for cutting operations	<b>i</b>
TF5410	TC3 Motion Collision Avoidance	collision avoidance and controlled accumulation when operating a number of linearly and/or translationally dependent axes with TC3 NC PTP	
TF5420	TC3 Motion Pick-and-Place	for handling tasks carried out by gantry robots and other kinematics	
TF5800	TC3 Digital Cam Server	fast cam controller with monitoring for various fieldbuses	<b>i</b>
TF5810	TC3 Hydraulic Positioning	algorithms for control and positioning of hydraulic axes	



## TwinCAT 3 | Functions

### Connectivity

TF6000	TC3 ADS Communication Library	ADS communication components	
TF6100	TC3 OPC UA	access to TwinCAT in accordance with OPC UA with UA server (DA/HA/AC) and UA client (DA)	
TF6120	TC3 OPC DA	access to TwinCAT variables, in accordance with OPC DA and OPC XML DA specification	
TF6220	TC3 EtherCAT Redundancy 250	extension of the TwinCAT EtherCAT master with cable redundancy capability for up to 250 slaves	
TF6221	TC3 EtherCAT Redundancy 250+	extension of the TwinCAT EtherCAT master with cable redundancy capability for more than 250 slaves	
TF6225	TC3 EtherCAT External Sync	extension of the TwinCAT EtherCAT master with an option to synchronise the Beckhoff real-time communication with external signals	
TF6250	TC3 Modbus TCP	communication with Modbus TCP devices (server and client functionality)	
TF6255	TC3 Modbus RTU	serial communication with Modbus end devices	
TF6270	TC3 PROFINET RT Device	communication via PROFINET (PROFINET slave)	
TF6271	TC3 PROFINET RT Controller	communication via PROFINET (PROFINET master)	
TF6280	TC3 Ethernet/IP Slave	communication via EtherNet/IP (EtherNet/IP slave)	
TF6281	TC3 Ethernet/IP Master	communication via EtherNet/IP (EtherNet/IP master)	<a href="#">i</a>
TF6300	TC3 FTP	easy access from TwinCAT PLC to FTP server	
TF6310	TC3 TCP/IP	communication via generic TCP server	
TF6311	TC3 TCP/UDP Realtime	direct access from real-time to Ethernet communication	
TF6340	TC3 Serial Communication	communication via serial Bus Terminals or PC COM ports with the 3964R and RK512 protocol	
TF6350	TC3 SMS/SMTP	sending SMS and e-mails from the PLC	
TF6360	TC3 Virtual Serial COM	virtual serial COM driver for Windows platforms	
TF6420	TC3 Database Server	accessing databases from the PLC	
TF6421	TC3 XML Server	read and write access to XML files from the PLC	
TF6500	TC3 IEC 60870-5-10x	communication according to IEC 60870-101, -102, -103, -104	
TF6510	TC3 IEC 61850/400-25	communication according to IEC 61850 and IEC 61400-25	
TF6600	TC3 RFID Reader Communication	connection of RFID readers to the TwinCAT PLC	
TF6610	TC3 S5/S7 Communication	communication with S5/S7 controllers	
TF6650	TC3 DBC File Import for CAN	reading of DBC file formats	
TF6701	TC3 IoT Communication (MQTT)	provides basic publisher/subscriber-based data connectivity via MQTT	<a href="#">i</a>
TF6710	TC3 IoT Functions	provides connectivity for cloud-based communication services	<a href="#">i</a>
TF6720	TC3 IoT Data Agent	gateway application for data connectivity between TwinCAT runtime and IoT services	<a href="#">i</a>
TF6721	TC3 IoT Data Agent Pack 4	extension of TC3 IoT Data Agent for 4 additional ADS target runtimes or OPC UA namespaces	<a href="#">i</a>
TF6722	TC3 IoT Data Agent Pack 16	extension of TC3 IoT Data Agent for 16 additional ADS target runtimes or OPC UA namespaces	<a href="#">i</a>
TF6723	TC3 IoT Data Agent Pack 64	extension of TC3 IoT Data Agent for 64 additional ADS target runtimes or OPC UA namespaces	<a href="#">i</a>
TF6724	TC3 IoT Data Agent Pack 256	extension of TC3 IoT Data Agent for 256 additional ADS target runtimes or OPC UA namespaces	<a href="#">i</a>
TF6730	TC3 IoT Communicator	sends process data and push notifications from TwinCAT to smartphones and tablets through a messaging service	<a href="#">i</a>
TF6735	TC3 IoT Communicator App	smartphone and tablet app to receive and visualise live data and push notifications sent from TwinCAT	<a href="#">i</a>
<b>Industry specific</b>			
TF8000	TC3 BA Connectivity Library	libraries for programming of Bus Terminals for building automation (DALI, EnOcean, SMI, EIB, LON, M-Bus, GENibus, MP-Bus, DMX and manual operating modules)	
TF8010	TC3 Building Automation Basic	executing basic room automation functions	
TF8020	TC3 BACnet/IP	communication with data networks of building automation and building control systems	<a href="#">i</a>
TF8040	TC3 Building Automation	software package covering all technical building automation services	
TF8310	TC3 Wind Framework	framework for the development of operational management software for wind turbines	
TF8810	TC3 AES70 (OCA)	communication library for the operation of a system as an OCA (Open Control Architecture) controller or OCA device in an OCA network	

# TwinCAT 2

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TX1200   TwinCAT PLC	
<b>PC hardware</b>	standard PC/IPC hardware, no extras
<b>Operating systems</b>	Windows NT/2000/XP/Vista, Windows 7/10, Windows CE*
<b>Real-time</b>	Beckhoff real-time kernel
<b>I/O system</b>	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet, SERCOS, Ethernet
<b>Runtime system</b>	4 multi-tasking PLCs each with 4 tasks in each PLC runtime system, development and runtime systems on one PC or separately (CE: only runtime)
<b>Memory</b>	process image size, flags area, program size, POU size, number of variables only limited by the size of the user memory (max. 2 GB with NT/2000/XP/Vista)
<b>Cycle time</b>	adjustable from 50 µs
<b>Link time</b>	1 µs (Intel® Core™ 2 Duo)
<b>Programming</b>	IEC 61131-3: IL, FBD, LD, SFC, ST, powerful library management, convenient debugging

TX1250   TwinCAT NC PTP	
<b>TwinCAT PLC</b>	inclusive
<b>PC hardware</b>	standard PC/IPC hardware, no extras
<b>Operating systems</b>	Windows NT/2000/XP/Vista, Windows 7/10, Windows CE*
<b>Real-time</b>	Beckhoff real-time kernel
<b>I/O system</b>	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet, SERCOS, Ethernet
<b>Programming</b>	performed using function blocks for TwinCAT PLC according to IEC 61131-3 (standardised PLCopen Motion Control libraries), convenient axis commissioning menus in the System Manager
<b>Runtime system</b>	NC point-to-point including TwinCAT PLC
<b>Number of axes</b>	up to 255
<b>Axis types</b>	electrical and hydraulic servo drives, frequency converter drives, stepper motor drives, switched drives (fast/crawl axes)
<b>Cycle time</b>	50 µs upwards, typically 1 ms (selectable)
<b>Axis functions</b>	standard axis functions: start/stop/ reset/reference, speed override, special functions: master/slave cascading, cam plates, electronic gearings, online distance compensation of segments, flying saw

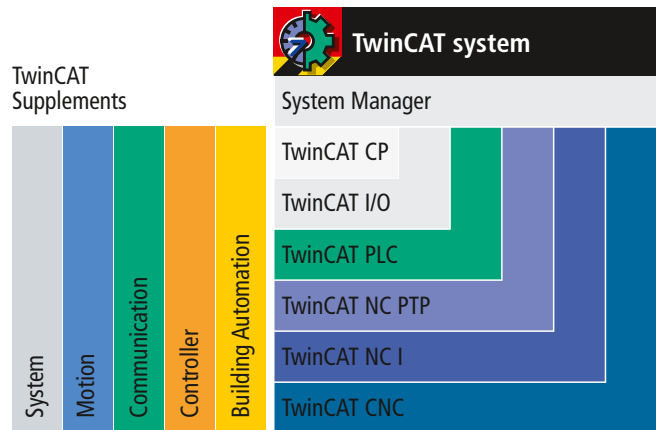
TX1100   TwinCAT I/O	
<b>PC hardware</b>	standard PC/IPC hardware, no extras
<b>Operating systems</b>	Windows NT/2000/XP/Vista, Windows 7, NT/XP/Windows 7 Embedded, CE (only runtime)*
<b>Real-time</b>	Beckhoff real-time kernel

Multi-purpose I/O interface for all common fieldbus systems, PC Fieldbus Cards and interfaces with integrated real-time driver

TX1000   TwinCAT CP	
<b>PC hardware</b>	standard PC/IPC hardware, no extras
<b>Operating systems</b>	Windows NT/2000/XP/Vista, Windows 7, NT/XP/Windows 7 Embedded*
<b>Real-time</b>	Beckhoff real-time kernel

Windows driver for Beckhoff Control Panel

\* version-dependent



TX1260   TwinCAT NC I	
<b>TwinCAT PLC</b>	inclusive
<b>TwinCAT NC PTP</b>	inclusive
<b>PC hardware</b>	standard PC/IPC hardware, no extras
<b>Operating systems</b>	Windows NT/2000/XP/Vista, Windows 7/10, Windows CE*
<b>Real-time</b>	Beckhoff real-time kernel
<b>I/O system</b>	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet, SERCOS, Ethernet
<b>Programming</b>	DIN 66025 programs for NC interpolation, access via function blocks from TwinCAT PLC according to IEC 61131-3
<b>Runtime system</b>	NC interpolation, including TwinCAT NC PTP and PLC
<b>Number of axes</b>	max. 3 axes and up to 5 auxiliary axes per group, 1 group per channel, max. 31 channels
<b>Axis types</b>	electrical servo axes, stepper motor drives
<b>Interpreter functions</b>	subroutines and jumps, programmable loops, zero shifts, tool compensations, M and H functions
<b>Geometries</b>	straight lines and circular paths in 3-D space, circular paths in all main planes, helices with base circles in all main planes linear, circular, helical interpolation in the main lanes and freely definable planes, Bezier splines, look-ahead function
<b>Axis functions</b>	online reconfiguration of axes in groups, path override, slave coupling to path axes, auxiliary axes, axis error and sag compensation, measuring functions
<b>Operation</b>	automatic operation, manual operation (jog/inching), single block operation, referencing, handwheel operation (motion/superposition)

TS511x   TwinCAT NC I Options	
<b>Options</b>	TS511x   TwinCAT Kinematic Transformation

TX1270   TwinCAT CNC	
<b>TwinCAT PLC</b>	inclusive
<b>TwinCAT NC PTP</b>	inclusive
<b>TwinCAT NC I</b>	inclusive
<b>PC hardware</b>	standard PC/IPC hardware, no extras
<b>Operating systems</b>	Windows NT/2000/XP/Vista, Windows 7, Windows NT/XP Embedded*
<b>Real-time</b>	Beckhoff real-time kernel
<b>I/O system</b>	EtherCAT, Lightbus, PROFIBUS DP/MC, CANopen, DeviceNet, SERCOS, Ethernet
<b>Programming</b>	DIN 66025 programming language with high-level language extensions, access via function blocks from TwinCAT PLC according to IEC 61131-3
<b>Runtime system</b>	CNC, including TwinCAT NC I, NC PTP, PLC
<b>Number of axes/spindles</b>	8 path axes/controlled spindles, max. of 64 axes/controlled spindles (optional), max. 12 channels (optional)
<b>Axis types</b>	electrical servo-axes, analog/encoder interface via fieldbus, digital interface via fieldbus
<b>Interpreter functions</b>	subroutines and jumps, programmable loops, zero shifts, tool compensations, M and H functions, mathematical functions, programming of parameters/variables, user macros, spindle and help functions, tool functions
<b>Geometries</b>	linear, circular, helical interpolation in the main planes and freely definable planes, max. 32 interpolating path axes per channel, look-ahead function
<b>Axis functions</b>	coupling and gantry axis function, override, axis error and sag compensation, measuring functions
<b>Operation</b>	automatic operation, manual operation (jog/inching), single block operation, referencing, block search, handwheel operation (motion/superposition)

TS52xx   TwinCAT CNC Options	
<b>Options</b>	TS5220   TwinCAT CNC Axes Pack
	TS5230   TwinCAT CNC Channel Pack
	TS5240   TwinCAT CNC Transformation
	TS5250   TwinCAT CNC HSC Pack
	TS5260   TwinCAT CNC Spline Interpolation

## TwinCAT 2 Supplements | System

TS1010	TwinCAT Eventlogger	alarm and diagnostic system for logging events which occur in the TwinCAT system
TS1110	TwinCAT Simulation Manager	simplified preparation and configuration of a simulation environment
TS1120	TwinCAT ECAD Import	importing engineering results from an ECAD program
TS1140	TwinCAT Management Server	central administration of Beckhoff CE control systems
TS1150	TwinCAT Backup	backing up and restoring files, operating system and TwinCAT settings
TS1600	TwinCAT Engineering Interface Server	co-ordinating programming tasks via a central source code management system
TS1800	TwinCAT PLC HMI	displaying visualisations created in PLC Control
TS1800-0030	TwinCAT PLC HMI CE	displaying visualisations created in PLC Control on Windows CE platforms
TS1810	TwinCAT PLC HMI Web	displaying visualisations created in PLC Control in a web browser
TS3300	TwinCAT Scope 2	graphical analysis tool for displaying time-continuous signals
TS3900	TwinCAT Solar Position Algorithm	precise calculation of the sun's position
TS622x	TwinCAT EtherCAT Redundancy	extension of the TwinCAT EtherCAT master with cable redundancy capability
TS6420	TwinCAT Database Server	accessing databases from the PLC
TS6420-0030	TwinCAT Database Server CE	accessing databases from the PLC for Windows CE platforms
TS6421	TwinCAT XML Data Server	reading and writing of XML-based data by the PLC
TS6421-0030	TwinCAT XML Data Server CE	reading and writing of XML-based data by the PLC for Windows CE platforms

## TwinCAT 2 Supplements | Controller

TS4100	TwinCAT PLC Controller Toolbox	modules for basic controllers (P, I, D), complex controllers (PI, PID), pulse width modulation, ramps, signal generators and filters
TS4110	TwinCAT PLC Temperature Controller	instanced temperature control function block for monitoring and controlling different temperature ranges

## TwinCAT 2 Supplements | Motion

TS1500	TwinCAT Valve Diagram Editor	graphical tool for designing the characteristic curve of a hydraulic valve
TS1510	TwinCAT Cam Design Tool	graphic design tool for electronic cam plates
TS5050	TwinCAT NC Camming	using the TwinCAT NC cam plate functionality (table coupling)
TS5055	TwinCAT NC Flying Saw	implementing flying saw functionality
TS5060	TwinCAT NC FIFO Axes	implementation of a pre-defined user setpoint generator for an NC axis
TS5065	TwinCAT PLC Motion Control XFC	high-precision logging and switching of digital signals in relation to axis positions
TS5066	TwinCAT PLC Remote Synchronisation	remote synchronisation
TS511x	TwinCAT Kinematic Transformation	implementation of different kinematic transformations for TwinCAT PTP or TwinCAT NC I
TS5800	TwinCAT Digital Cam Server	software implementation of fast cam controller
TS5810	TwinCAT PLC Hydraulic Positioning	control and adjustment of hydraulic axes

## TwinCAT 2 Supplements | Communication

TS6100	TwinCAT OPC UA Server	access to TwinCAT in accordance with OPC UA with UA server (DA/HA/AC) and UA client (DA)
TS6100-0030	TwinCAT OPC UA Server CE	access to TwinCAT in accordance with OPC UA with UA server (DA/HA/AC) and UA client (DA) for Windows CE platforms

## TwinCAT 2 Supplements | Communication

TS6120	<b>TwinCAT OPC Server</b>	access to TwinCAT variables in accordance with the OPC DA/OPC XML DA specification
TS6250	<b>TwinCAT Modbus TCP Server</b>	communication with Modbus TCP devices (server and client functionality)
TS6250-0030	<b>TwinCAT Modbus TCP Server CE</b>	communication with Modbus TCP devices (server and client functionality) for Windows CE platforms
TS6255	<b>TwinCAT PLC Modbus RTU</b>	serial communication with Modbus end devices
TS6270	<b>TwinCAT PROFINET RT Device</b>	TwinCAT PROFINET RT device turns every PC-based controller into a PROFINET RT device.
TS6271	<b>TwinCAT PROFINET RT Controller</b>	TwinCAT PROFINET RT controller turns every PC-based controller into a PROFINET RT controller.
TS6280	<b>TwinCAT EtherNet/IP Slave</b>	TwinCAT EtherNet/IP slave turns every PC-based controller into an EtherNet/IP slave.
TS6300	<b>TwinCAT FTP Client</b>	basic access from TwinCAT PLC to FTP server
TS6310	<b>TwinCAT TCP/IP Server</b>	communication via generic TCP servers
TS6310-0030	<b>TwinCAT TCP/IP Server CE</b>	communication via generic TCP servers for Windows CE platforms
TS6340	<b>TwinCAT PLC Serial Communication</b>	communication via serial Bus Terminals or PC COM ports
TS6341	<b>TwinCAT PLC Serial Communication 3964R/RK512</b>	communication via serial Bus Terminals or PC COM ports with the 3964R and RK512 protocol
TS6350	<b>TwinCAT SMS/SMTP Server</b>	sending SMS and e-mails from the PLC
TS6350-0030	<b>TwinCAT SMS/SMTP Server CE</b>	sending SMS and e-mails from the PLC for Windows CE platforms
TS6360	<b>TwinCAT Virtual Serial COM Driver</b>	virtual serial COM driver for Windows and Windows CE platforms
TS6370	<b>TwinCAT DriveCOM OPC Server</b>	fieldbus-independent communication connections between the engineering tool and the drive
TS6371	<b>TwinCAT DriveTop Server</b>	configuring Indramat SERCOS drives with DriveTop software on TwinCAT systems
TS650x	<b>TwinCAT PLC IEC 60870-5-101, -102, -103, -104 Master</b>	implementation of IEC 60870-101, -102, -103 and -104 masters
TS650x-0030	<b>TwinCAT PLC IEC 60870-5-104 Master CE</b>	implementation of IEC 60870-104 masters under Windows CE
TS6507	<b>TwinCAT PLC IEC 60870-5-101, -104 Slave</b>	implementation of IEC 60870-101 and -104 slaves
TS6507-0030	<b>TwinCAT PLC IEC 60870-5-104 Slave CE</b>	implementation of IEC 60870-104 slaves under Windows CE
TS6509	<b>TwinCAT PLC IEC 61400-25 Server</b>	IEC 61400-25 communication
TS6511	<b>TwinCAT PLC IEC 61850 Server</b>	IEC 61850 communication
TS6600	<b>TwinCAT PLC RFID Reader Communication</b>	connection of RFID readers to the TwinCAT PLC
TS6610	<b>TwinCAT PLC S5/S7 Communication</b>	communication with S5/S7 controllers

## TwinCAT 2 Supplements | Building Automation

TS8000	<b>TwinCAT PLC HVAC</b>	automation of HVAC and sanitary installations
TS8010	<b>TwinCAT PLC Building Automation Basic</b>	executing basic room automation functions
TS8020	<b>TwinCAT BACnet/IP</b>	communication with the data networks of the building automation and building control systems
TS8035	<b>TwinCAT FIAS Server</b>	communication between TwinCAT PLC and a system using the FIAS standard
TS8036	<b>TwinCAT Crestron Server</b>	communication between a TwinCAT PLC and a Crestron controller
TS8040	<b>TwinCAT Building Automation</b>	software package covering all technical building automation services
TS8100	<b>TwinCAT Building Automation Framework</b>	configuration and commissioning of building automation projects

# TwinSAFE

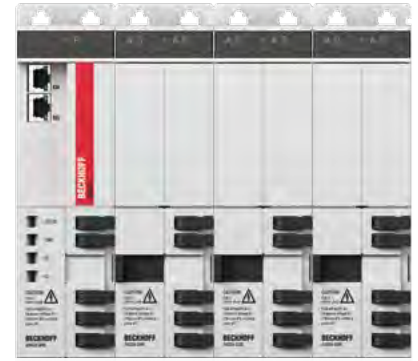
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EK1960



EJ1914



AX8000

TwinSAFE		I/O		Drive Technology		
Controller		I/O		Drive Technology		
<b>EtherCAT Terminal</b>	<b>EK1960</b> TwinSAFE Compact Controller, 20 safe digital inputs, 10 safe digital outputs	<b>EtherCAT Terminal</b>	<b>EK1914</b> EtherCAT Coupler with integrated digital I/Os: 4 inputs + 4 outputs, 2 safe inputs + 2 safe outputs	<b>Option cards</b>	<b>AX5801-0200</b> drive-integrated safety functions: STO, SS1	
	<b>EL6900</b> TwinSAFE Logic		<b>EL1904</b> TwinSAFE, 4 safe inputs		<b>AX5805, AX5806</b> drive-integrated safety functions: STO, SOS, SS1, SS2, SLS, SSM, SSR, SMS, SLP, SCA, SLI, SAR, SMA, SDIp and SDIn	
	<b>EL6910</b> TwinSAFE Logic		<b>EL2901</b>  TwinSAFE, 1 safe output		<b>Axis modules</b>	<b>AX81xx-0100, AX82xx-0100</b> feedback: OCT, TwinSAFE: STO/SS1, TwinSAFE Logic integrated
	<b>EL6930</b> TwinSAFE/PROFIsafe logic and gateway terminal		<b>EL2902</b>  TwinSAFE, 2 safe outputs			<b>AX81xx-0200, AX82xx-0200</b> feedback: OCT, TwinSAFE: Safe Motion, TwinSAFE Logic integrated
<b>Bus Terminal</b>	<b>KL6904</b> TwinSAFE Logic Bus Terminal, 4 safe outputs	<b>EtherCAT Box</b>	<b>EP1908-0002</b> TwinSAFE, 8 safe inputs	<b>Servo-motor terminals</b>	<b>EL7201-9014</b> $I_{ms} = 2.8 \text{ A}$ , 50 V DC, OCT, STO	
		<b>EtherCAT Plug-in Modules</b>	<b>EJ1914</b> TwinSAFE, 4 safe inputs		<b>EL7211-9014</b> $I_{ms} = 4.5 \text{ A}$ , 50 V DC, OCT, STO	
			<b>EJ1918</b> TwinSAFE, 8 safe inputs		<b>EL7221-9014</b> $I_{ms} = 7 \dots 8 \text{ A}$ with ZB8610, 50 V DC, OCT, STO	
			<b>EJ1957</b> TwinSAFE, 8 safe inputs, 4 safe outputs		<b>Servo-motor modules</b>	<b>EP7211-9034</b> $I_{ms} = 4.5 \text{ A}$ , 50 V DC, OCT, STO
			<b>EJ2914</b> TwinSAFE, 4 safe outputs			
			<b>EJ2918</b> TwinSAFE, 8 safe outputs			
			<b>EJ6910</b> TwinSAFE Logic			
		<b>Bus Terminal</b>	<b>KL1904</b> TwinSAFE, 4 safe inputs			
			<b>KL2904</b> TwinSAFE, 4 safe outputs			

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